

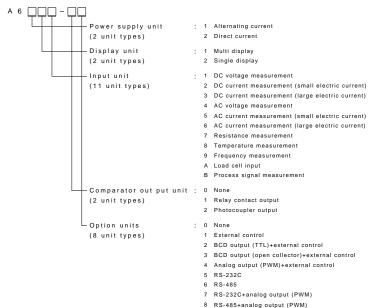
- without prior notice. Information contained herein is considered accurate to the best of our knowledge. If you have (4) any question or comment on the information, please contact us or our distributo
- Read this manual carefully and thoroughly before starting to operate the unit, and keep the manual available for future reference. (5)

1 Before Using the Unit

Thank you for purchasing our quality designed and manufactured A6000 Series. Before unpacking the unit, check for damages during transportation. If you have noticed any damage, directly contact us or our distributor.

1.1 Type Identification

Each model number of the A6000 series has its general specifications, and the following describes each note and the meaning. Before using the unit, check that the model number and specifications of the delivered unit match those of the product you ordered. For optional units, see the separate instruction Manuals.



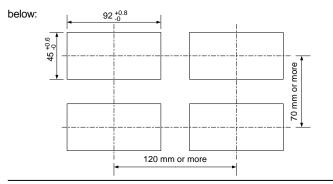
1.2 Accessories

Accessory	Quantity	Remarks
6-p terminal cover	2 or 3 each	2 without a comparator output 3 with a comparator output
Mounting band	2 pieces	
Unit indication label	1 each	

Mounting Method 2

Panel Cut Size 2.1

Cut the panel to mount the A6000 series in accordance with the illustration



2.2 How to Mount the Unit on the Panel

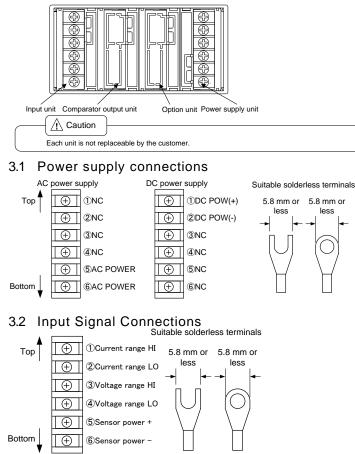
Mount the A6000 series to the panel in accordance with the illustration

below: (1) Remove the mounting band and insert the case (2) Fix the case using the mounting band from the from the front of the panel rear of the panel



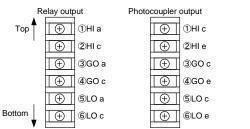
- (1) The recommended panel thickness is 0.8 to 5mm
- (i) The recommended parter thickness is 0.5 to 5000 minit.
 (2) Do not install the unit in locations where it is exposed to direct sunlight; where ambient emperature or humidity doesn't meet the requirements below; or where a drastic change in temperature may ause condensation. Ambient temperature: 0 to 50°C Ambient temperature: 0 to 50°C
 (3) Do not install the unit where it is exposed to dust, particles, chemicals harmful to electric components, corrosive gases, etc.
- (4) When this unit is installed inside other equipment, pay attention to the heat radiation and keep the heat inside the equipment 50°C or below.
- (5) Do not install the unit where it is exposed to excessive vibration or shock. (6) Install the unit horizontally; otherwise, ventilation will be adversely affected and may result in deterioration.

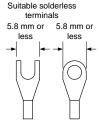
3 Terminals and Connections Illustration of the rear of the A6000



*(2), (4) and (6) watch terminal are these potential.

3.3 Comparator Output Connections





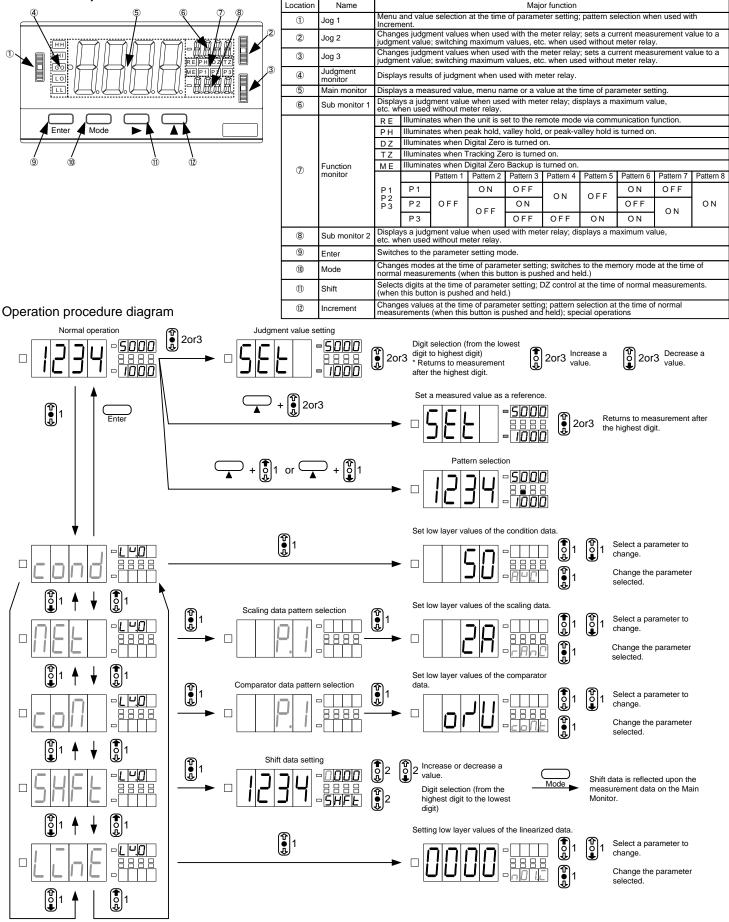
3.4 Option connections

For connections of the options, see separate optional function instruction Manuals.

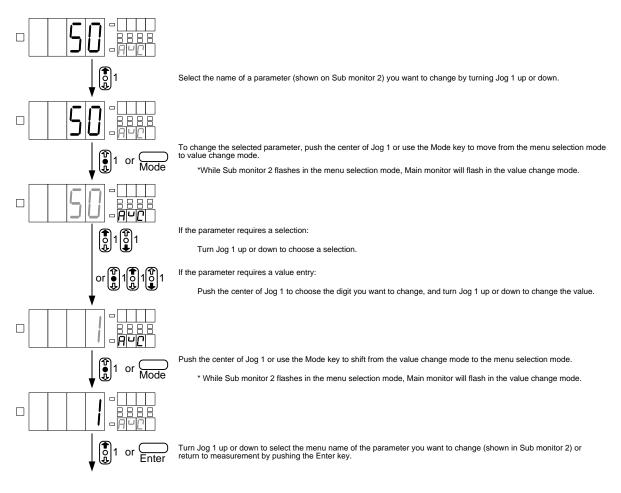
4 Parameter Settings

4.1 Multi Display Unit

Names and major functions



How to set a low layer value (Condition data/scaling data/comparator data)

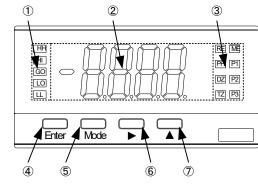


Remarks:

The multi display unit can also follow the operation procedure of the single display unit operation system.
Comparator judgment values can be set not only from Jog 2 and Jog 3 but also from the low layers of the comparator data.
For operation procedures in the memory mode (maximum value/minimum value/(maximum value-minimum value)), see the operation procedure diagram of the single display unit.

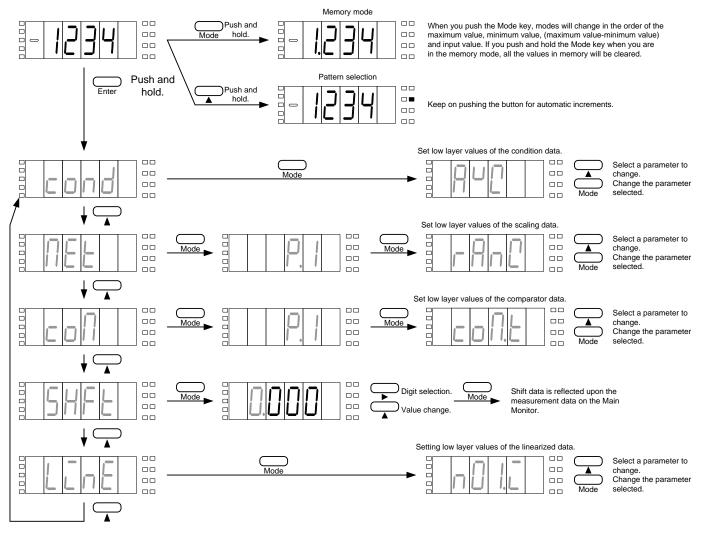
4.2 Single Display Unit

Names and major functions

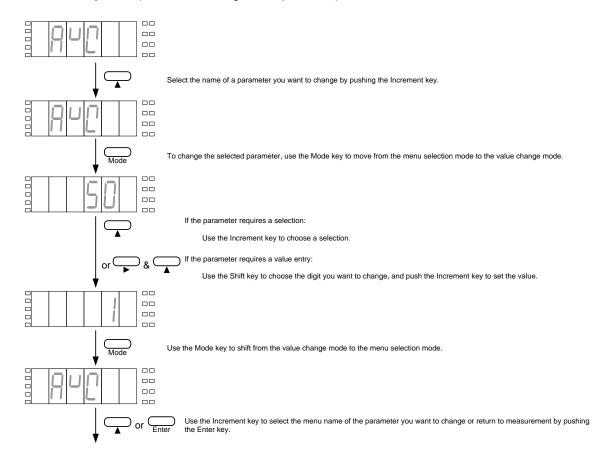


Location	Name	Major function									
1	Judgment monitor	Displa	Displays judgment results when used with meter relay.								
2	Main monitor	Displa	Displays a measured value as well as menu names and values at the time of parameter setting.								
		RE Illuminates when the unit is set to the remote mode via communication fu								ion functior	۱.
		ΡH	Illun	ninates wh	en peak ho	old, valley h	old, or pea	ak-valley ho	old is turne	d on.	
		DZ	Illun	ninates wh	en Digital Z	Zero is turn	ed on.				
		ΤZ	Z Illuminates when Tracking Zero is turned on.								
3	Function monitor	ME	Illuminates when Digital Zero Backup is turned on.								
		P1 P2		Pattern 1	Pattern 2	Pattern 3	Pattern 4	Pattern 5	Pattern 6	Pattern 7	Pattern 8
			P1		F OFF	OFF	ON	OFF	ON	OFF	ON
		P3		OFF		ON	ON		OFF	ON	
			Ρ3			OFF	OFF	ON	ON		
4	Enter	Switch	nes to	the param	neter setting	g mode.					
5	Mode	Chang norma	Changes modes at the time of parameter setting; switches to the memory mode at the time of normal measurements (when this button is pushed and held.)								
6	Shift	Select (when	Selects digits at the time of parameter setting; DZ control at the time of normal measurements. (when this button is pushed and held.)								
Ø	Increment	Chang (when	es valı this bu	ues at the ti utton is push	me of param ned and held	neter setting l) ; special o	; pattern sel perations	ection at the	time of nor	mal measur	ements

Operation procedure diagram



How to set a low layer value (Condition data/scaling data/comparator data)



4.3 Numeric and Character Indications

4.4 Protection Levels

Each parameter of the A6000 has an individual protection level, and by setting the protection level of the condition data, you can set an access level. (For the protect level of each parameter, see the P.L. column of the tables in Section 4.5.)

The higher the protection level is, the less the number of settable parameters will be. If you set the protection level to the strictest LV3, you can change the protection level only, and all the other parameters may not be changed. (No comparator judgment value can be changed using the jog switches in this case.) *The protection level set at the time of shipment is LV1. (Settings of display colors, scaling and judgment-related values only are available.)

