Instruction Manual for A6000 Series Universal Digital Panel Meters **Resistance Measurement Unit**

A Caution

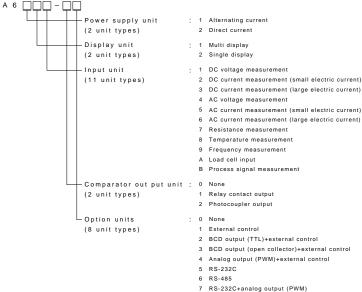
- Applying a voltage or current exceeding its maximum permissible value may cause the unit to be damaged. Always use the unit within the specified voltage range; otherwise, it may cause a fire, electric (1)
- (2)
- shock or personal/equipment damage. For the purpose of functional improvement, the information written herein may be changed (3) without prior notice.
- Information contained herein is considered accurate to the best of our knowledge. If you have (4) any question or comment on the information, please contact us or our distributo (5)
- Read this manual carefully and thoroughly before starting to operate the unit, and keep the manual available for future reference.

1 Before Using the Unit

Thank you for purchasing our quality designed and manufactured A6000 Series. Before unpacking the unit, check for damages during transportation. If you have noticed any damage, directly contact us or our distributor.

1.1 Type Identification

Each model number of the A6000 series has its general specifications, and the following describes each note and the meaning. Before using the unit, check that the model number and specifications of the delivered unit match those of the product you ordered. For optional units, see the separate instruction Manuals.



RS-485+analog output (PWM)

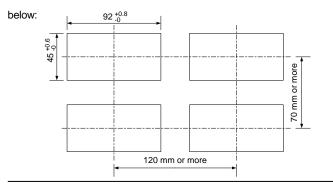
1.2 Accessories

| Accessory | Quantity | Remarks |
|-----------------------|-------------|--|
| 6-p terminal cover | 2 or 3 each | 2 without a comparator output 3 with a comparator output |
| Mounting band | 2 pieces | |
| Unit indication label | 1 each | |

Mounting Method 2

Panel Cut Size 2.1

Cut the panel to mount the A6000 series in accordance with the illustration



2.2 How to Mount the Unit on the Panel

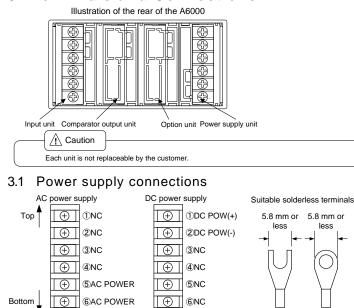
Mount the A6000 series to the panel in accordance with the illustration

below: (1) Remove the mounting band and insert the case (2) Fix the case using the mounting band from the rear of the panel from the front of the panel

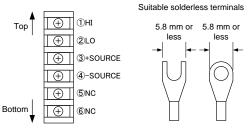
▲ Caution

- (1) The recommended panel thickness is 0.8 to 5mm (i) The recommended parter thickness is 0.5 to 5000 minit.
 (2) Do not install the unit in locations where it is exposed to direct sunlight; where ambient emperature or humidity doesn't meet the requirements below; or where a drastic change in temperature may ause condensation. Ambient temperature: 0 to 50°C Ambient temperature: 0 to 50°C
 (3) Do not install the unit where it is exposed to dust, particles, chemicals harmful to electric components, corrosive gases, etc.
- (4) When this unit is installed inside other equipment, pay attention to the heat radiation and keep the heat inside the equipment 50°C or below.
- (5) Do not install the unit where it is exposed to excessive vibration or shock.
- (6) Install the unit horizontally; otherwise, ventilation will be adversely affected and may result in deterioration.

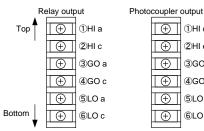
3 Terminals and Connections

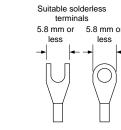


3.2 Input Signal Connections



3.3 **Comparator Output Connections**





3.4 Option connections

For connections of the options, see separate optional function instruction Manuals.

(+)

 \oplus

①HI c

②HI e

3GO c

④GO e

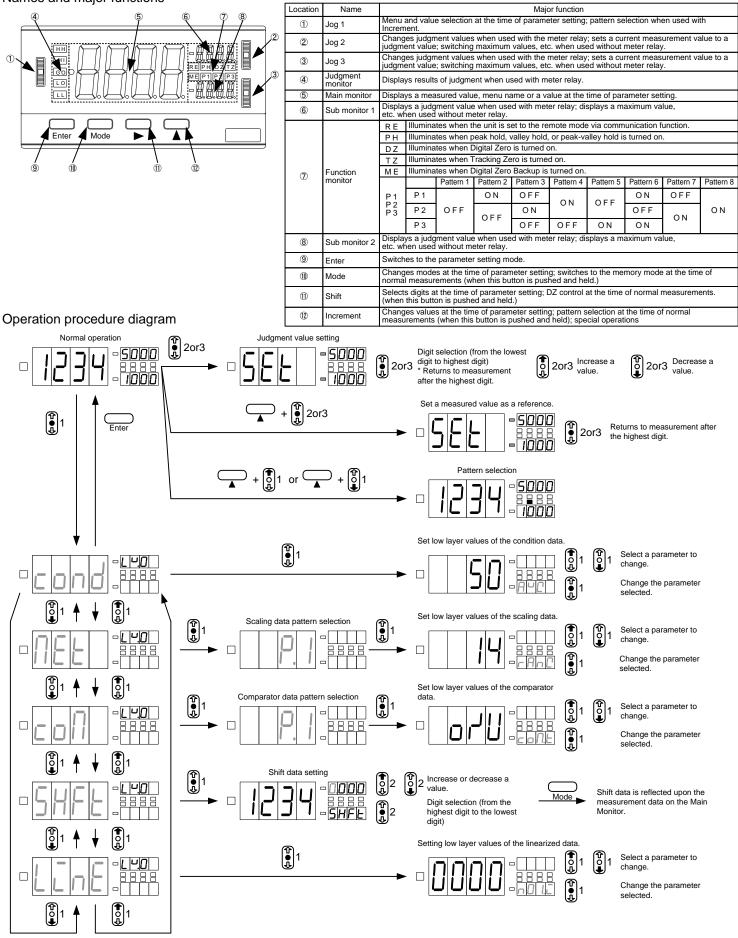
⑤LO c

⑥LO e

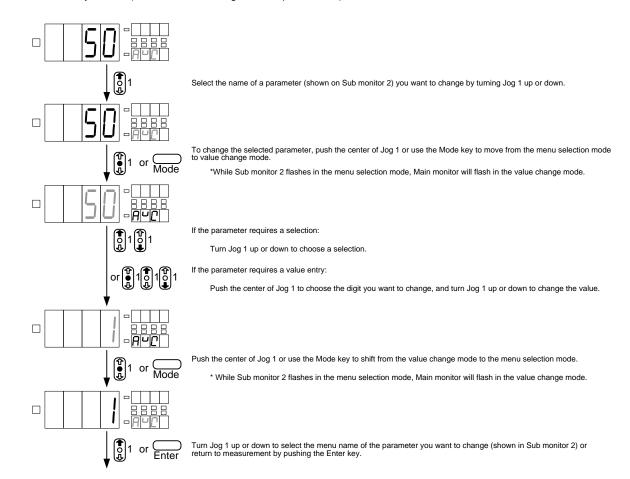
4 Parameter Settings

4.1 Multi Display Unit

Names and major functions



How to set a low layer value (Condition data/scaling data/comparator data)

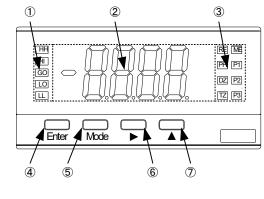


Remarks:

%The multi display unit can also follow the operation procedure of the single display unit operation system.
%Comparator judgment values can be set not only from Jog 2 and Jog 3 but also from the low layers of the comparator data.
%For operation procedures in the memory mode (maximum value/minimum value/(maximum value-minimum value)), see the operation procedure diagram of the single display unit.

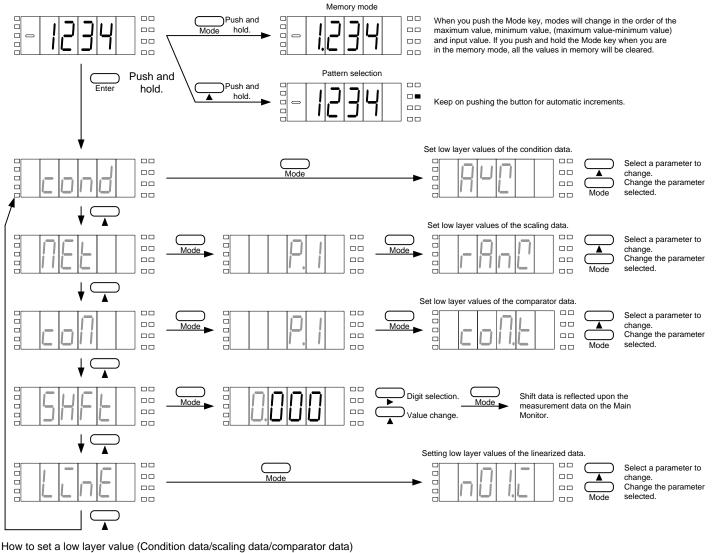
4.2 Single Display Unit

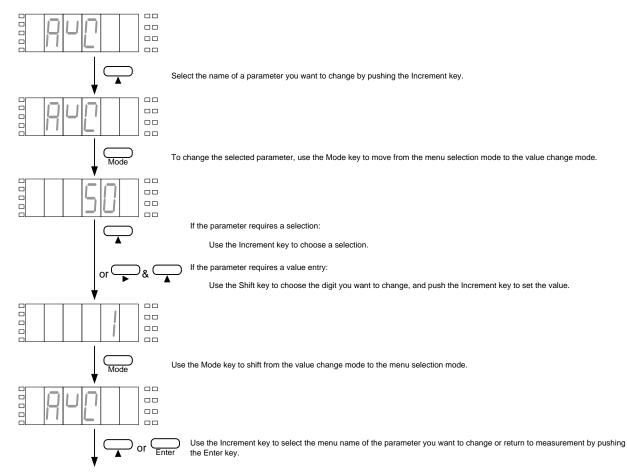
Names and major functions



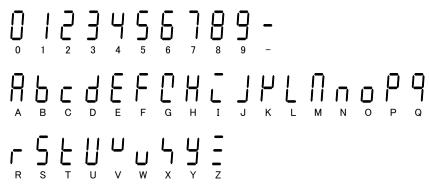
| Location | Name | | Major function | | | | | | | | |
|----------|------------------|-----------------|--|--------------------------------|------------------------------|--------------------------------|-----------------------------|-------------------------|--------------|-------------|-------------|
| 1 | Judgment monitor | Displa | iys juo | dgment res | ults when u | used with n | neter relay | | | | |
| 2 | Main monitor | Displa | iys a i | measured | value as we | ell as menu | i names ar | nd values a | t the time o | of paramete | er setting. |
| | | RE | Illur | ninates wh | en the unit | is set to th | e remote n | node via co | ommunicati | on functior | ι. |
| | | ΡH | Illur | ninates wh | en peak ho | ld, valley h | old, or pea | ak-valley ho | old is turne | d on. | |
| | | DZ | Illur | ninates wh | en Digital Z | Zero is turn | ed on. | | | | |
| | | ΤZ | Illur | ninates wh | en Trackin | g Zero is tu | Irned on. | | | | |
| 3 | Function monitor | ΜE | Illuminates when Digital Zero Backup is turned on. | | | | | | | | |
| | | | | Pattern 1 | Pattern 2 | Pattern 3 | Pattern 4 | Pattern 5 | Pattern 6 | Pattern 7 | Pattern 8 |
| | | P1 P2 | P1 | | ON | OFF | ON | OFF | ON | OFF | ON |
| | | P2 P3 | Ρ2 | OFF | OFF | ON | UN | | OFF | | |
| | | | Ρ3 | | OFF | OFF | OFF | ON | ON | ON | |
| 4 | Enter | Switch | nes to | the param | eter setting | g mode. | | | | | |
| 5 | Mode | Chang norma | ges m al mea | odes at the surements | e time of pa s (when this | rameter se s button is | etting; swite oushed and | ches to the d held.) | memory m | ode at the | time of |
| 6 | Shift | Select (when | Selects digits at the time of parameter setting; DZ control at the time of normal measurements. (when this button is pushed and held.) | | | | | | | | |
| Ī | Increment | Chang (when | es val this bu | ues at the ti utton is push | me of param ned and held | eter setting l) ; special o | pattern sel | ection at the | time of nor | mal measur | ements |

Operation procedure diagram





4.3 Numeric and Character Indications



4.4 Protection Levels

Each parameter of the A6000 has an individual protection level, and by setting the protection level of the condition data, you can set an access level. (For the protect level of each parameter, see the P.L. column of the tables in Section 4.5.)

The higher the protection level is, the less the number of settable parameters will be. If you set the protection level to the strictest LV3, you can change the protection level only, and all the other parameters may not be changed. (No comparator judgment value can be changed using the jog switches in this case.) *The protection level set at the time of shipment is LV1. (Settings of display colors, scaling and judgment-related values only are available.)