4.5 List of the Parameters

The parameters for the process signal measurement unit can be roughly divided into three types: condition data which deal with basic functions including sampling time; scaling data which control measurement including input range; and comparator data (for meter relay only) which deal with comparator output.

4.5.1 Condition Data

Menu indication	Parameter name	Initial value	P.L.	Setting range or alternatives	Major setting purpose and remarks
AVG	Average times	50	0	1/2/4/8/10/20/50/100/200/ 400/800/1000/2000/5000	Selects Conversion rate (average times of internal sampling; sampling time: approx. 1 millisecond)
MAV	Average times of movements	1	0	1/2/4/8/16/32	Selects the average times of movements.Filtering effects: Small<1(OFF)-2-4-8-16-32>Big
S.WD	Step wide	1	0	1/2/5/10	Selects the range of display changes to maintain image display consistency. (If this parameter is set to 5, the lowest digit will display either 0 or 5 only).
CLR	Display color	RED	1	RED/GREEN	Selects display colors.*Only when without meter relay.
CLR.T	Display color type	Αυτο	1	AUTO/MANU	Selects automatic (red in the HI or LO mode or green in the GO mode) or manual setting for display color type. *Only when with meter relay.
HI.CL	HI display color	RED	1	RED/GREEN	Selects red or green as display color at the time of HI judgment.*Only when CLR.T is MANU.
GO.CL	GO display color	GREN	1	RED/GREEN	Selects red or green as display color at the time of GO judgment.*Only when CLR.T is MANU.
LO.CL	LO display color	RED	1	RED/GREEN	Selects red or green as display color at the time of LO judgment.*Only when CLR.T is MANU.
BLNK	Display blank level	OFF	0	OFF/LV1/LV2/LV3/ON	Selects the display brightness. <bright off-lv1-lv2-lv3-on="">turned off</bright>
J.SW	Jog SW	ON	0	ON/OFF	Selects whether the jog SW is used or not.*With the multi display unit only.
PVH	PH Selection	PH	0	PH/VH/PVH	Selects a type that operates when the PH function is turned on (peak hold/valley hold/peak-valley hold).
DZ.BU	DZ backup	OFF	0	OFF/ON	Selects whether the digital zero value is backed up or not at the time when the unit is turned off.
ΡS	P.SEL	1	0	1/2/4/8	Selects the number of patterns available for the pattern selection function.
LINE	Linearize	OFF	0	OFF/2/4/8/16	Selects whether the linearize function is enabled/disabled and sets the number of correction points.
TR.T	TZ time	000	0	000 to 999	Selects whether the tracking zero function is enabled/disabled and sets the correction time (setup value/conversion rate).
TR.W	TZ correction range	01	0	01 to 99	Sets the correction range of the tracking zero function.*Only when TR.T is set to a value other than 000.
P.ON	Power on delay time	0	0	0 to 9	Sets the time between the startup and actual start of measurements (setup value x 1 second).
PRO	Protection level	LV.1	3	Lv.0/LV.1/LV.2/LV.3	Selects the protection level to prevent operation mistakes.High< LV3-LV2-LV1-LV0 >Low
U-NO.	Unit number indication	OFF	0	OFF/ON	Selects whether the code of a unit mounted at the time of startup is displayed or not.
S/H.T	Start/hold type	А	0	A/B	Selects an operation type of start/hold (A: free run; B: one shot).*Only with the external control.
S/H.D	S/H delay time	0	0	0 to 9999	Sets the delay time at the time of startup (setup value x 1 ms).*Only with the external control.
PVH.T	PH type	Α	0	A/B	Selects an operation type of peak hold (A: real-time display; B: results display).*Only with the external control.
DZ.C	DZ control	SW	0	SW/TERM	Selects a control method of Digital Zero (SW: front key; TERM: external control terminal).* Only with the external control.
PS.C	P.SEL control	SW	0	SW/TERM	Selects a control method of Pattern Selection (SW: front key; TERM: external control terminal).*Only with the external control.
BCD.L	BCD logic	N.LOG	0	N.LOG/P.LOG	Selects the BCD output logic (N: negative logic; P: positive logic).*Only when the BCD output is available.
BAUD	Baud rate	9600	1	2400/4800/9600/19200/38400	Sets a baud rate for communication.*Only when the communication function is available.
DATA	Data length	7	1	7/8	Selects the data length for communication.*Only when the communication function is available.
P.BIT	Parity bit	E	1	E/O/N	Selects the parity bit for communication.*Only when the communication function is available.
STP.B	Stop bit	2	1	1/2	Selects the stop bit for communication.*Only when the communication function is available.
T-	Delimiter	CR.LF	1	CR.LF/CR	Selects a delimiter for communication.*Only when the communication function is available.
ADR	Equipment ID	01	1	01 to 99	Selects the equipment ID for the RS-485 function.*Only when the RS-485 function is available.

4.5.2 Scaling Data

Menu indication	Parameter name	Initial value	P.L.	Setting range or alternatives	tives Major setting purpose and remarks	
RANG	Input range	2A	1	1V/2V/2A/3A	Selects an input range.*Note that input terminals vary depending on the actual input range.	
FSC	Full scale indication	9999	2	-9999 to +9999		
FIN	Full scale input	9999	2	-9999 to +9999	Cata dha salationakin katuraa dha inaut simal an Jita indiantian	
OFS	Offset indication	0	2	-9999 to +9999	Sets the relationship between the input signal and its indication.	
OIN	Offset input	0	2	-9999 to +9999		
DLHI	Digital limiter HI	9999	0	-9999 to +9999	Sets the upper limit of the displayable range. (Any value equal to or exceeding the digital limiter HI setting will not be updated and kept at the setup value.	
DLLO	Digital limiter LO	-9999	0	-9999 to +9999	Sets the lower limit of the displayable range. (Any value equal to or below the digital limiter LO setting will not be updated and kept at the setup value.	
A.OUT	Analog output type	0-1	1	0-1/0-10/1-5/4-20	Selects an analog output range.*Only when the analog output is available.	
AOHI	Analog output HI	9999	1	-9999 to +9999	Cate the relationship between indications and enclose outputs ≯Osh when the analog output is surilable.	
AOLO	Analog output LO	0	1	-9999 to +9999	Sets the relationship between indications and analog outputs.*Only when the analog output is available.	
D P Decimal point None 2 Each digit can be set independently. Sets the position of the decimal point.			Sets the position of the decimal point.			

4.5.3 Comparator Data (for meter relay only)

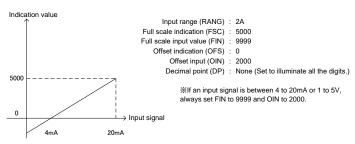
Menu indication	Parameter name	Initial value	P.L.	Setting range or alternatives	Major setting purpose and remarks		
COM.T	Comparator output type	O/U	1	O/U/ERR	Select either [above or below] or error comparator types.		
HI-S	Hl judgment value	1000	2	-9999 to +9999	Sets a HI judgment value.*Only when COM.T is O/U.		
LO-S	LO judgment value	500	2	-9999 to +9999	Sets a LO judgment value.*Only when COM.T is O/U.		
N.VAL	Nominal value	5000	2	-9999 to +9999	Sets a nominal value.*Only when COM.T is ERR.		
ERR1	Error 1	5.00	2	0.00 to 99.99	Sets an error.*Only when COM T is ERR.		
HI-H	HI hysteresis	0	1	0 to +999	Sets a HI hysteresis value *Only when COM.T is O/U.		
LO-H	LO hysteresis	0	1	0 to +999	Sets a LO hysteresis value *Only when COM.T is O/U.		
ER1.H	Error 1 hysteresis	1	1	0 to +999	Sets an error hysteresis *Only when COM.T is ERR.		
HI-L	HI logic	N.O	0	N.O/N.C	Sets a HI output logic (N.O.=normally open or N.C.=normally closed)*Output when the power is OFF is always open (OFF).		
GO-L	GO logic	N.O	0	N.O/N.C	Sets a GO output logic (N.O.=normally open or N.C.=normally closed)*Output when the power is OFF is always open (OFF).		
LOL	LO logic	N.O	0	N.O/N.C	Sets a LO output logic (N.O.=normally open or N.C.=normally dosed)*Output when the power is OFF is always open (OFF).		

5 Setting Examples

5.1 Calibration Data Setting Examples

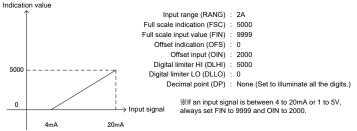
Example 1

When the input signal varies between 4 to 20mA, corresponding indication values should be 0 to 5000.



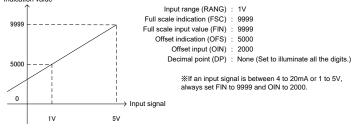
Example 2

When the input signal varies between 4 to 20mA, corresponding indication are changed from 0 to 5000 thereby limiting the indication range to between 0 and 5000.

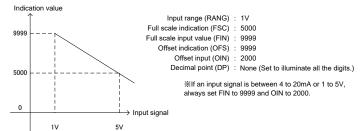


Example 3

When the input signal varies between 1 to 5V, corresponding indication values should be 5000 to 9999. Indication value

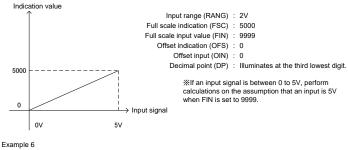


Example 4 When the input signal varies between 1 to 5V, corresponding indication values should be 9999 to 5000.

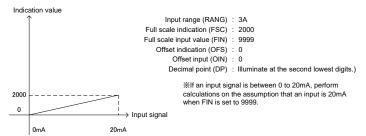




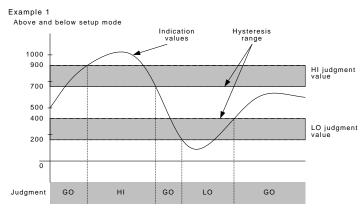
. When the input signal varies between 0 to 5V, corresponding indication values should be 0.000 to 5.000.



When the input signal varies between 0 to 20mA, corresponding indication values should be 0.00 to 20.00.

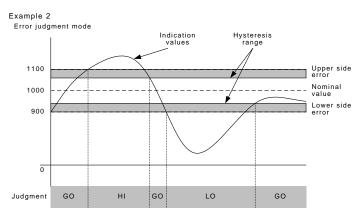


5.2 Comparator Data Setting Examples (for meter relay only)



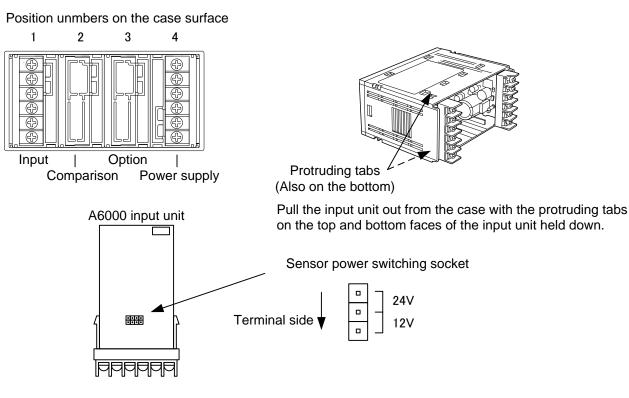
%The hysteresis is effective either in the range lower than the HI judgment value or that higher than the LO judgment value.

5.3 How to Switch the Measuring Method



 $\ensuremath{\mathbbmath{\mathbb{K}}}\xspace$ for the nominal value.

%The hysteresis is to be set as xx digits of the indication value.
%The hysteresis is effective either in the range lower than the upper side error or that higher than the lower side error.



*Upon shipment from the factory, the sensor power switching socket is set 24V side.

When installing the input unit, slide it along the guides inside the main-unit case.

*Push the input unit into the case so that the input unit's connector (female) is securely fit into the display unit's connector (male).

6 Specifications and External Dimensions

6.1 Input Specifications

Range	Measurement range	Indication	Error (23°C ±5°C; 35 to 85%)	Input impedance	Maximum permissible input				
1V	1 to 5V		±(0.03% of rdg + 2digit)	Approx. 1MΩ	±100V				
2V	±5V	Offset: ±9999	±(0.03% of rug + 20igit)	Approx. Twisz	±100V				
2A	4 to 20mA	Full scale: ±9999	±(0.1% of rdg + 3digit)	Approx. 10Ω	+50mA				
ЗA	±20mA		±(0.1 % 01 lug + 3ulgit)	Approx. 10 se	ESOINA				
Sampling rate : Maximum approx. 1,000 times/second Sensor power : 12V DC ±10% 50mA or 24V DC ±10% 25mA %The error is applied when the sampling rate is 20 times/second or less.									
x the entrin is applied when the sampling rate is 20 times/second on less.									

(1) The sensor power supply is set at 24V upon shipment from the factory.(internal socket
swiching)
(2) If a load exceeding the rated level is connected to the sensor power supply, the sensor
power supply will be turned off (protection mode). To recover from the protection mode,
ture the power on again.

6.2 General Specifications

Display	: Multi display Main display: Red/green 7-segment display (character height: approx. 20 mm) Sub display: Red 7-segment display (character height: approx. 6 mm) Single display Red/green 7-segment display (character height: approx. 20 mm)
Display range	: -9999 to 9999
Operational temperature	: 0 to 50°C 35 to 85%RH
	: -10 to 70 ℃; 60%RH or less
	: AC PS
Power supply	
	AC 100 to 240V±10%
	DC PS
	DC 12 to 48V±10%
Power consumption	: AC PS
	Maximum load: Approx. 8 VA at 100 VAC
	DC PS
	Maximum load: Approx. 7 W at 24 VDC
External dimension	: 48 mm (H) x 96 mm (W) x 97.5 mm (with no DX option unit mounted)
Weight	: Approx. 450g
Withstand voltage	AC PS
	PS-input, output: 1,500 VAC, 1 minute (AC PS)
	Input-output: 500 VDC. 1 minute
	Output-output: 500 VDC, 1 minute
	Case-PS, input, output: 1,500 VAC, 1 minute
	DC PS
	PS-input, output: 500 VDC, 1 minute (DC PS)
	Input-output: 500 VDC, 1 minute
	Output-output: 500 VDC, 1 minute
	Case-PS, input, output: 1,500 VAC, 1 minute
Insulation	AC PS
resistance	Among the above terminals: 500 VDC 100 M Ω or more
	DC PS
	Among the above terminals: 500 VDC 100 M Ω or more

Caution
The PS voltage must be applied or shut down at once (not gradually).

Take at least a 10-second interval between a shutdown and startup.

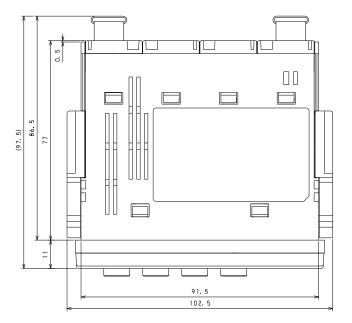
6.3 Output Comparison Specifications

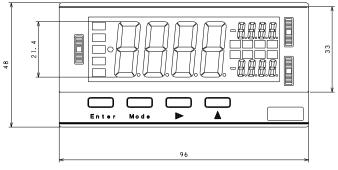
(for meter relay only)

Common	specifications

	Judgment result							
In	Indicated value Upper limit judgment value							
Lower limit judg	Lower limit judgment value Indicated value Upper limit judgment value							
Le	Lower limit judgment value Indicated value							
Judgment value s Hysteresis Operating speed	etup	: Can	99 to +9999 be set in the rang ends on the same	ge of 1 to 999 digits fo bling rate	r each	judgment value		
 Relay contact outp Contact quantity Contact rating 		Relay contact 250V AC 2A,	×3	 Photo coupler o Output quantity Output rating 		Photo coupler 30V DC 20mA		

6.4 External Dimensions





7 Warranty and Service

7.1 Warranty

× 3

The manufacturer warrants to the original retail customer its A6000 series universal digital panel meter to be free of defects in material and workmanship for use under normal care and will repair or replace any meter at no charge to the customer during the one (1) year warranty period of the meter.

7.2 After Sales Service

Under strict quality control measures, this product was manufactured,

tested, inspected and shipped. Should a defect in manufacture or

workmanship be identified, please return the product to our distributor or

directly to us. It would be highly appreciated if you could give a detailed

account of the fault and enclose it with the product.



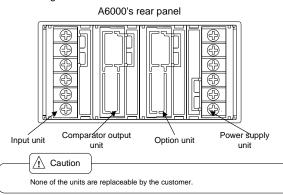
Homepage http://www.watanabe-electric.co.jp/en/

Instruction Manual for A6000 Series Universal Digital Panel Meters

External Control Unit

1 Before Using the Unit

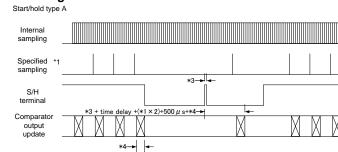
This instruction manual is for the external control unit of the A6000 series. Read this manual along with the main unit's instruction manual before using the unit.



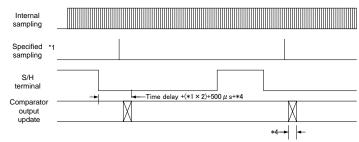
2 Terminals and Connections

	Top ① ① ① ② ② PH ③ ③ DZ ③ DZ ④ ④ ③ DZ ④ ④ RESET ⑤ ⑤ ⑤ P.SEL1 ⑦ P.SEL2 ⑤ ⑥ ⑧ NC ⑨ ⑨ ⑨ ⑧ NC ⑨ ⑨ NC ⑨ ℕ Bottom ∅ ℕ □ ℕ □ ∅ ℕ □ ∅ ℕ □ ∅ ℕ □ ∅ ℕ □ ∅ ℕ □ ∅ ℕ □ ∅ ℕ □ ∅ ℕ □ ∅ ℕ □ ∅ ℕ □ ∅ ℕ □ ∅ ℕ □ ∅ ℕ □ ∅ ℕ □ ∅ ℕ □ ∅ ℕ □ ∅ ℕ □ ∅ ∅ ∅ □ ∅ ∅ ∅ ∅ ∅ <td< th=""></td<>						
Terminal	Function						
S/H	"Start/hold" control terminal. The "hold" state is turned on when this terminal is at the same potential as the COM terminal or short-circuited.						
PH	"Peak hold" control terminal. The peak hold function is turned on when this terminal is at the same potential as the COM terminal or short-circuited.						
DZ	*Digital zero* control terminal. The digital zero function is turned on when this terminal is at the same potential as the COM terminal or short-circuited. This setting is valid only when the external control terminal is selected as the control method for digital zero using condition data.						
R.RESET	"Relay reset control terminal. The relay reset function is turned on (only for the meter relay) when this terminal is at the same potential as the COM terminal or short-circuited.						
P.SEL0 P.SEL1 P.SEL2	*Pattern selection* control terminals. Patterns can be selected by setting these terminals at the same potential as the COM terminal or short-circuiting them as shown in the table below. These settings are valid only when the external control terminal is selected as the control method for pattern selection using condition data.						
COM	External control's common terminals, which are at the same potential as the LO or AG terminal for the input circuit.						

3 Timing Charts



Start/hold type B



*1 Specified sampling

The sampling speed is determined by the AVG parameter setting of condition data as shown in the table below

AVG setting	Sampling speed	Sampling cycle	AVG setting	Sampling speed	Sampling cycle
1	1041.65 times/sec	Approx. 960 µs	100	10.4165 times/sec	Approx. 96 ms
2	520.825 times/sec	Approx. 1.92 ms	200	5.20825 times/sec	Approx. 192 ms
4	260.4125 times/sec	Approx. 3.84 ms	400	2.604125 times/sec	Approx. 384 ms
8	130.20625 times/sec	Approx. 7.68 ms	800	1.3020625 times/sec	Approx. 768 ms
10	104.165 times/sec	Approx. 9.6 ms	1000	1.04165 times/sec	Approx. 960 ms
20	52.0825 times/sec	Approx. 19.2 ms	2000	0.520825 times/sec	Approx. 1.92 sec
50	20.833 times/sec	Approx. 48 ms	5000	0.20833 times/sec	Approx. 4.8 sec
XI laing a to			a appendie he	olf of the velue in the t	

XUsing a temperature measuring unit, the sampling speed is half of the value in the table above when the RTD is selected and quarter of it when the TC is selected.

%It is different, and a frequency measurement unit is indication update time with a range. Please refer to input specifications (Clause 6.1) of an instruction manual for frequency measurement.

- Please refer to input specifications (Clause 6.1) of an instruction manual for frequency measurement. *3 External start signal The width of the external start signal must be from between 500 µs to a specified sampling cycle. A time
- delay can be set for the external start signal must be from between 500 µs to a specified sampling cycle. A tir delay can be set for the external start using the S/H delay time parameter of the condition data.
- *4 Time delay for comparator output

Relay output: 10 ms max., photocoupler output: 200 μs max.

4 Specifications and External Dimensions

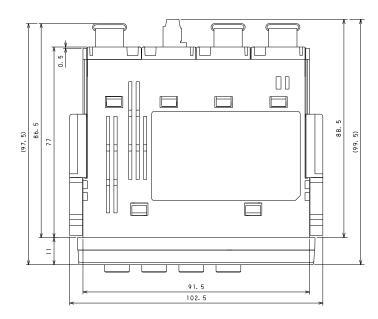
External control terminal

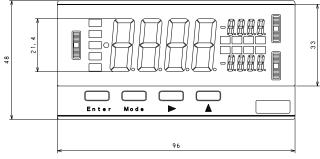
Internal circuit: Pulled up to approximately +5 V (through a 10 $k\Omega$ resistor).

Control signal's HI level: 4.2 to 5 V relative to the COM terminal

Control signal's LO level: 0 to 0.4 V relative to the COM terminal







5 Warranty and Service

5.1 Warranty

The manufacturer grants a warranty to the original retail customer stating that its A6000 series universal digital panel meter is free of defects in material and workmanship for use under normal care, and will repair or replace the meter at no charge to the customer during the one (1) year warranty period.

5.2 After Sales Service

This product was manufactured, tested, inspected and shipped under strict quality control measures. Should a defect in manufacture or workmanship be identified, please return the product to our distributor or directly to us. It would be highly appreciated if you could give a detailed account of the problem and enclose it with the product.

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WATANABE ELECTRIC INDUSTRY CO., LTD.

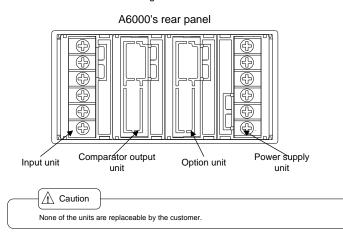
6-16-19, Jingumae, Shibuya-ku, Tokyo 150-0001, Japan Phone: (81)3-3400-6141 Homepage http://www.watanabe-electric.co.jp/en/

Instruction Manual for A6000 Series Universal Digital Panel Meters

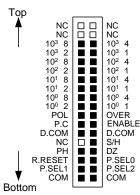
BCD Output and External Control Unit

1 Before Using the Unit

This instruction manual is for the BCD output and external control unit of the A6000 series. Read this manual along with the main unit's instruction manual before using the unit.