4.5 List of the Parameters

4.5.1 Condition Data

| Menu indication | Parameter name | Initial value | P.L. | Setting range or alternatives | Major setting purpose and remarks |
|--------------------|-------------------------------|------------------|------|---|---|
| AVG | Average times | 50 | 0 | 1/2/4/8/10/20/50/100/200/ 400/800/1000/2000/5000 | Selects Conversion rate (average times of internal sampling; sampling time: approx. 1 millisecond) |
| MAV | Average times of movements | 1 | 0 | 1/2/4/8/16/32 | Selects the average times of movements.Filtering effects: Small<1(OFF)-2-4-8-16-32>Big |
| S.WD | Step wide | 1 | 0 | 1/2/5/10 | Selects the range of display changes to maintain image display consistency. (If this parameter is set to 5, the lowest digit will display either 0 or 5 only). |
| CLR | Display color | RED | 1 | RED/GREEN | Selects display colors.*Only when without meter relay. |
| CLR.T | Display color type | Αυτο | 1 | AUTO/MANU | Selects automatic (red in the HI or LO mode or green in the GO mode) or manual setting for display color type. *Only when with meter relay. |
| HI.CL | HI display color | RED | 1 | RED/GREEN | Selects red or green as display color at the time of HI judgment.*Only when CLR.T is MANU. |
| GO.CL | GO display color | GREN | 1 | RED/GREEN | Selects red or green as display color at the time of GO judgment.*Only when CLR.T is MANU. |
| LO.CL | LO display color | RED | 1 | RED/GREEN | Selects red or green as display color at the time of LO judgment.*Only when CLR.T is MANU. |
| BLNK | Display blank level | OFF | 0 | OFF/LV1/LV2/LV3/ON | Selects the display brightness. kinetry of the display brightness. |
| J.SW | Jog SW | ON | 0 | ON/OFF | Selects whether the jog SW is used or not.*With the multi display unit only. |
| PVH | PH Selection | PH | 0 | PH/VH/PVH | Selects a type that operates when the PH function is turned on (peak hold/valley hold/peak-valley hold). |
| DZ.BU | DZ backup | OFF | 0 | OFF/ON | Selects whether the digital zero value is backed up or not at the time when the unit is turned off. |
| ΡS | P.SEL | 1 | 0 | 1/2/4/8 | Selects the number of patterns available for the pattern selection function. |
| LINE | Linearize | OFF | 0 | OFF/2/4/8/16 | Selects whether the linearize function is enabled/disabled and sets the number of correction points. |
| TR.T | TZ time | 000 | 0 | 000 to 999 | Selects whether the tracking zero function is enabled/disabled and sets the correction time (setup value/conversion rate). |
| TR.W | TZ correction range | 01 | 0 | 01 to 99 | Sets the correction range of the tracking zero function.*Only when TR.T is set to a value other than 000. |
| P.ON | Power on delay time | 0 | 0 | 0 to 9 | Sets the time between the startup and actual start of measurements (setup value x 1 second). |
| PRO | Protection level | LV.1 | 3 | Lv.0/LV.1/LV.2/LV.3 | Selects the protection level to prevent operation mistakes.High< LV3-LV2-LV1-LV0 >Low |
| U-NO. | Unit number indication | OFF | 0 | OFF/ON | Selects whether the code of a unit mounted at the time of startup is displayed or not. |
| S/H.T | Start/hold type | А | 0 | A/B | Selects an operation type of start/hold (A: free run; B: one shot).*Only with the external control. |
| S/H.D | S/H delay time | 0 | 0 | 0 to 9999 | Sets the delay time at the time of startup (setup value x 1 ms).*Only with the external control. |
| PVH.T | PH type | А | 0 | A/B | Selects an operation type of peak hold (A: real-time display; B: results display).*Only with the external control. |
| DZ.C | DZ control | SW | 0 | SW/TERM | Selects a control method of Digital Zero (SW: front key; TERM: external control terminal).*Only with the external control. |
| PS.C | P.SEL control | SW | 0 | SW/TERM | Selects a control method of Pattern Selection (SW: front key; TERM: external control terminal).*Only with the external control. |
| BCD.L | BCD logic | N.LOG | 0 | N.LOG/P.LOG | Selects the BCD output logic (N: negative logic; P: positive logic).*Only when the BCD output is available. |
| BAUD | Baud rate | 9600 | 1 | 2400/4800/9600/19200/38400 | Sets a baud rate for communication.*Only when the communication function is available. |
| DATA | Data length | 7 | 1 | 7/8 | Selects the data length for communication.*Only when the communication function is available. |
| P.BIT | Parity bit | Е | 1 | E/O/N | Selects the parity bit for communication.*Only when the communication function is available. |
| STP.B | Stop bit | 2 | 1 | 1/2 | Selects the stop bit for communication.*Only when the communication function is available. |
| Τ- | Delimiter | CR.LF | 1 | CR.LF/CR | Selects a delimiter for communication.*Only when the communication function is available. |
| ADR | Equipment ID | 01 | 1 | 01 to 99 | Selects the equipment ID for the RS-485 function.*Only when the RS-485 function is available. |

4.5.2 Scaling Data

| Menu indication | Parameter name | Initial value | P.L. | Setting range or alternatives | Major setting purpose and remarks |
|--------------------|-----------------------|------------------|------|---|---|
| RANG | Input range | 14 | 1 | 11/12/13/14 | Selects an input range. |
| FSC | Full scale indication | 9999 | 2 | -9999 to +9999 | |
| FIN | Full scale input | 9999 | 2 | -9999 to +9999 | Sets the relationship between the input signal and its indication. |
| OFS | Offset indication | 0 | 2 | -9999 to +9999 | |
| OIN | Offset input | 0 | 2 | -9999 to +9999 | |
| DLHI | Digital limiter HI | 9999 | 0 | -9999 to +9999 | Sets the upper limit of the displayable range. (Any value equal to or exceeding the digital limiter HI setting will not be updated and kept at the setup value. |
| DLLO | Digital limiter LO | -9999 | 0 | -9999 to +9999 | Sets the lower limit of the displayable range. (Any value equal to or below the digital limiter LO setting will not be updated and kept at the setup value. |
| A.OUT | Analog output type | 0-1 | 1 | 0-1/0-10/1-5/4-20 | Selects an analog output range.*Only when the analog output is available. |
| AOHI | Analog output HI | 9999 | 1 | -9999 to +9999 | Sets the relationship between indications and analog outputs.*Only when the analog output is available. |
| AOLO | Analog output LO | 0 | 1 | -9999 to +9999 | |
| DP | Decimal point | None | 2 | Each digit can be set independently. | Sets the position of the decimal point. |

4.5.3 Comparator Data (for meter relay only)

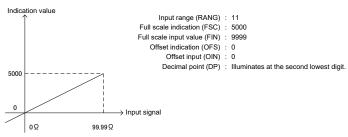
| Menu indication | Parameter name | Initial value | P.L. | Setting range or alternatives | Major setting purpose and remarks |
|--------------------|------------------------|------------------|------|----------------------------------|--|
| COM.T | Comparator output type | O/U | 1 | O/U/ERR | Select either [above or below] or error comparator types. |
| HI-S | Hl judgment value | 1000 | 2 | -9999 to +9999 | Sets a HI judgment value.*Only when COM.T is O/U. |
| LO-S | LO judgment value | 500 | 2 | -9999 to +9999 | Sets a LO judgment value.*Only when COM T is O/U. |
| N.VAL | Nominal value | 5000 | 2 | -9999 to +9999 | Sets a nominal value.*Only when COM.T is ERR. |
| ERR1 | Error 1 | 5.00 | 2 | 0.00 to 99.99 | Sets an error.*Only when COMT is ERR |
| HI-H | HI hysteresis | 0 | 1 | 0 to +999 | Sets a HI hysteresis value *Only when COM.T is O/U. |
| LO-H | LO hysteresis | 0 | 1 | 0 to +999 | Sets a LO hysteresis value *Only when COM T is O/U. |
| ER1.H | Error 1 hysteresis | 1 | 1 | 0 to +999 | Sets an error hysteresis *Only when COM.T is ERR. |
| HI-L | HI logic | N.O | 0 | N.O/N.C | Sets a HI output logic (N.O.=normally open or N.C.=normally closed)*Output when the power is OFF is always open (OFF). |
| GO-L | GO logic | N.O | 0 | N.O/N.C | Sets a GO output logic (N.O.=normally open or N.C.=normally closed)*Output when the power is OFF is always open (OFF). |
| LO-L | LO logic | N.O | 0 | N.O/N.C | Sets a LO output logic (N.O.=normally open or N.C.=normally closed)*Output when the power is OFF is always open (OFF). |

5 Setting Examples

5.1 Scaling Data Setting Examples

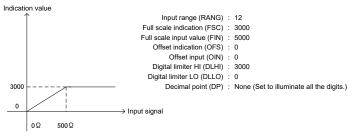
Example 1

. When the input varies between 0 to 99.99Ω, corresponding indication values should be 0.00 to 50.00.

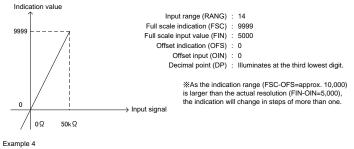


Example 2

When the input varies between 0 to 500Ω , corresponding indication values should be 0 to 3000.



When the input varies between 0 to $50k\Omega$, corresponding indication values should be 0 to 9999.



When the input varies between 0 to $9.999k\Omega$, corresponding indication values should be 1000 to 0.