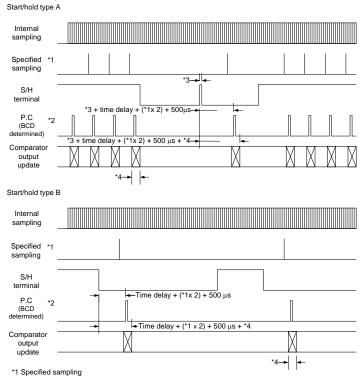


2 Terminals and Connections



Suitable connector (receptacle): KEL Corporation's 8822E-035-171-F

Terminal	Function
10º1	Least significant bit output of least significant BCD digit. The output logic can be switched using condition data.
10º2	Second least significant bit output of least significant BCD digit. The output logic can be switched using condition data.
10º4	Second most significant bit output of least significant BCD digit. The output logic can be switched using condition data.
10º8	Most significant bit output of least significant BCD digit. The output logic can be switched using condition data.
:	
10 ³ 1	Least significant bit output of most significant BCD digit. The output logic can be switched using condition data.
10 ³ 2	Second least significant bit output of most significant BCD digit. The output logic can be switched using condition data.
10 ³ 4	Second most significant bit output of most significant BCD digit. The output logic can be switched using condition data.
10 ³ 8	Most significant bit output of most significant BCD digit. The output logic can be switched using condition data.
POL	BCD polarity output. The output logic can be switched using condition data.
OVER	BCD overflow output. The output logic can be switched using condition data.
P.C	BCD print instruction output.
ENABLE	"Enable BCD' control terminal. The BCD output is set to the high-impedance state or the transistor is turned off when this terminal is short-circuited or at the same potential as the D.COM terminal.
D.COM	BCD output• fs common terminals
S/H	"Start/hold" control terminal. The "hold" state is turned on when this terminal is at the same potential as the COM terminal or short-circuited.
PH	"Peak hold" control terminal. The peak hold function is turned on when this terminal is at the same potential as the COM terminal or short-circuited.
DZ	*Digital zero* control terminal. The digital zero function is turned on when this terminal is at the same potential as the COM terminal or short-circuited. This setting is valid only when the external control terminal is selected as the control method for digital zero using condition data.
R.RESET	*Relay reset control terminal. The relay reset function is turned on (only for the meter relay) when this terminal is at the same potential as the COM terminal or short-circuited.
P.SEL0 P.SEL1 P.SEL2	Pattern selection* control terminals. Patterns can be selected by setting these terminals at the same potential as the COM terminals of short-circuiting them as shown in the table below. These settings are valid only when the external control terminal is selected as the control method for pattern selection using condition data. Pattern 2 Pattern 3 Pattern 4 Pattern 5 Pattern 7 Pattern 5 Pattern 4 Pattern 5 Pattern 7 Pattern 8 Pattern 5 Pattern 7 Pattern 8 Pattern 4 Pattern 5 Pattern 7 Pattern 5 Pattern
COM	External control's common terminals, which are at the same potential as the LO or AG terminal for the input circuit.



3 Timing Charts

The sampling	speed is determined	by the AVG parameter	eter setting of	condition data as show	n in the table below:
AVG setting	Sampling speed	Sampling cycle	AVG setting	Sampling speed	Sampling cycle
1	1041.65 times/sec	Approx. 960 µs	100	10.4165 times/sec	Approx. 96 ms
2	520.825 times/sec	Approx. 1.92 ms	200	5.20825 times/sec	Approx. 192 ms
4	260.4125 times/sec	Approx. 3.84 ms	400	2.604125 times/sec	Approx. 384 ms
8	130.20625 times/sec	Approx. 7.68 ms	800	1.3020625 times/sec	Approx. 768 ms
10	104.165 times/sec	Approx. 9.6 ms	1000	1.04165 times/sec	Approx. 960 ms
20	52.0825 times/sec	Approx. 19.2 ms	2000	0.520825 times/sec	Approx. 1.92 sec
50	20.833 times/sec	Approx. 48 ms	5000	0.20833 times/sec	Approx. 4.8 sec

*Using a temperature measuring unit, the sampling speed is half of the value in the table above when the RTD is selected and quarter of it when the TC is selected. %It is different, and a frequency measurement unit is indication update time with a range.

Please refer to input specifications (Clause 6.1) of an instruction manual for frequency measurement

*2 P.C output signal width

The output signal width is determined by the specified sampling setting as shown in the table below:

AVG	P.C	AVG	P.C
setting	output width	setting	output width
1	Approx. 220 µs	100	
2	Approx. 0.25 ms	200	
4	Approx. 1.15 ms	400	
8	Approx. 2.3 ms	800	Approx. 30 ms
10	Approx. 2.9 ms	1000	
20	Approx. 5.8 ms	2000	
50	Approx. 14.4 ms	5000	
The output	width is always 30 m	ns for the frequ	Jency measureme

*3 External start signal

The width of the external start signal must be from between 500 µs to a specified sampling cycle. A time delay can be set for the external start using the S/H delay time parameter of the condition data *4 Time delay for comparator output

Relay output: 10 ms max., photocoupler output: 200 µs max.

4 Specifications and External Dimensions

BCD output

Output type	:	open collector or TTL-compatible
Polarity	:	The applicable transistor (open collector) or polarity bit (TTL) turns on when
		negative values are indicated.
Overflow	:	The applicable transistor (open collector) or bit (TTL) turns on when the overflow
		state is indicated.
Output logic	:	Can be switched alternatively (the logic for the P.C bit cannot be changed).
Output rating	:	30 V DC and 10 mA (open collector), or fan-out 2 (TTL)
Cau		
data, whic	ch i	tput logic can be switched using the BCD logic parameter (BCD.L) of the condition s positive when BCD.L is set to P.LOG and negative when BCD.L is set to N.LOG type of Open collector. This logic is reversed if the output type is "TTL."
●External cor	ntro	ol terminal

Internal circuit: Pulled up to approximately +5 V (through a 10 kΩ resistor).

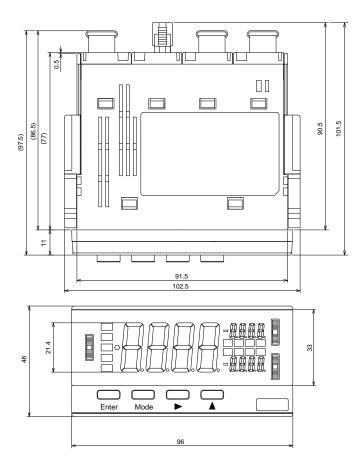
Control signal's HI level: 4.2 to 5 V relative to the COM terminal

Control signal's LO level: 0 to 0.4 V relative to the COM terminal

A Caution

The BCD output circuit and the external control circuit are electrically isolated from each other (withstand voltage: 500 V DC for one minute). The external control circuit's COM terminals and the input circuit's LO or AG terminal are

- set at the same DC potential.



5 Warranty and Service

5.1 Warranty

The manufacturer grants a warranty to the original retail customer stating that its A6000 series universal digital panel meter is free of defects in material and workmanship for use under normal care, and will repair or replace the meter at no charge to the customer during the one (1) year warranty period.

5.2 After Sales Service

This product was manufactured, tested, inspected and shipped under strict quality control measures. Should a defect in manufacture or workmanship be identified, please return the product to our distributor or directly to us. It would be highly appreciated if you could give a detailed account of the problem and enclose it with the product.



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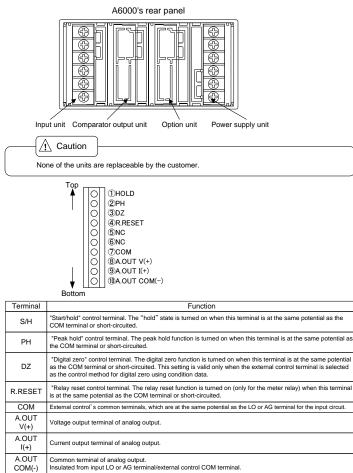
Instruction Manual for A6000 Series Universal Digital Panel Meters

Analog Output and External Control Unit

1 Before Using the Unit

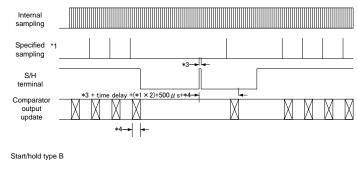
This instruction manual is for the analog output and external control unit of the A6000 series. Read this manual along with the main unit's instruction manual before using the unit.

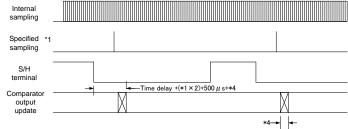
2 **Terminals and Connections**



3 Timing Charts

Start/hold type A





*1 Specified sampling

The sampling speed is determined by the AVG parameter setting of condition data as shown in the table below

AVG setting	Sampling speed	Sampling cycle	AVG setting	Sampling speed	Sampling cycle
1	1041.65 times/sec	Approx. 960 µs	100	10.4165 times/sec	Approx. 96 ms
2	520.825 times/sec	Approx. 1.92 ms	200	5.20825 times/sec	Approx. 192 ms
4	260.4125 times/sec	Approx. 3.84 ms	400	2.604125 times/sec	Approx. 384 ms
8	130.20625 times/sec	Approx. 7.68 ms	800	1.3020625 times/sec	Approx. 768 ms
10	104.165 times/sec	Approx. 9.6 ms	1000	1.04165 times/sec	Approx. 960 ms
20	52.0825 times/sec	Approx. 19.2 ms	2000	0.520825 times/sec	Approx. 1.92 sec
50	20.833 times/sec	Approx. 48 ms	5000	0.20833 times/sec	Approx. 4.8 sec
VI laina a ta	monoratura magauria	a unit the complin	a anaad ia hu	Slf of the velue in the t	

%Using a temperature measuring unit, the sampling speed is half of the value in the table above when the RTD is selected and quarter of it when the TC is selected.

%It is different, and a frequency measurement unit is indication update time with a range. Please refer to input specifications (Clause 6.1) of an instruction manual for frequency measurement. *3 External start signal

The width of the external start signal must be from between 500 µs to a specified sampling cycle. A time delay can be set for the external start using the S/H delay time parameter of the condition data

*4 Time delay for alarm output

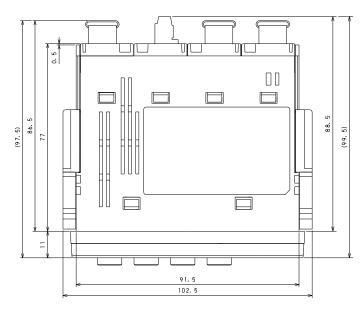
Relay output: 10 ms max., photocoupler output: 200 µs max.

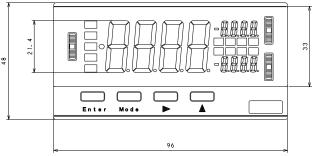
4 Specifications and External Dimensions

Analog output (PWM)

Output type	Load resistance	Accuracy	Response speed	Ripple
0 to 1V				
0 to 10V	10kΩ or more	1 (0 50(-4 50)	A	50mVp-p
1 to 5V		±(0.5% of FS)	Approx. 0.5 second	
4 to 20mA	550Ω or less			25mVp-p
Conversion system	n : PWM conve	sion		
Resolution	: Equivalent to	14 bits		
Scaling	: Digital scalin	g		
External control te Internal circuit Control signal's H level	: Pulled up 1	o approximately +5V (elative to the COM ter	through a 10kΩ resistor). minal	

(1) Ana one minute) (2) COM terminals of external control circuits and LO terminals of input circuits have the same electric potential at direct current.





5 Warranty and Service

5.1 Warranty

The manufacturer grants a warranty to the original retail customer stating that its A6000 series universal digital panel meter is free of defects in material and workmanship for use under normal care, and will repair or replace the meter at no charge to the customer during the one (1) year warranty period.

5.2 After Sales Service

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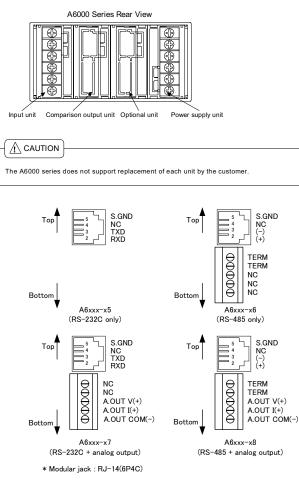
Instruction Manual for A6000 Series Universal Digital Panel Meter

~RS-232C/RS-485 and Analog Output Units~

1 Before Using the Unit

This Operation Manual corresponds to the communication function + analog output optional units of the A6000 Series Universal Digital Panel Meters. When using the instrument, please read through this manual in combination with the Operation Manual of the main unit.

2 Terminals and Connections

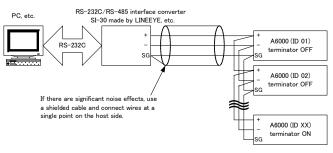


3 Examples of Connections and Use

3.1 Connecting the RS-232C Interface

A6000 series modular jack	D-sub 25-pin connector of PC, etc.	A6000 series modular jack	D-sub 9-pin connector of PC, etc.
RXD 🔫	► RXD (2)	RXD 🚽	► RXD (2)
TXD 🚽	► TXD (3)	TXD 🚽	► TXD (3)
SG 👞	► RTS (4)	SG 👞	► RTS (7)
	CTS (5)		CTS (8)
	SG (7)		SG (5)

3.2 Connecting the RS-485 Interface



*If cascade wiring is carried out with a RS-485 connection, use a commercially available Y-type split connector or the like. *To turn ON an RS-485 I/O unit's terminator (200 Q), short-circuit the two TERM terminals.

3.3 Control Codes Used in RS-485 Interface

		-
Code	Hexadecimal	Name
STX	02H	Start of Text
ETX	03H	End of Text
EOT	04H	End of Transmission
ENQ	05H	Enquiry
ACK	06H	Acknowledge

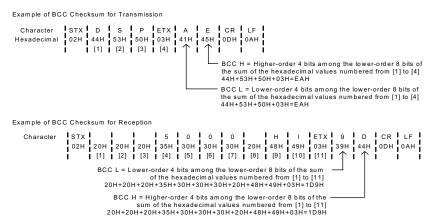
3.4 Establishing RS-485 Communication

Function	1 2	3	4	5	6	7	Char. Length	1	2	3	4	5	6	7	8	9	10	Char. Length
Establishing	ENQ 0		CR				3	ACK	0	1	Q	R LF						3
communication	*Device	D	is s	pecif	fied	l in		•				onse	<i>'</i>				}	
	2 digits	(00) is i	nvali	d).				re	 spo		me: is n						is
Canceling communication	EOT CR *If anot specific canceli commu commu possibl	her ed w ng inic	devi vitho atior	ut n,			1	, con	nm	unic	atio	e is n on.) me:						of

3.5 RS-485 Communication formats

As a means of error detection, a block check character (BCC) checksum is added to the RS-485 communication function of the A6000. See the following illustrations for details on the transmission and reception formats.

(RS-232C communication format is same as the command table which is mentioned in the next section.)



4 Communication Commands

Function	1 1	2	{ 3	} 4	5	6	7 8	3 9	10 11	12	13 14	15	Char. Le	Length 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 Char. Ler
Measured value and comparison result responses				CR									3	3 5 0 0 0 H I CR LF 10 ("+" indication without decimal point)
lesponses														- 5 0 0 0 H I CR LF 10
														("+" indication without decimal point) 5 0 0 . 0 H I CR LF 11
														("+" indication with a decimal point)
														< = 9 8 0 0 0 H I CR LF 10 ("+" side excess indication without decimal point)
														< =] - { 9 8 0 . 0 H I CR LF 11 ("-" side excess indication with a decimal point)
														P H 5 0 0 0 H I CR LF 10
														(Peak hold indication without decimal point) 5 0 0 0 A L 1 CR LF 11
														("+" indication without decim al point)
			1											("-" indication without decimal point)
														("+" indication with a decimal point)
		Ļ		1				1						
Measured value response A measurement condition such as peak	M	E	S	CR	LF								3	3 0 CR LF 12 ("0" indication without decimal point)
hold, etc. or compression decision is not responded.														("0.01" indication with a decimal point) CR LF 12
is notresponded.														- 1 CR LF 12
														("-1" indication without decimal point)
								1						("-0.005" indication with a decimal point)
			1					1						(Excess indication with a decimal point)
														<pre>< = - 9 8 0 . 5 CR LF 12 ("-" side excess indication with a decimal point)</pre>
														* All responses have a fixed length of 12 characters.
Judgment result response	J	G	M	CR	LF		+	+	++	+	+	-	3	
* A measurement condition is not responded.														(Response of a state in which the judgment result is HI) G O G O
			1					1						(Response of a state in which the judgment result is GO)
														L O CR LF 15 (Response of a state in which the judgment result is LO) In the state in which the judgment result is LO) In the state in which the judgment result is LO)
														O F F I
														N O ? CR LF 5
														(Response made if the relevant optional unit is not installed) * All responses have a fixed length of 15 characters with the
Unit num ber response	$\frac{1}{10}$	N	}	CR	1.5		_		\square		_	-	3	exception of an error. 4 6 CR LF 11 3 1 1 2 1 N O 4 6 CR LF 11
	ľ		1											(Response is made in the order of the display unit number, input
														unit number, comparison output unit number, and optional unit If the unit concerned is not installed, "NO" is returned.)
Response of the maximum value,	м			CR	1 5		_	<u> </u>			_	Ļ	3	3 M A X 5 0 0 . 0 CR LF 1 1 10
minimum value, or maximum and			Î										Ū	(Response of maximum value)
minimum values														M I N - 1 0 0 . 0 CR LF 10 (Response of minimum value) 0 CR LF 10
				1				1						M - M 6 0 0 1 0 CR LF 10 (Response of maximum and minimum values)
														* These values are simultaneously responded by dividing them with a delimiter.
Clear of the maximum value,						A							6	
minimum value, or maximum and minimum values						ım va I∣C							6	6 Y E S CR LF 5
						m va M∣C							6	6 Y E S CR LF 5
									um valu	ies.)				
Key operation inhibition response	к	E	Y	CR	LF	1		1			+	+	3	
				1										O N CR LF 2
				1										(Response of a state in which the key operation inhibition function is ON)
Key operation inhibition setting		E				F				functio			7	7 Y E S CR LF 5
	ĸ	E	Y	1	0	NC	RLF	1	ibition				6	6 Y E S CR LF 5
	(Ac	tivat	test 	hek }	eyo	perat 	on ir	hibit	ion fun	ction.)				
Response of remote-controlled hold	S	Т	н	CR	LF								3	3 S T A R T CR LF 5 (Response of a state in which hold is deactivated by remote control)
				1										H O L D CR LF 4
				-										(Response of a state in which hold is activated by remote control)
								-						(Response of a state in which hold is not remote controlled)
Hold remote control		T				CR L Id fur							5	5 Y E S CR LF 5
	s	Т	н	1	н	CR	F	1					5	5 Y E S CR LF 5
	Ľ		1	}	old	functi	on.)							
Trigger input	Т	CR	LF										1	1 5 0 0 . 0 H I CR LF 11 ("+" indication with a decimal point)
														* The response format is the same as the DSP command.
Cancellation of hold remote control	E	s	м	CR	LF								3	3 Y E S CR LF 5
		1		}		Ĭ		1			1	1		

Function	1	2	<u> </u>	-		<i>.</i>	7	8	9	10	11	12	13	14	15	Char. Length	1 }	_	<u> </u>	-	_		_	_		_	<u> </u>	1	10	11	12	1	3	14	15	1	6	17	18	Ch	ar. Lengti
Response of remote-controlled peak hold	P	V	Н	CR	LF											3	P (Res												is (102	c tiv	ater	d by	/ ro	mol	te c	oni	rol			6
peak noid							[V																	, 16			1	101)			6
							[(Res P											holo	alis I	dea			ed b	by r	emo	ote	ر نان	ntro	I)		6
			1					{									(Res											 y ho	l i bla	e da	acti	vate	ed b	y re	mot	e co	ontr	ol)			0
																	P (Res	Н	-	0	N	1 0	CR	LF			}									1					5
			1					1									V															1	y I	emo			100	"			5
			1														(Res															ted	by	rem	note	co	ntr	ol)			5
							[P (Res											y ho				ted	by i	rem	ote ({ cont	trol)				5
																	L (Re									o h	1		h 0	d ir				oto				(bo			3
							[spu		101			e II		1	511	fe {					1				{	1	euj			
Peak hold selection setting		V ets u				H	CR	LF								6	Υ	Е	s			0	CR	LF																	5
		V					CR	LF								6	Y	Е	s				CR	LF			}														5
	(Se	nts u	p va	illev	hol	d.)	}	{								6	Y	_					CR																		5
	(Se	V tsu	β Π p p	l eak	and	vall	ey h	old.)								0	'	-	3			ľ	-	LI																	5
Peak hold remote control		v				N										6	Y	-					CR				1														5
reak noid temole control								nctio	n.)							0						ľ	511	-																	5
								CR I fun								7	Υ	Е	s			0	CR	LF																	5
		acu	{	is u	e pe	ar l	}	{		.,																															
Peak-held value response	P	V	D	CR	LF		[3	P (Re						5				{ ·		D	CR	LF										10
							[8							V	н		1		. [1	0	1	0	{.		5	CR	LF										10
																	(Re P				fval									CR											10
																	(Re				[fpe						}. /-h€														10
Clear of peak-held value		с	١.		Þ	н		I.E.								6	Y	F	ç				CR				{														5
	(C)	ears	s'a p	beak	-hel	ld va	lue.	.)								0						ſ	511	-			1														5
		C Cars														6	Y	Е	s			0	CR	LF			1														5
		C														6	Y	Е	s			0	CR	LF			1														5
	(CI	ears	pe	ak-	ind	vall	ey-h	ėld	alu	es.)																	}														
Cancellation of peak hold remote control	E	Р	м	CR	LF		[3	Y	Е	s	1		0	CR	LF			1														5
Response of remote-controlled		Z	R	CR	LE	-	<u> </u>	<u> </u>			_	\rightarrow	_	+	_	3	0	F	F	CE	21	F		_	+		<u>{</u>	+			_	+	+		_	+	+	_		+	3
digital zero		-	[``		-			1								Ŭ	(Res	pon	ise	òf a	sta	te i	n w	hio	h	digi	ital:	zer	o is				edi	by r	em	ote	coi	ntro	I)		
							[1 (Res	0 pons	0 e of	{ 0 a st	C tate	R [I in w	LF hich	dig	iita	ze	{ rois	act	tiv a		at 1	000	by i	rem	ote ((cont	trol)				5
							[- 1	1	0	0	0		CR	LF			1									1					5
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				_}	_ {													averaging is deactivated in mediately aller setting.