Input signal

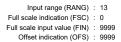
9.999k Ω

Indication value

9999

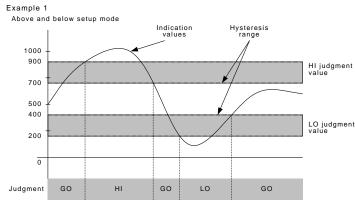
0

Example 3



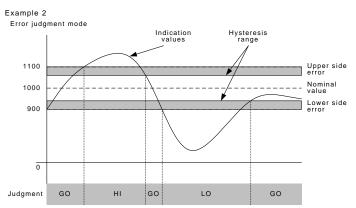
Offset input (OIN) : 0 Decimal point (DP) : None (Set to illuminate all the digits.)

Comparator Data Setting Examples (for meter relay only) 5.2



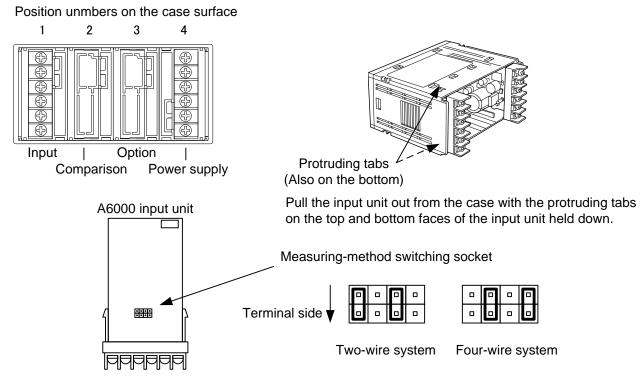
%The hysteresis is effective either in the range lower than the HI judgment value or that higher than the LO judgment value.

5.3 How to Switch the Measuring Method



%Error is to be set as a percentage of the nominal value.

%The hysteresis is to be set as xx digits of the indication value.
 %The hysteresis is effective either in the range lower than the upper side error or that higher than the lower side error.



XUpon shipment from the factory, the measuring-method switching socket is set two-wire system side. When installing the input unit, slide it along the guides inside the main-unit case.

%Push the input unit into the case so that the input unit's connector (female) is securely fit into the display unit's connector (male).

6 Specifications and External Dimensions

6.1 Input Specifications

| Resistan | ce measurements | | | |
|----------|-------------------|---|---|-----------------|
| Range | Measurement range | Indication | Error (23°C ±5°C; 35 to 85%) | Circuit current |
| 11 | 99.99 Ω | | | Approx. 9mA |
| 12 | 999.9 <i>Ω</i> | Offset: ±9999 | + (0.40(of refer + 4 digit) | Approx. 0.9mA |
| 13 | 9.999k Ω | Full scale: ±9999 | \pm (0.1% of rdg + 4digit) | Approx. 0.09mA |
| 14 | 99.99k Ω | | | Approx. 0.009mA |
| • | 8 | Aaximum approx. 1,00 wo-wire system or fou | 0 times/second ur-wire system (Internal socket c | hange-over) |

%The error is applied when the sampling rate is 20 times/second or less

Caution

The instrument is set to the two-wire measuring method upon shipment from the factory.

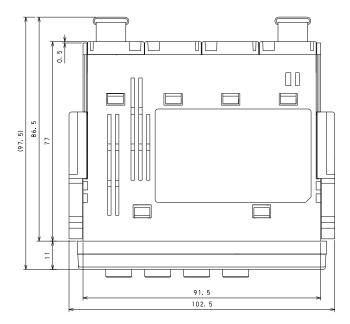
6.2 General Specifications

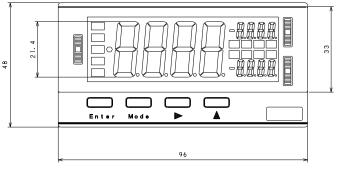
| | • |
|--|--|
| Display | : Multi display Main display: Red/green 7-segment display (character height: approx. 20 mm) Sub display: Red 7-segment display (character height: approx. 6 mm) Single display Red/green 7-segment display (character height: approx. 20 mm) |
| Display range Operational temperature Storage temperature | : -9999 to 9999 ∶ 0 to 50°C 35 to 85%RH ∶ -10 to 70 °C; 60%RH or less |
| Power supply | : AC PS AC 100 to 240V±10% DC PS DC 12 to 48V±10% |
| Power consumption | : AC PS Maximum load: Approx. 8 VA at 100 VAC DC PS Maximum load: Approx. 7 W at 24 VDC |
| External dimension | : 48 mm (H) x 96 mm (W) x 97.5 mm (with no DX option unit mounted) |
| Weight | : Approx. 450g |
| Withstand voltage | : AC PS PS-input, output: 1,500 VAC, 1 minute (AC PS) Input-output: 500 VDC, 1 minute Output-output: 500 VDC, 1 minute Case-PS, input, output: 1,500 VAC, 1 minute DC PS PS-input, output: 500 VDC, 1 minute (DC PS) Input-output: 500 VDC, 1 minute Output-output: 500 VDC, 1 minute Case-PS, input, output: 1,500 VAC, 1 minute |
| Insulation resistance | : AC PS Among the above terminals: 500 VDC 100 M Ω or more DC PS Among the above terminals: 500 VDC 100 M Ω or more |

Caution

The PS voltage must be applied or shut down at once (not gradually). Take at least a 10-second interval between a shutdown and startup.

6.3 External Dimensions





7 Warranty and Service

7.1 Warranty

The manufacturer warrants to the original retail customer its A6000 series universal digital panel meter to be free of defects in material and workmanship for use under normal care and will repair or replace any meter at no charge to the customer during the one (1) year warranty period of the meter.

7.2 After Sales Service

Under strict quality control measures, this product was manufactured, tested, inspected and shipped. Should a defect in manufacture or workmanship be identified, please return the product to our distributor or directly to us. It would be highly appreciated if you could give a detailed account of the fault and enclose it with the product.

watanabe

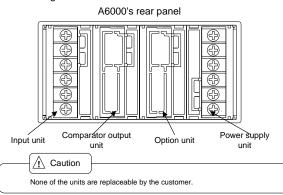
WATANABE ELECTRIC INDUSTRY CO., LTD.

Instruction Manual for A6000 Series Universal Digital Panel Meters

External Control Unit

1 Before Using the Unit

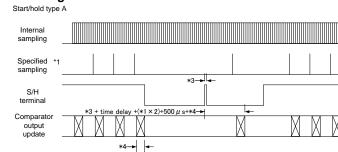
This instruction manual is for the external control unit of the A6000 series. Read this manual along with the main unit's instruction manual before using the unit.



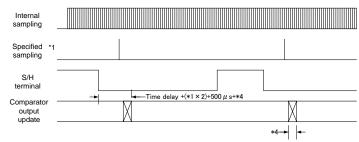
2 Terminals and Connections

| | Top ① ① ① ② ② PH ③ ③ DZ ③ DZ ④ ④ ③ DZ ④ ④ RESET ⑤ ⑤ ⑤ P.SEL1 ⑦ P.SEL2 ⑤ ⑥ ⑧ NC ⑨ ⑨ ⑨ ⑧ NC ⑨ ⑨ NC ⑨ ℕ Bottom ● <td< th=""></td<> |
|----------------------------|---|
| Terminal | Function |
| S/H | "Start/hold" control terminal. The "hold" state is turned on when this terminal is at the same potential as the COM terminal or short-circuited. |
| PH | "Peak hold" control terminal. The peak hold function is turned on when this terminal is at the same potential as the COM terminal or short-circuited. |
| DZ | *Digital zero* control terminal. The digital zero function is turned on when this terminal is at the same potential as the COM terminal or short-circuited. This setting is valid only when the external control terminal is selected as the control method for digital zero using condition data. |
| R.RESET | "Relay reset control terminal. The relay reset function is turned on (only for the meter relay) when this terminal is at the same potential as the COM terminal or short-circuited. |
| P.SEL0 P.SEL1 P.SEL2 | *Pattern selection* control terminals. Patterns can be selected by setting these terminals at the same potential as the COM terminal or short-circuiting them as shown in the table below. These settings are valid only when the external control terminal is selected as the control method for pattern selection using condition data. |
| COM | External control's common terminals, which are at the same potential as the LO or AG terminal for the input circuit. |