INSTRUCTION MANUAL MODEL A6xxx-x5/x6/x7/x8

Function	1 2 3 4 5 6 7 8 9 10 11 1	13 14 15 Char. Length 1 2	3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 cr	har. Length
Step wide response	S W D CR LF	3 1 CR		1
		1 0	CR LF	2
		(Respo	nse of a state in which step wide is "10")	
Step wide setting	S W D 1 CR LF	5 Y E	S CR LF	5
	(Sets step wide to "1.") S W D 1 0 CR LF	6 Y E	S CR LF	5
	(Sets step wide to "10.")		vide is switched immediately after setting.	Ū
Display color response		3 R E	D CR LF	3
		(Respo	nse of a state in which the display color is red)	
			E E N CR LF	5
		N O	? CR LF	5
		(Respo	nse made if the comparison output unit is not installed)	
Display color setting	C L R R CR LF	5 Y E	S CR LF	5
	(Sets display color to red.) C L R G CR LF	5 Y E	S CR LF	5
	(Sets display color to green.)			5
		N O (Respo	? CR LF	5
Dianterration				
Display color type response	C L T CR LF		TO CR LF In the display color type is Auto)	4
			N U A L CR LF A N N N N LF N N LF N N N N LF N N N N N	6
			? CR LF	5
			nse made if the comparison output unit is not installed)	
Display color type setting	C L T A CR LF	5 Y E	S CR LF	5
	(Sets the display color type to Auto.)	5 Y E	S CR LF	5
	C L R M CR LF (Sets the display color type to Manual.)		isplay color type is switched immediately after setting.	5
			? CR LF	5
HI display color response	C H I CR LF		D CR LF	3
		GR	E E N CR LF	5
			nse of a state in which the HI display color is green)	4
		(Respo	nse of a state in which the display color type is Auto)	
		N O	nse made if the comparison output unit is not installed)	5
HI display color setting	C H I R CR LF (Sets HI display color to red.)	5 Y E	S CR LF	5
	C H I G CR LF	5 Y E		5
	(Sets HI display color to green.)	* Hidis	play color is switched im mediately after setting.	4
		(Respo	nse of a state in which the display color type is Auto)	
			? CR LF	5
		(Respo	nse of the state of independent judgment specifications)	
GO display color response		3 R E		3
		(Respo	onse of a state in which the GO display color is red)	5
			E E N CR LF onse of a state in which the GO display color is green)	э
		A U	TOCRLF	4
		N O	onse of a state in which the display color type is Auto) ? CR LF	5
		(Respo	onse made if the comparison output unit is not installed)	
GO display color setting	C G O R CR LF	5 Y E	S CR LF	5
	(Sets GO display color to red.) C G O G CR LF	5 Y E	S CR!LF	5
	(Sets GO display color to green.)	* GO d	isplay color is switched immediately after setting.	
		A U (Respo	T O CR LF onse of a state in which the display color type is Auto)	4
		N O	? CR LF	5
			onse made if the comparison output unit is not installed) onse of the state of independent judgment specifications)	
LO display color response	C L O CR LF		D CR LF onse of a state in which the LO display color is red)	3
		GR	E E N CR LF	5
			onse of a state in which the LO display color is green)	4
		(Respo	onse of a state in which the display color type is Auto)	-
		N O (Respo	? CR LF onse made if the comparison output unit is not installed)	5
				-
LO display color setting	C L O R CR LF (Sets LO display color to red.)	5 Y E	S CRILF	5
	C L O G CR LF	5 Y E		5
	(Sets LO display color to green.)	A U	isplay color is switched immediately after setting. T O CR LF	4
		(Respo	onse of a state in which the display color type is Auto) ? CR LF	
		N O (Respo	? CR LF onse made if the comparison output unit is not installed)	5
			onse of the state of independent judgment specifications)	

Departy have variables 6 K Column 7 Column <th>Function</th> <th>1 2 3 4 5 6 7 8 9 10 11 12 13 14 15</th> <th>Char. Length 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 Char. Length</th>	Function	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	Char. Length 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 Char. Length
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$			
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$			
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$			(Response of a state in which blank setting is at LV1)
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $			
Deploy tonx setting S L K O F C Y X			(Response of a state in which blank setting is at LV2)
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $			(Response of a state in which blank setting is at LV3)
Display shake setting B L K D F V E S OC S			
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $			
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	Display blank setting		7 Y E S CR LF 5
$ \begin{array}{ c $			7 YES CRLF 5
$ \begin{vmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1 \\ 1$		(Sets blank setting to LV1.)	
BLKKVNCCVFSCCFSSSJog solen responseJSWWNNN </td <td></td> <td>B L K L V 2 CR LF</td> <td>7 YES CRLF 5</td>		B L K L V 2 CR LF	7 YES CRLF 5
BLKONCVESOCVESOVVSJog and/drivesponeJSWONO </td <td></td> <td>BLK LV3CRLF</td> <td>7 Y E S CR LF 5</td>		BLK LV3CRLF	7 Y E S CR LF 5
(Additional banks barling.) J S W O V C V C<		(Sets blank setting to LV3.)	
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $		(Activates blank setting.)	
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $			
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	Jog switch response	J S W CRIF	
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $			O F F CR LF 3
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$			(Response of a state in which jog switch setting is OFF)
$ \left \begin{array}{c} (Active try is go witch exting) \\ J \in \mathbb{N} \left\{ \begin{array}{c} 0 \in J \in F \in \mathbb{C} \setminus U \\ (Deactive try is go witch exting) \\ J \in \mathbb{N} \left\{ \begin{array}{c} 0 \in J \in F \in \mathbb{C} \setminus U \\ (Deactive try is go witch exting) \\ (Deactive try is go witch exting) \\ (Deactive try is go witch exting) \\ Digital zero backup response \\ B \mid D \mid Z \mid O \mid N \mid OR \mid U \\ (Active tra digital zero trackup) \\ (Deactive trackup control \\ B \mid D \mid Z \mid O \mid N \mid OR \mid U \\ (Deactive trackup control \\ B \mid D \mid Z \mid O \mid N \mid OR \mid U \\ (Deactive trackup control \\ B \mid D \mid Z \mid O \mid P \mid CR \mid U \\ (Deactive trackup control \\ B \mid D \mid Z \mid O \mid P \mid CR \mid U \\ (Deactive trackup control \\ B \mid D \mid Z \mid O \mid P \mid CR \mid U \\ (Deactive trackup control \\ Control control control digital zero trackup control \\ B \mid D \mid Z \mid O \mid P \mid CR \mid U \\ (Deactive trackup control \\ Control cont$			
$ \left \begin{array}{c} (Active try is go witch exting) \\ J \in \mathbb{N} \left\{ \begin{array}{c} 0 \in J \in F \in \mathbb{C} \setminus U \\ (Deactive try is go witch exting) \\ J \in \mathbb{N} \left\{ \begin{array}{c} 0 \in J \in F \in \mathbb{C} \setminus U \\ (Deactive try is go witch exting) \\ (Deactive try is go witch exting) \\ (Deactive try is go witch exting) \\ Digital zero backup response \\ B \mid D \mid Z \mid O \mid N \mid OR \mid U \\ (Active tra digital zero trackup) \\ (Deactive trackup control \\ B \mid D \mid Z \mid O \mid N \mid OR \mid U \\ (Deactive trackup control \\ B \mid D \mid Z \mid O \mid N \mid OR \mid U \\ (Deactive trackup control \\ B \mid D \mid Z \mid O \mid P \mid CR \mid U \\ (Deactive trackup control \\ B \mid D \mid Z \mid O \mid P \mid CR \mid U \\ (Deactive trackup control \\ B \mid D \mid Z \mid O \mid P \mid CR \mid U \\ (Deactive trackup control \\ Control control control digital zero trackup control \\ B \mid D \mid Z \mid O \mid P \mid CR \mid U \\ (Deactive trackup control \\ Control cont$	log switch setting		
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	Sog Switch Setting	(Activates jog switch setting.)	
Digital zero backup response B D Z CR F CR S N CR <		J S W O F F CR LF	7 YES CRLF 5
Digital zero backup responseBDZCRCRCRZCR <td></td> <td>(Deactivates jog switch setting.)</td> <td>N O ? CR LF 5</td>		(Deactivates jog switch setting.)	N O ? CR LF 5
Image: control Image			
Image: control Image	Digital zero backup response		
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$			(Response of a state in which digital zero backup is ON)
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $			
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$			
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	Digital zero backup control		6 Y E S CR LF 5
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$			7 YES CRLF 5
Response of the number of patterns for pattern select P S N CR F S N S S S S S S S S N S			
Response of the number of patterns for pattern select P S N CR F S N S S S S S S S S N S	Digital zero data save command	S A V CRIE	3 YES CRIE
Response of the number of patterns for pattern select P S N CR F S N CR CR<			
Response of the number of patterns for pattern selectPSNCRLIICRIII			
for pattern selectIII<			
Control over the number of patternsPSN1CRI1Responsed state in which the number of patterns for patterns select is "5")Control over the number of patterns for patt		P S N CR LF	
Control over the number of patterns for patterns allectIICRLFICRCFFSN1CRCRFSN1CRCRFSNACRCRFSNACRCRFSNACRCRFSNACRCRFSNACRCRFFCRCRFFCRCRFFCRCRFFCRCRFFCR <td>for pattern select</td> <td></td> <td>8 CR LF</td>	for pattern select		8 CR LF
for pattern select (Sets the number of patterns for patterns select to 1.1, (Sets the number of patterns for patterns select to 10.7, (Sets the number of patterns for patterns select to 10.7, (Sets the number of patterns for patterns select to 10.7, (Sets the number of patterns for patterns select to 10.7, (Response of a state in which the linearize function is OFF) 3 0 F F CR L 3 3 0 F F CR L 1 N CR A 3 0 F F CR L 1 3 3 0 F F CR L 1 3 3 0 F F CR L 1 1 3 3 0 F F CR L 1 1 3 3 0 F F CR L 1			(Response of a state in which the number of patterns for pattern select is "8")
for pattern select V E S V E S CR F S S S V E S CR F S S S V E S CR F S S CR F S S CR F S S	Control over the number of patterns	P S N 1 CR LF	5 YES CRIF
(Sets the number of patterns for patterns		(Sets the number of patterns for pattern select to "1.")	
Linearize function status responseLINCRLFII <td></td> <td>P S N 8 CR LF 9</td> <td>5 Y E S CR LF 5</td>		P S N 8 CR LF 9	5 Y E S CR LF 5
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $			
$ \begin{array}{ c c c c c c c c c c c c c c c c c c c$	Linearize function status response	L I N CR LF	
Linearize function status settingLINOFFCCFCCFCCCFCCC<			
Linearize function status settingLINOFFCRLFILINOFFCRLFISCRLFSSS<			(Response of a state in which the linearize correction point is "2")
Linearize function status settingLINOFFC.R. LFISC.R. LFISSS <td></td> <td></td> <td></td>			
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $			
LIN2CRLF5YESCRLF5LIN16CRF6YESCRLF1CRLF5Tracking zero responseTRKCRLFIN1CRLF10Response of a state in which the tracking zero time is "1" and tracking zero widh is "1")10Tracking zero settingTRKCRLFIResponse of a state in which the tracking zero time is "1" and tracking zero widh is "1")12Tracking zero settingTRKT=1CRLF10Tracking zero settingTRKT=1CRLF10Tracking zero settingTRKT=1CRCRLF10Tracking zero settingTRKT=1CRLF10Tracking zero time is "1"ICRLFIResponse of a state in which the tracking zero time is "99" and tracking zero time is "1"12Gest tracking zero time to "1.")TRKT=99CRF5Gest tracking zero time to "99.")TRKW=99CRF5TRKW=99CRF5CRF5Gest tracking zero width to 190CR	Linearize function status setting		
(Sets linearize correction point to "2.") L I N 1 6 CR LF (Sets linearize correction point to "16.")6YESCRLF16Tracking zero responseTRKCRLF3ONT=1CRLF10Tracking zero responseTRKCRLFNNT=1CRLF10Tracking zero responseTRKCRLFNNT=1CRLF10Tracking zero responseTRKCRLFNNT=99CRLF10Tracking zero responseTRKT=1CRLF12Response of a state in which the tracking zero rime is "9" and tracking zero rime is "9"3OFFCRLF12Tracking zero rime to "1.")TRKT=1CRLF3Response of a state in which the tracking zero rime is "9" and tracking zero rime to "1.")8YESCRCRF5Tracking zero rime to "1.")TRKW=1CRFSCRF5TRKW=1CRFSCRCRF5Sets tracking zero rime t			5 Y E S CR LF 5
(Sets linearize correction point to "16.") 3 0 N T 1 CR LF 10 Tracking zero response T R K CR LF 10 (Response of a state in which the tracking zero time is "1" and tracking zero widh is "1") 0 N T = 9 9 CR LF 12 (Response of a state in which the tracking zero time is "1" and tracking zero time is "1") 0 N T = 9 9 CR LF 12 (Response of a state in which the tracking zero time is "1") 0 N T = 9 9 CR LF 12 (Response of a state in which the tracking zero time to "1.") T R K T = 9 9 CR LF 5 (Sets tracking zero time to "1.") T R K T = 9 9 CR LF 5 (Sets tracking zero time to "1.") T R K V = 9 9 CR F 5 (Sets tracking zero width to 1digit.) T R K		(Sets linearize correction point to "2.")	
Tracking zero responseTRKCRLF10Tracking zero isestingTRKCRLF10Tracking zero settingTRKTII </td <td></td> <td></td> <td></td>			
Tracking zero settingTRKTIICRLFITracking zero settingTRKTIICRLFI12Response of a state in which the tracking zero time is "1")ONTI99VI99CRLF12CRCRCRCRCRCRCRCRCRFCRCRF3OFFCRCRCRCRCRCRCRF3OFFCRCRCRCRCRCRF5OFFCRCRCRCRCRCRF5OFFCRCRCRCRCRCRCRCRF5OFFCR <t< td=""><td>Tracking part services</td><td></td><td></td></t<>	Tracking part services		
Tracking zero settingTRKTI1CRLF12Tracking zero settingTRKTI1CRLF12(Response of a state in which the tracking zero time is "99" and tracking zero width is "99")IIIITRKTI1CRLFII(Sets tracking zero time to "1.")TRKIIIIITRKVIICRLFIISets tracking zero time to "9.")TRKVIISCRLFITRKWIICRLFISCRLFITRKWIICRLFISCRLFITRKWIICRLFISCRLFSTRKWIICRLFISSCRLFSTRKWIICRLFISSCRLFSTRKWIICRLFISSCRLFSTRKVIIICRISSCRLFSTRKVIII <td< td=""><td>i racking zero response</td><td></td><td></td></td<>	i racking zero response		
Tracking zero settingTRKT=1CRLFSCRLFSSCRLFSSS </td <td></td> <td></td> <td>O N T = 9 9 W = 9 9 CR LF 12</td>			O N T = 9 9 W = 9 9 CR LF 12
Tracking zero settingTRKTIICRLFIISCRLFIISSSCRLFISSS </td <td></td> <td></td> <td></td>			
Tracking zero settingTRKT=1CRLF(Sets tracking zero time to "1.")TRKT=99CRLFTRKT=99CRLF(Sets tracking zero time to "39.")TRKW=1CRLFTRKW=1CRLF5(Sets tracking zero width to 1 digit.)TRKW=99SicRF(Sets tracking zero width to 1 digit.)TRKW=99SicRF5(Sets tracking zero width to 99 digits.)TRKT=0CRF5TRKT=0CRF5CRLF5TRKT=0CRF5CRLF5TRKT=0CRF5CRLF5TRKT=0CRLF5CRLF5TRKT=0CRLF5CRLF5TRKT=0CRLF5CRLF5TRKT=0CRLF5CRLF5CCCCC <td></td> <td></td> <td>OFFCRLF 3</td>			OFFCRLF 3
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $			(Response of a state in which the tracking zero function is OFF)
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $	Tracking zero setting		7 YES CRLF 5
(Sets tracking zero time to "99.") T R K W = 1 CR LF7YESCR LF5(Sets tracking zero width to 1 digit.) T R K W = 9 9 : CR LF8YESCR LF5(Sets tracking zero width to 99 digits.) T R K T = 0 CR LF0CR LF55(Deactivates the tracking zero function.)7YESCR LF5		(Sets tracking zero time to "1.")	
$ \begin{array}{c c c c c c c c c c c c c c c c c c c $			δ Y E S CR LF 5
TRKW=99CRLF5(Sets tracking zero width to 99 digits.)TRKT=0CRLF7YESCRLF5(Deactivates the tracking zero function.)CRLF7YESCRLF5		T R K W = 1 CR LF	7 YES CRLF 5
(Sets tracking zero width to 99 digits.) T R K T = 0 CR LF (Deactivates the tracking zero function.)			
T R K T = 0 CR LF 7 Y E S CR LF 5 (Deactivates the tracking zero function.) 5 </td <td></td> <td>(Sets tracking zero width to 99 digits.)</td> <td></td>		(Sets tracking zero width to 99 digits.)	
		T R K T = 0 CR LF	7 YES CRLF 5
			number of times setup of an average continuously after carrying out a tracking zero setup.