3 Timing Charts



Start/hold type B



*1 Specified sampling

The sampling speed is determined by the AVG parameter setting of condition data as shown in the table below

| AVG setting | Sampling speed | Sampling cycle | AVG setting | Sampling speed | Sampling cycle |
|----------------|---------------------|-----------------|----------------|---------------------------|------------------|
| 1 | 1041.65 times/sec | Approx. 960 µs | 100 | 10.4165 times/sec | Approx. 96 ms |
| 2 | 520.825 times/sec | Approx. 1.92 ms | 200 | 5.20825 times/sec | Approx. 192 ms |
| 4 | 260.4125 times/sec | Approx. 3.84 ms | 400 | 2.604125 times/sec | Approx. 384 ms |
| 8 | 130.20625 times/sec | Approx. 7.68 ms | 800 | 1.3020625 times/sec | Approx. 768 ms |
| 10 | 104.165 times/sec | Approx. 9.6 ms | 1000 | 1.04165 times/sec | Approx. 960 ms |
| 20 | 52.0825 times/sec | Approx. 19.2 ms | 2000 | 0.520825 times/sec | Approx. 1.92 sec |
| 50 | 20.833 times/sec | Approx. 48 ms | 5000 | 0.20833 times/sec | Approx. 4.8 sec |
| XI laing a to | | | a appendie he | olf of the velue in the t | |

XUsing a temperature measuring unit, the sampling speed is half of the value in the table above when the RTD is selected and quarter of it when the TC is selected.

%It is different, and a frequency measurement unit is indication update time with a range. Please refer to input specifications (Clause 6.1) of an instruction manual for frequency measurement.

- Please refer to input specifications (Clause 6.1) of an instruction manual for frequency measurement. *3 External start signal The width of the external start signal must be from between 500 µs to a specified sampling cycle. A time
- delay can be set for the external start signal must be from between 500 µs to a specified sampling cycle. A tir delay can be set for the external start using the S/H delay time parameter of the condition data.
- *4 Time delay for comparator output

Relay output: 10 ms max., photocoupler output: 200 μs max.

4 Specifications and External Dimensions

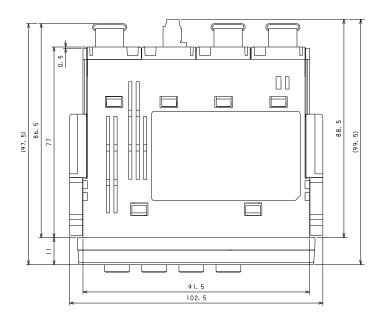
External control terminal

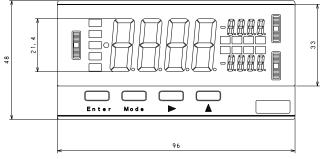
Internal circuit: Pulled up to approximately +5 V (through a 10 $k\Omega$ resistor).

Control signal's HI level: 4.2 to 5 V relative to the COM terminal

Control signal's LO level: 0 to 0.4 V relative to the COM terminal







5 Warranty and Service

5.1 Warranty

The manufacturer grants a warranty to the original retail customer stating that its A6000 series universal digital panel meter is free of defects in material and workmanship for use under normal care, and will repair or replace the meter at no charge to the customer during the one (1) year warranty period.

5.2 After Sales Service

This product was manufactured, tested, inspected and shipped under strict quality control measures. Should a defect in manufacture or workmanship be identified, please return the product to our distributor or directly to us. It would be highly appreciated if you could give a detailed account of the problem and enclose it with the product.

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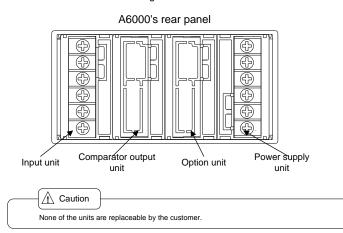
WATANABE ELECTRIC INDUSTRY CO., LTD.

Instruction Manual for A6000 Series Universal Digital Panel Meters

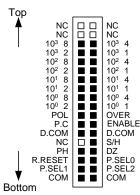
BCD Output and External Control Unit

1 Before Using the Unit

This instruction manual is for the BCD output and external control unit of the A6000 series. Read this manual along with the main unit's instruction manual before using the unit.

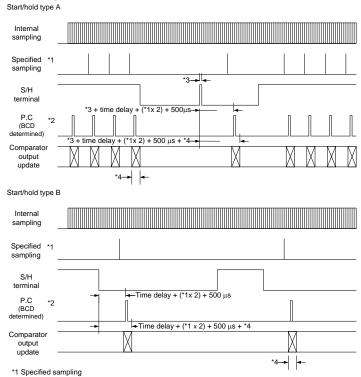


2 Terminals and Connections



Suitable connector (receptacle): KEL Corporation's 8822E-035-171-F

| Terminal | Function | | | | | | |
|----------------------------|---|--|--|--|--|--|--|
| 10º1 | Least significant bit output of least significant BCD digit. The output logic can be switched using condition data. | | | | | | |
| 10º2 | Second least significant bit output of least significant BCD digit. The output logic can be switched using condition data. | | | | | | |
| 10º4 | Second most significant bit output of least significant BCD digit. The output logic can be switched using condition data. | | | | | | |
| 10º8 | Most significant bit output of least significant BCD digit. The output logic can be switched using condition data. | | | | | | |
| : | | | | | | | |
| 10 ³ 1 | Least significant bit output of most significant BCD digit. The output logic can be switched using condition data. | | | | | | |
| 10 ³ 2 | Second least significant bit output of most significant BCD digit. The output logic can be switched using condition data. | | | | | | |
| 10 ³ 4 | Second most significant bit output of most significant BCD digit. The output logic can be switched using condition data. | | | | | | |
| 10 ³ 8 | Most significant bit output of most significant BCD digit. The output logic can be switched using condition data. | | | | | | |
| POL | BCD polarity output. The output logic can be switched using condition data. | | | | | | |
| OVER | BCD overflow output. The output logic can be switched using condition data. | | | | | | |
| P.C | BCD print instruction output. | | | | | | |
| ENABLE | "Enable BCD' control terminal. The BCD output is set to the high-impedance state or the transistor is turned off when this terminal is short-circuited or at the same potential as the D.COM terminal. | | | | | | |
| D.COM | BCD output• fs common terminals | | | | | | |
| S/H | "Start/hold" control terminal. The "hold" state is turned on when this terminal is at the same potential as the COM terminal or short-circuited. | | | | | | |
| PH | "Peak hold" control terminal. The peak hold function is turned on when this terminal is at the same potential as the COM terminal or short-circuited. | | | | | | |
| DZ | *Digital zero* control terminal. The digital zero function is turned on when this terminal is at the same potential as the COM terminal or short-circuited. This setting is valid only when the external control terminal is selected as the control method for digital zero using condition data. | | | | | | |
| R.RESET | *Relay reset control terminal. The relay reset function is turned on (only for the meter relay) when this terminal is at the same potential as the COM terminal or short-circuited. | | | | | | |
| P.SEL0 P.SEL1 P.SEL2 | Pattern selection* control terminals. Patterns can be selected by setting these terminals at the same potential as the COM terminals of short-circuiting them as shown in the table below. These settings are valid only when the external control terminal is selected as the control method for pattern selection using condition data. Pattern 2 Pattern 3 Pattern 4 Pattern 5 Pattern 7 Pattern 5 Pattern 4 Pattern 5 Pattern 7 Pattern 8 Pattern 5 Pattern 7 Pattern 8 Pattern 4 Pattern 5 Pattern 7 Pattern 5 Pattern | | | | | | |
| COM | External control's common terminals, which are at the same potential as the LO or AG terminal for the input circuit. | | | | | | |



3 Timing Charts

| The sampling | speed is determined | by the AVG parameter | eter setting of | condition data as show | n in the table below: |
|----------------|---------------------|----------------------|-----------------|------------------------|-----------------------|
| AVG setting | Sampling speed | Sampling cycle | AVG setting | Sampling speed | Sampling cycle |
| 1 | 1041.65 times/sec | Approx. 960 µs | 100 | 10.4165 times/sec | Approx. 96 ms |
| 2 | 520.825 times/sec | Approx. 1.92 ms | 200 | 5.20825 times/sec | Approx. 192 ms |
| 4 | 260.4125 times/sec | Approx. 3.84 ms | 400 | 2.604125 times/sec | Approx. 384 ms |
| 8 | 130.20625 times/sec | Approx. 7.68 ms | 800 | 1.3020625 times/sec | Approx. 768 ms |
| 10 | 104.165 times/sec | Approx. 9.6 ms | 1000 | 1.04165 times/sec | Approx. 960 ms |
| 20 | 52.0825 times/sec | Approx. 19.2 ms | 2000 | 0.520825 times/sec | Approx. 1.92 sec |
| 50 | 20.833 times/sec | Approx. 48 ms | 5000 | 0.20833 times/sec | Approx. 4.8 sec |

*Using a temperature measuring unit, the sampling speed is half of the value in the table above when the RTD is selected and quarter of it when the TC is selected. %It is different, and a frequency measurement unit is indication update time with a range.

Please refer to input specifications (Clause 6.1) of an instruction manual for frequency measurement

*2 P.C output signal width

The output signal width is determined by the specified sampling setting as shown in the table below:

| AVG | P.C | AVG | P.C |
|------------|----------------------|------------------|-----------------|
| setting | output width | setting | output width |
| 1 | Approx. 220 µs | 100 | |
| 2 | Approx. 0.25 ms | 200 | |
| 4 | Approx. 1.15 ms | 400 | |
| 8 | Approx. 2.3 ms | 800 | Approx. 30 ms |
| 10 | Approx. 2.9 ms | 1000 | |
| 20 | Approx. 5.8 ms | 2000 | |
| 50 | Approx. 14.4 ms | 5000 | |
| The output | width is always 30 m | ns for the frequ | Jency measureme |

*3 External start signal

The width of the external start signal must be from between 500 µs to a specified sampling cycle. A time delay can be set for the external start using the S/H delay time parameter of the condition data *4 Time delay for comparator output

Relay output: 10 ms max., photocoupler output: 200 µs max.

4 Specifications and External Dimensions

BCD output

| Output type | : | open collector or TTL-compatible |
|---------------|------|---|
| Polarity | : | The applicable transistor (open collector) or polarity bit (TTL) turns on when |
| | | negative values are indicated. |
| Overflow | : | The applicable transistor (open collector) or bit (TTL) turns on when the overflow |
| | | state is indicated. |
| Output logic | : | Can be switched alternatively (the logic for the P.C bit cannot be changed). |
| Output rating | : | 30 V DC and 10 mA (open collector), or fan-out 2 (TTL) |
| Cau | | |
| data, whic | ch i | tput logic can be switched using the BCD logic parameter (BCD.L) of the condition s positive when BCD.L is set to P.LOG and negative when BCD.L is set to N.LOG type of Open collector. This logic is reversed if the output type is "TTL." |
| ●External cor | ntro | ol terminal |

Internal circuit: Pulled up to approximately +5 V (through a 10 kΩ resistor).

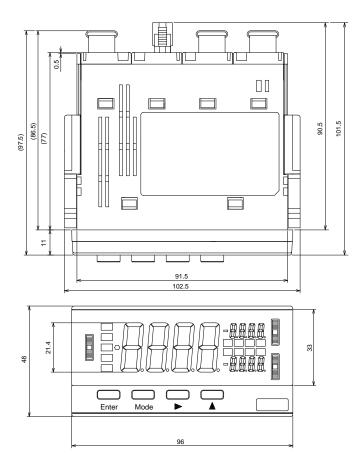
Control signal's HI level: 4.2 to 5 V relative to the COM terminal

Control signal's LO level: 0 to 0.4 V relative to the COM terminal

A Caution

The BCD output circuit and the external control circuit are electrically isolated from each other (withstand voltage: 500 V DC for one minute). The external control circuit's COM terminals and the input circuit's LO or AG terminal are

- set at the same DC potential.



5 Warranty and Service

5.1 Warranty

The manufacturer grants a warranty to the original retail customer stating that its A6000 series universal digital panel meter is free of defects in material and workmanship for use under normal care, and will repair or replace the meter at no charge to the customer during the one (1) year warranty period.

5.2 After Sales Service

This product was manufactured, tested, inspected and shipped under strict quality control measures. Should a defect in manufacture or workmanship be identified, please return the product to our distributor or directly to us. It would be highly appreciated if you could give a detailed account of the problem and enclose it with the product.



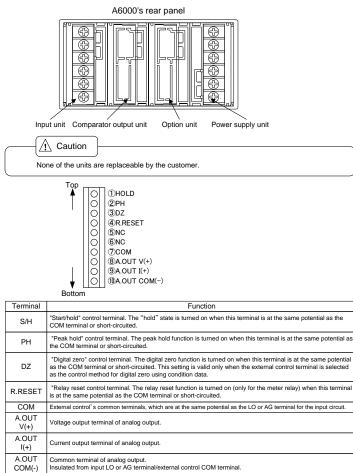
Instruction Manual for A6000 Series Universal Digital Panel Meters

Analog Output and External Control Unit

1 Before Using the Unit

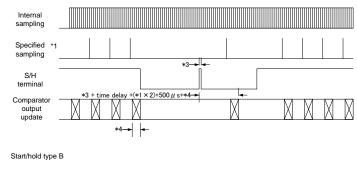
This instruction manual is for the analog output and external control unit of the A6000 series. Read this manual along with the main unit's instruction manual before using the unit.

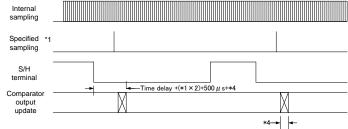
2 **Terminals and Connections**



3 Timing Charts

Start/hold type A





*1 Specified sampling

The sampling speed is determined by the AVG parameter setting of condition data as shown in the table below

| AVG setting | Sampling speed | Sampling cycle | AVG setting | Sampling speed | Sampling cycle |
|----------------|---------------------|--------------------|----------------|---------------------------|------------------|
| 1 | 1041.65 times/sec | Approx. 960 µs | 100 | 10.4165 times/sec | Approx. 96 ms |
| 2 | 520.825 times/sec | Approx. 1.92 ms | 200 | 5.20825 times/sec | Approx. 192 ms |
| 4 | 260.4125 times/sec | Approx. 3.84 ms | 400 | 2.604125 times/sec | Approx. 384 ms |
| 8 | 130.20625 times/sec | Approx. 7.68 ms | 800 | 1.3020625 times/sec | Approx. 768 ms |
| 10 | 104.165 times/sec | Approx. 9.6 ms | 1000 | 1.04165 times/sec | Approx. 960 ms |
| 20 | 52.0825 times/sec | Approx. 19.2 ms | 2000 | 0.520825 times/sec | Approx. 1.92 sec |
| 50 | 20.833 times/sec | Approx. 48 ms | 5000 | 0.20833 times/sec | Approx. 4.8 sec |
| VI laina a ta | monoratura magauria | a unit the complin | a anaad ia hu | Slf of the velue in the t | |

%Using a temperature measuring unit, the sampling speed is half of the value in the table above when the RTD is selected and quarter of it when the TC is selected.