Function	1 2 3 4 5 6 7 8 9 10 11 12	13 14 15 Char. Length 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 Char. Length
Power-on delay time response	P O N CR LF	3 0 CR LF 1
		(Response of a state in which the power-on delayfunction is OFF)
		(Response of a state in which the power-on delay time is 1 second)
		9 CR LF
		(Response of a state in which the power-on delay time is 9 seconds)
Power-on delay time setting	PON 1 CR LF (Sets power-on delay time to 1 second.)	5 Y E S CR LF 5
	P O N 9 CR LF	5 Y E S CR LF 5
	(Sets power-on delay time to 9 seconds.)	
	PON 0 CR LF	5 Y E S CR LF 5
	(Deactivates the power-on delay function.)	
Protect level response	P R O CR LF	3 L V 0 CR LF 3
		(Response of a state in which the protect level is at LV0)
		L V 1 CR LF 3
		(Response of a state in which the protect level is at LV1)
		L V 2 CR LF 3 (Response of a state in which the protect level is at LV2)
		(Response of a state in which the protect level is at LV3)
Dente et les se les ettines		7 YES CRLF
Protect level setting	P R O L V 0 CR LF (Sets protect level to LV0.)	7 Y E S CR LF 5
	P R O L V 1 CR LF	7 YES CRLF 5
	(Sets protect level to LV1.)	
	PROLV2CRLF	7 Y E S CR LF 5
	(Sets protect level to LV2.) P R O L V 3 CR LF	7 Y E S CR LF 5
	(Sets protect level to LV3.)	
Unit number indication response	U N O CR LF	3 0 N CR LF 2
		(Response of a state in which the unit number indication is ON) O F F CR LF 3
		(Response of a state in which the unit number indication is OFF)
Unit number indication setting	U N O O N CR LF	6 Y E S CR LF 5
	(Activates unit number indication.)	7 Y E S CR LF 5
	(Deactivates unit number indication.)	
Start hold type response	S T T CR LF	3 A CR LF 1
		(Response of a state in which the start hold type is A) B CR LF 1
		(Response of a state in which the start hold type is B)
Start hold type setting	S T T A CR LF	5 Y E S CR LF 5
	(Sets start hold type to A) S T T B CR LF	5 Y E S CR LF 5
	(Sets start hold type to B.)	
Peak hold type response	P V T CR LF	3 A CR LF 1
		(Response of a state in which the peak hold type is A) B CR LF 1
		(Response of a state in which the peak hold type is B)
Peak hold type setting	P V T A CR LF	5 YES CRLF 5
reak noid type setting	(Sets peak hold type to A.)	
		5 YES CRLF 5
	P V T B CR LF (Sets peak hold type to B.)	5 Y E S CR LF 5

Function	1 2 3 4 5 6 7 8 9 10 11 12 13	14 15 Char. Length		
Baud rate response	B A U CR LF	3	2 4 0 0 CR LF	4
			(Response of a state in which the baud rate is 2400 bps)	
			(Response of a state in which the baud rate is 4800 bps)	4
			9 6 0 0 CR LF	4
			(Response of a state in which the baud rate is 9600 bps)	
			1 9 2 0 0 CR LF	5
			(Response of a state in which the baud rate is 19200 bps)	
			3 8 4 0 0 CR LF	5
			(Response of a state in which the baud rate is 38400 bps)	
	B A U 2 4 0 0 CR LF	8	Y E S CR LF	5
	(Sets the baud rate to 2400 bps.)	Ŭ		, i i
	B A U 4 8 0 0 CR LF	8	Y E S CR LF	5
	(Sets the baud rate to 4800 bps.)			
	B A U 9 6 0 0 CR LF	8	Y E S CR LF	5
	(Sets the baud rate to 9600 bps.) B A U 1 9 2 0 0 CR LF	9	Y E S CR LF	5
	(Sets the baud rate to 19200 bps.)	9		
	B A U 3 8 4 0 0 CR LF	9	Y E S CR LF	5
	(Sets the baud rate to 38400 bps.)		* The baud rate is switched upon next power-up.	
Data length response	D A T CR LF	3	7 CR LF	1
			(Response of a state in which the data length is 7 bits) 8 CR LF	1
			(Response of a state in which the data length is 8 bits)	
	DAT 7 CR LF	5	Y E S CR LF	5
	(Sets data length to 7 bits.)			
	DAT 8 CR LF	5	Y E S CR LF	5
	(Sets data length to 8 bits.)		* The data length is switched upon next power-up.	
Parity bit response	P B T CR LF	3	E V E N CR LF	4
ranty bit lesponse		5	(Response of a state in which a parity bit is even parity)	4
			O D D CR LF	3
			(Response of a state in which a parity bit is odd parity)	
			N O CR LF	2
			(Response of a state in which a parity bit is none)	
	P B T E CR LF	5	Y E S CR LF	5
	(Sets a parity bit to even parity.)	5		
	P B T O CR LF	5	Y E S CR LF	5
	(Sets a parity bit to odd parity.)			
	P B T N CR LF	5	Y E S CR LF	5
	(Sets a parity bit to none.)		* A parity bit is switched upon next power-up.	
Otan hit manana a	S B T CR LF		1 CR LF	
Stop bit response		3	(Response of a state in which a stop bit is 1 bit)	1
			2 CR LF	1
			(Response of a state in which a stop bit is 2 bits)	
	S B T 1 CR LF	5	Y E S CR LF	5
	(Sets a stop bit to 1 bit.)	5		5
	S B T 2 CR LF (Sets a stop bit to 2 bits.)	5	Y E S CR LF * A stop bit is switched upon next power-up.	5
Delimiter response	D L M CR LF	3	C R + L F CR LF	5
			(Response of a state in which a delimiter is CR + LF)	
			C R CR LF	2
			(Response of a state in which a delimiter is CR)	
	D L M C L CR LF	6	Y E S CR LF	5
	(Sets a delimiter to CR + LF.)	0		
	D L M C CR LF	5	Y E S CR LF	5
	(Sets a delimiter to CR.)		* A delimiter is switched upon next power-up.	
Device ID response	A D R CR LF	3	1 CR LF	1
			(Response of a state in which the device ID is "01")	2
			9 9 CR LF	2 ²
Device ID setting	A D R 1 CR LF	5	Y E S CR LF	5
5	(Sets device ID to "01".)			
	A D R 9 9 CR LF	6	Y E S CR LF	5
	(Sets device ID to "99".)		* Device ID is switched upon next power-up.	
				1 1