%It is different, and a frequency measurement unit is indication update time with a range. Please refer to input specifications (Clause 6.1) of an instruction manual for frequency measurement. *3 External start signal

The width of the external start signal must be from between 500 µs to a specified sampling cycle. A time delay can be set for the external start using the S/H delay time parameter of the condition data

*4 Time delay for alarm output

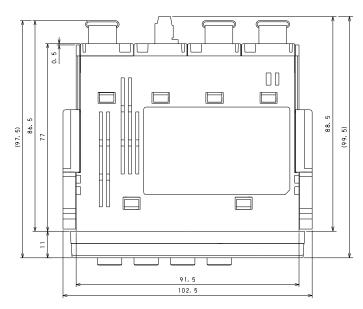
Relay output: 10 ms max., photocoupler output: 200 µs max.

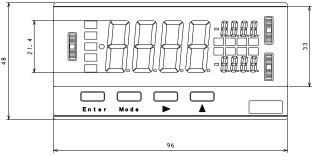
4 Specifications and External Dimensions

Analog output (PWM)

| Output type | Load resistance | Accuracy | Response speed | Ripple |
|--|------------------|---|------------------------------------|---------|
| 0 to 1V | | | | |
| 0 to 10V | 10kΩ or more | 1 (0 50(-1 50) | A | 50mVp-p |
| 1 to 5V | | ±(0.5% of FS) | Approx. 0.5 second | |
| 4 to 20mA | 550Ω or less | | | 25mVp-p |
| Conversion system | n : PWM conve | sion | | |
| Resolution | : Equivalent to | 14 bits | | |
| Scaling | : Digital scalin | g | | |
| External control te Internal circuit Control signal's H level | : Pulled up 1 | o approximately +5V (elative to the COM ter | through a 10kΩ resistor). minal | |

(1) Ana one minute) (2) COM terminals of external control circuits and LO terminals of input circuits have the same electric potential at direct current.





5 Warranty and Service

5.1 Warranty

The manufacturer grants a warranty to the original retail customer stating that its A6000 series universal digital panel meter is free of defects in material and workmanship for use under normal care, and will repair or replace the meter at no charge to the customer during the one (1) year warranty period.

5.2 After Sales Service

This product was manufactured, tested, inspected and shipped under strict quality control measures. Should a defect in manufacture or workmanship be identified, please return the product to our distributor or directly to us. It would be highly appreciated if you could give a detailed account of the problem and enclose it with the product.

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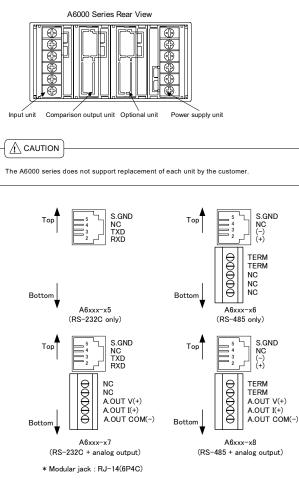
Instruction Manual for A6000 Series Universal Digital Panel Meter

~RS-232C/RS-485 and Analog Output Units~

1 Before Using the Unit

This Operation Manual corresponds to the communication function + analog output optional units of the A6000 Series Universal Digital Panel Meters. When using the instrument, please read through this manual in combination with the Operation Manual of the main unit.

2 Terminals and Connections

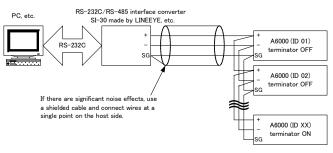


3 Examples of Connections and Use

3.1 Connecting the RS-232C Interface

| A6000 series modular jack | D-sub 25-pin connector of PC, etc. | A6000 series modular jack | D-sub 9-pin connector of PC, etc. |
|------------------------------|---------------------------------------|------------------------------|--------------------------------------|
| RXD 🔫 | ► RXD (2) | RXD 🚽 | ► RXD (2) |
| TXD 🚽 | ► TXD (3) | TXD 🚽 | ► TXD (3) |
| SG 👞 | ► RTS (4) | SG 👞 | ► RTS (7) |
| | CTS (5) | | CTS (8) |
| | SG (7) | | SG (5) |

3.2 Connecting the RS-485 Interface



*If cascade wiring is carried out with a RS-485 connection, use a commercially available Y-type split connector or the like. *To turn ON an RS-485 I/O unit's terminator (200 Q), short-circuit the two TERM terminals.

3.3 Control Codes Used in RS-485 Interface

| | | - |
|------|-------------|---------------------|
| Code | Hexadecimal | Name |
| STX | 02H | Start of Text |
| ETX | 03H | End of Text |
| EOT | 04H | End of Transmission |
| ENQ | 05H | Enquiry |
| ACK | 06H | Acknowledge |

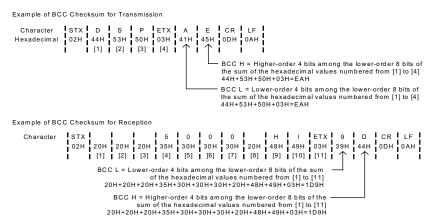
3.4 Establishing RS-485 Communication

| Function | 1 2 | 3 | 4 | 5 | 6 | 7 | Char. Length | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | Char. Length |
|----------------------------|--|---------------------------|------------------------|----------|------|------|--------------|----------|----|---------|------|-----------------------|----------|---|---|---|----|--------------|
| Establishing | ENQ 0 | | CR | | | | 3 | ACK | 0 | 1 | Q | R LF | | | | | | 3 |
| communication | *Device | D | is s | pecif | fied | l in | | • | | | | onse | <i>'</i> | | | | } | |
| | 2 digits | (00 |) is i | nvali | d). | | | | re | spo | | me: is n | | | | | | is |
| Canceling communication | EOT CR *If anot specific canceli commu commu possibl | her ed w ng inic | devi vitho atior | ut n, | | | 1 | , con | nm | unic | atio | e is n on.) me: | | | | | | of |

3.5 RS-485 Communication formats

As a means of error detection, a block check character (BCC) checksum is added to the RS-485 communication function of the A6000. See the following illustrations for details on the transmission and reception formats.

(RS-232C communication format is same as the command table which is mentioned in the next section.)