Function	1	2 3 4	5 6 7 8	9 10 11	12 13 1	1 15 Char. Leng	th 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 Char.	. Length
Condition data parameter response	A					3	A V G 1 CR LF	5
							(Response of a state in which the number of averaging times is "1") M A V O F F CR LF	7
							(Response of a state in which the moving averaging function is OFF)	_
							S W D 1 CR LF 4 (Response of a state in which step wide is "1")	5
							C L R R E D CR LF	7
							(Response of a state in which the display color is red) 1 C L T M A N U A L CR LF 1	10
							(Response of a state in which the display color type is Manual)	10
								7
							(Response of a state in which the HH display color is red) C H I R E D CR LF I <td< td=""><td>7</td></td<>	7
							(Response of a state in which the HI display color is red)	_
							C G O R E D CR LF	7
								7
							(Response of a state in which the LO display color is red) C L R E D CR L I	7
							(Response of a state in which the LL display color is red)	
							B L K O F F CR LF	7
								6
							(Response of a state in which the jog switch is ON)	
							P V H P H - O F F CR LF 1 (Response of a state in which peak hold select is OFF at PH) 1	10
							B D Z O N CR LF	6
							(Response of a state in which digital zero backup is ON) P S N 1 CR LF	5
							(Response of a state in which pattern select is "1")	
							L I N O F F CR LF Image: CR Image: CR <t< td=""><td>7</td></t<>	7
								7
							(Response of a state in which tracking zero is OFF)	5
							PONOOCRLF (Response of a state in which the delay time is "0")	5
								7
							(Response of a state in which the protect level is at LV0) U N O F F CR LF F <td< td=""><td>7</td></td<>	7
							(Response of a state in which unit number indication is OFF)	_
							S T T A CR LF Image: CR Image	5
							S T D	9
							P V T A CR LF Image: CR Image	5
							B A U 9 6 0 0 CR LF	8
							(Response of a state in which the baud rate is 9600 bps) D A T 7 CR LF	5
							(Response of a state in which the data length is 7 bits)	5
								8
							(Response of a state in which a parity bit is even parity) S B T 2 CR LF 4	5
							(Response of a state in which a stop bit is 2 bits)	
							D L M C R + L F CR LF (Response of a state in which a delimiter is CR + LF)	9
								5
							(Response of a state in which the device ID is 01)	
Scaling data parameter response	A	L 2 CR L	F			3		3
							(The pattern used previously is responded.)	7
							(Response of a state in which the measurement range is 2 A)	
							(Response of a state in which the input type is open collector)	8
							F S C 9 9 9 9 9 CR LF 1 (Response of a state in w hich the full-scale indicated value is "9999") 1	10
							F I N 9 9 9 CR LF 1	10
							(Response of a state in which the full-scale input value is "9999") O F S I O CR LF	10
							(Response of a state in which the offset indicated value is "0")	10
							(Response of a state in which the offset input value is "0")	
								7
							P P R 1 CR LF	5
							(Response of a state in which the frequency division value is "1") D L H I 9 9 9 9 0 CR LF	10
							(Response of a state in which the digital limiter HI value is "9999")	
							D L L O - 9 9 9 CR LF 1 (Response of a state in which the digital limiter LO value is "-9999")	10
							A O U T 0 - 1 CR LF	8
								9
							(Response of a state in which the analog output HI indicated value is "9999")	6
							(Response of a state in which the analog output LO indicated value is "0")	
							UNITIC CRLF (Response of a state in which the temperature indication unit is °C)	6
								7
							(Response of a state in which there is no decimal point)	
				· · · ·	4 1 1	· ·		

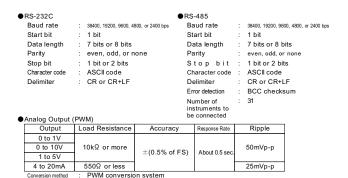
Function		2			5	6 7 8	9	10	11 } 12	2 13	14	15	Char. Length	
Comparator data parameter response *Case of the comparison output type is high-and low-limit setting	A	L	3	CR	LF								3	P - 1 CR LF 3 (The pattern used previously is responded.) C O M T O / U CR LF 8
														(Response of a state in which the comparison output type is of high-and low-limit setting) H - S 1 0 0 0 0 CR LF 10 10
														(Response of a state in which the HI judgment value is "1000") L O - S - S - S - S - S - S
														(Response of a state in which the LO judgment value is "500") 1 H I - H 0 CR LF 10 10
														(Response of a state in which the HI hysteresis is "0") 1 L O - H 1 10 CR L O - H 10
														(Response of a state in which the LO hysteresis is "0") H I - L N O CR LF
														(Response of a state in which HI logic is normally open) Image: Comparison of a state in which GO logic is normally open) 7 (Response of a state in which GO logic is normally open) 7
														(Response of a state in which LO logic is normally open)
*Case of the comparison output type is the tolerance judgment	A	L	3	CR	LF		\uparrow		-	1			3	P - 1 CR LF 3 (The pattern used previously is responded.) 3 3 3 3
														C O M T E R R CRLF 8 (Response of a state in which the comparison output type is of
														$ \begin{array}{c c} Response \\ Ins \\ V \\ A \\ L \\ Ins \\ I$
														Response of a state in which the nominal value is "5000") 1 E R 1 5 0 0 CR LF 11
														(Response of a state in which tolerance 1 is "5.00") 1 E R 1 1 0 CR{LF 10
														$\begin{array}{c c c c c c c c c c c c c c c c c c c $
														(Response of a state in which HI logic is normally open) G O ! - L N O CR LF
														(Response of a state in which GO logic is normally open)
														Response of a state in which LO logic is normally open) N O ? CR LF
Calibration data response			4	CR	LF		-		_	_			3	(Response made if the relevant input unit is not installed) P - 1 (CR LF
		-											-	The pattern used previously is responded.) S N S R 5 CR LF 6
														(Response of a state in which the sensor power is 5 V) 1 Z R I N 0 . 0 0 CR LF 10
														CResponse of a state in which the zero input value is "0.000") Z E R O 0 CR LF 6
														(Response of a state in which the zero indicated value is "0") S P I I N 2 0 0 CR LF 10
														(Response of a state in which the span input value is "2.000") \$\$ P A N \$\$ 9 9 9 9 CR LF\$\$ \$\$ 9
														(Response of a state in which the span indicated value is "9999") N O ? CR LF 5
														(Response made if the relevant input unit is not installed)
Linearize data response	A	L	5	CR	LF								3	0 1 6 (Response of a state in which the linearize data N-01 input value is "0") 0 1 1 0 = 0 ICR LF 3 6 6
														0 1 0 = 0 0R LF 6 (Response of a state in which the linearize data N-01 output value is "0") 0 2 1 = 1 0 0 CR LF 8
														(Response of a state in which the linearize data N-02 input value is "100") 0 2 0 = 1 1 1 0 CR LF 8
														(Response of a state in which the linearize data N-02 output value is "110")
														0 2 1 = 5 0 0 CR LF 8
														1 6 I I 9 0 0 0 CR LF 9 (Response of a state in which the linearize data N-16 9
														input value is "9000")
														output value is "9200")
														(Response of a state in which the linearize function is OFF)
Common response	┢	-	┝	1			-			+				Y E S CR LF 5
														(Normal response) N 0 7 CR LF 5
														(Response to an undefined command, etc.)
														E R R O R A CR LF I F F F F F F F F F F F F F F F F F
														(Response made if there is a communication parameter error) * There are ERROR B to ERROR F as an equivalent response command. * If there is a response of the ERROR X command, perform the
														same steps again. If this does not solve the problem, turn the meter supply OFF and then ON again.
Response made if internal memory data is abnormal														D A T A L O S T C O N D CR LF 14 (Response made if condition data is abnormal)
* Generally, a response is made only once.														D A T A L O S T C O M CR LF 13
														(Response made if comparator data is abnormal)
														(Response made if scaling data is abnormal)
														* Set scaling data again.
	-	-	•	2			-	· ·	0		, 1			

INSTRUCTION MANUAL MODEL A6xxx-x5/x6/x7/x8

Function Scaling data setting	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 Char. Length 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 Char. Length 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 Char. Length 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 Char. Length 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 M E T CR LF 3 P - 1 CR LF 14 15 16	17 18 Char. Length
	* Indication becomes "MET" at the instant the MET (The pattern used previously is responded.)	
	command has been received.	
	2 CR LF	3
	M CR LF 2 R A N G 2 A CR LF	7
		7
	(Sets the measurement range to 1 V.) 1 F S C 9 9 9 CR LF	8
		U U U
	8 0 0 0 CR LF 4 F S C 8 0 0 0 CR LF	8
	(Sets the full-scale indicated value to "8000.") 1 0 F S 0 CR LF I <t< td=""><td>5</td></t<>	5
		5
	2 0 0R LF 2 0 F S 2 0 0R LF	6
	(Sets the offset indicated value to "20.")	
	E CR LF	5
	command causes data acquired up to that point to be NO ? CR LF	5
	return to measurement operation. (Response made if a value out of the setting range is input)	
Comparator data setting	COMCRIF	3
*Case of the companson output type	* The main unit's indication becomes "COM" at the (1) (The pattern used previously is responded.)	
is high-and low-limit setting.	instant the COM command has been received.	
Sets data-setting pattern to "2" and HI logic to "8000",set LO logic to "-5000",		3
and sets HI &LO logic to normally	Sets data-setting pattern to "2.") 1 C O M U CR LF I	8
closed.		
	M CR LF 1 H I - S 1 0 0 0 CR LF	9
	8 0 0 0 CR LF	9
	(Sets HI logic to "8000.")	
	M CR LF 1 L O - S 5 0 0 CR LF	8
	- 5 0 0 0 0 0 CR LF 5 L O - S - 5 0 0 0 0 CR LF	
	- 5 0	10
		6
	M CR LF 1 L O - H 0 CR LF	6
	M CR LF	7
	N C CR LF LF LF LF (Sets HI logic to normally closed.) 2 H I - L N C CR LF	7
	M CR LF 1 G O - L N O CR LF	7
	M CR LF 1 L O - L N O CR LF	7
		7
	(Sets LO logic to normally closed.)	
		5
	A return to measurement operation using the E E R R O R 0 CR LF	7
	command (If the N command is sent, a return to side judgment value is made.)	
	N 0 ? 08 LF	5
	(Response of a state in which the relevant input unit is not installed)	
*Case of the compason output type is sets the nominal value to "8000",	C O M CR LF 3 P - 1 CR LF 3 P - 1 CR LF 5 COM at the 5 CO	3
sets the tolerance 1 to "20.00".		8
	E R R CR LF 6 C O M T E R R CR LF (Sets the comparator output type to tolerance judgment.)	8
	M CR LF 1 N V A L 5 0 0 0 CR LF	10
	8 0 0 0 CR LF 4 N V A L 8 0 0 0 CR LF	10
	(Sets the nominal value to "8000.") 1 E R 1 5 . 0 0 CR LF	11
	2 0 0 0 CR LF 5 E R R 1 2 0 . 0 0 CR LF	11
	Sets tolerance 1 to "20.00.") 1 E R 1 H 0 0 CR LF 0 CR	10
		5
	* Areturn to measurement operation using the E	
	command (If the N command is sent, a return to side judgment value is made.)	7
	side judgment value is made.) (Response made if a value not meeting the setting conditions is input NO OR	5
	(Response of a state in which the relevant input unit is not installed)	
* The serves estimation methods as these a	above are also used for setting of other data (such as linearize data)	

* The same setting methods as those above are also used for setting of other data (such as linearize data).

5 Specifications and Dimensions



about 14 bits or equivalent

Resolution

6 Warranty and After-sales Services

6.1 Warranty

The warranty period of this product is one year from the date of delivery. If a problem occurs during this warranty period and its cause is determined to be attributable to us, and will repair the product without charge.

6.2 After-sales Services

This product has been manufactured, tested, and inspected under strict quality control before shipment from the factory. If the product breaks down, contact your sales representative or our local office (or send it). In this case, write down the problem in detail and report it to your service representative (or enclose it with the product).