4 Communication Commands

| Function | 1 1 | 2 | { 3 | } 4 | 5 | 6 | 7 8 | 3 9 | 10 11 | 12 | 13 14 | 15 | Char. Le | Length 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 Char. Ler |
|---|----------------|-------|----------|----------|-----|----------------|-------|----------|-----------|---------|-------|----|----------|--|
| Measured value and comparison result responses | | | | CR | | | | | | | | | 3 | 3 5 0 0 0 H I CR LF 10 ("+" indication without decimal point) |
| lesponses | | | | | | | | | | | | | | - 5 0 0 0 H I CR LF 10 |
| | | | | | | | | | | | | | | ("+" indication without decimal point) 5 0 0 . 0 H I CR LF 11 |
| | | | | | | | | | | | | | | ("+" indication with a decimal point) |
| | | | | | | | | | | | | | | < = 9 8 0 0 0 H I CR LF 10 ("+" side excess indication without decimal point) |
| | | | | | | | | | | | | | | < =] - { 9 8 0 . 0 H I CR LF 11 ("-" side excess indication with a decimal point) |
| | | | | | | | | | | | | | | P H 5 0 0 0 H I CR LF 10 |
| | | | | | | | | | | | | | | (Peak hold indication without decimal point) 5 0 0 0 A L 1 CR LF 11 |
| | | | | | | | | | | | | | | ("+" indication without decim al point) |
| | | | 1 | | | | | | | | | | | ("-" indication without decimal point) |
| | | | | | | | | | | | | | | ("+" indication with a decimal point) |
| | | Ļ | | 1 | | | | 1 | | | | | | |
| Measured value response A measurement condition such as peak | M | E | S | CR | LF | | | | | | | | 3 | 3 0 CR LF 12 ("0" indication without decimal point) |
| hold, etc. or compression decision is not responded. | | | | | | | | | | | | | | ("0.01" indication with a decimal point) CR LF 12 |
| is notresponded. | | | | | | | | | | | | | | - 1 CR LF 12 |
| | | | | | | | | | | | | | | ("-1" indication without decimal point) |
| | | | | | | | | 1 | | | | | | ("-0.005" indication with a decimal point) |
| | | | 1 | | | | | 1 | | | | | | (Excess indication with a decimal point) |
| | | | | | | | | | | | | | | <pre>< = - 9 8 0 . 5 CR LF 12 ("-" side excess indication with a decimal point)</pre> |
| | | | | | | | | | | | | | | * All responses have a fixed length of 12 characters. |
| Judgment result response | J | G | M | CR | LF | | + | + | ++ | + | + | - | 3 | |
| * A measurement condition is not responded. | | | | | | | | | | | | | | (Response of a state in which the judgment result is HI) G O G O |
| | | | 1 | | | | | 1 | | | | | | (Response of a state in which the judgment result is GO) |
| | | | | | | | | | | | | | | L O CR LF 15 (Response of a state in which the judgment result is LO) In the state in which the judgment result is LO) In the state in which the judgment result is LO) |
| | | | | | | | | | | | | | | O F F I |
| | | | | | | | | | | | | | | N O ? CR LF 5 |
| | | | | | | | | | | | | | | (Response made if the relevant optional unit is not installed) * All responses have a fixed length of 15 characters with the |
| Unit num ber response | $\frac{1}{10}$ | N | } | CR | 1.5 | | _ | | \square | | _ | - | 3 | exception of an error. 4 6 CR LF 11 3 1 1 2 1 N O 4 6 CR LF 11 |
| | ľ | | 1 | | | | | | | | | | | (Response is made in the order of the display unit number, input |
| | | | | | | | | | | | | | | unit number, comparison output unit number, and optional unit If the unit concerned is not installed, "NO" is returned.) |
| Response of the maximum value, | м | | | CR | 1 5 | | _ | <u> </u> | | | _ | Ļ | 3 | 3 M A X 5 0 0 . 0 CR LF 1 1 10 |
| minimum value, or maximum and | | | Î | | | | | | | | | | Ū | (Response of maximum value) |
| minimum values | | | | | | | | | | | | | | M I N - 1 0 0 . 0 CR LF 10 (Response of minimum value) 0 CR LF 10 |
| | | | | 1 | | | | 1 | | | | | | M - M 6 0 0 1 0 CR LF 10 (Response of maximum and minimum values) |
| | | | | | | | | | | | | | | * These values are simultaneously responded by dividing them with a delimiter. |
| Clear of the maximum value, | | | | | | A | | | | | | | 6 | |
| minimum value, or maximum and minimum values | | | | | | ım va I∣C | | | | | | | 6 | 6 Y E S CR LF 5 |
| | | | | | | m va M∣C | | | | | | | 6 | 6 Y E S CR LF 5 |
| | | | | | | | | | um valu | ies.) | | | | |
| Key operation inhibition response | к | E | Y | CR | LF | 1 | | 1 | | | + | + | 3 | |
| | | | | 1 | | | | | | | | | | O N CR LF 2 |
| | | | | 1 | | | | | | | | | | (Response of a state in which the key operation inhibition function is ON) |
| Key operation inhibition setting | | E | | | | F | | | | functio | | | 7 | 7 Y E S CR LF 5 |
| | ĸ | E | Y | 1 | 0 | NC | RLF | 1 | ibition | | | | 6 | 6 Y E S CR LF 5 |
| | (Ac | tivat | test | hek } | eyo | perat | on ir | hibit | ion fun | ction.) | | | | |
| Response of remote-controlled hold | S | Т | н | CR | LF | | | | | | | | 3 | 3 S T A R T CR LF 5 (Response of a state in which hold is deactivated by remote control) |
| | | | | 1 | | | | | | | | | | H O L D CR LF 4 |
| | | | | - | | | | | | | | | | (Response of a state in which hold is activated by remote control) |
| | | | | | | | | - | | | | | | (Response of a state in which hold is not remote controlled) |
| Hold remote control | | T | | | | CR L Id fur | | | | | | | 5 | 5 Y E S CR LF 5 |
| | s | Т | н | 1 | н | CR | F | 1 | | | | | 5 | 5 Y E S CR LF 5 |
| | Ľ | | 1 | } | old | functi | on.) | | | | | | | |
| Trigger input | Т | CR | LF | | | | | | | | | | 1 | 1 5 0 0 . 0 H I CR LF 11 ("+" indication with a decimal point) |
| | | | | | | | | | | | | | | * The response format is the same as the DSP command. |
| Cancellation of hold remote control | E | s | м | CR | LF | | | | | | | | 3 | 3 Y E S CR LF 5 |
| | | 1 | | } | | Ĭ | | 1 | | | 1 | 1 | | |

| Function | 1 | 2 | <u> </u> | - | | <i>.</i> | 7 | 8 | 9 | 10 | 11 | 12 | 13 | 14 | 15 | Char. Length | 1 } | _ | <u> </u> | - | _ | | _ | _ | | _ | <u> </u> | 1 | 10 | 11 | 12 | 1 | 3 | 14 | 15 | 1 | 6 | 17 | 18 | Ch | ar. Lengti |
|---|-----|------------|------------|----------|------|-----------|-----------|-------------|-----|------|----|---------------|----|----|----|--------------|--------------|-----------|-----------|-------------|-----------|---------------|------------|-----|---------|------|------------|----------|------------|------|----------|------|------|------|-------|-----------|-----------|------|----|----|------------|
| Response of remote-controlled peak hold | P | V | Н | CR | LF | | | | | | | | | | | 3 | P (Res | | | | | | | | | | | | is (| 102 | c tiv | ater | d by | / ro | mol | te c | oni | rol | | | 6 |
| peak noid | | | | | | | [| | | | | | | | | | V | | | | | | | | | | | | | | | | | , 16 | | | 1 | 101) | | | 6 |
| | | | | | | | [| | | | | | | | | | (Res P | | | | | | | | | | | holo | alis I | dea | | | ed b | by r | emo | ote | ر نان | ntro | I) | | 6 |
| | | | 1 | | | | | 1 | | | | | | | | | (Res | | | | | | | | | | | y ho | l i bla | e da | acti | vate | ed b | y re | mot | e co | ontr | ol) | | | 0 |
| | | | | | | | | | | | | | | | | | P (Res | Н | - | 0 | N | 1 0 | CR | LF | | | } | | | | | | | | | 1 | | | | | 5 |
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| Peak hold selection setting | | V ets u | | | | H | CR | LF | | | | | | | | 6 | Υ | Е | s | | | 0 | CR | LF | | | | | | | | | | | | | | | | | 5 |
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| Peak hold remote control | | v | | | | N | | | | | | | | | | 6 | Y | - | | | | | CR | | | | 1 | | | | | | | | | | | | | | 5 |
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| | | | | | | | | CR I fun | | | | | | | | 7 | Υ | Е | s | | | 0 | CR | LF | | | | | | | | | | | | | | | | | 5 |
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| Peak-held value response | P | V | D | CR | LF | | [| | | | | | | | | 3 | P (Re | | | | | | 5 | | | | { · | | D | CR | LF | | | | | | | | | | 10 |
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| Clear of peak-held value | | с | ١. | | Þ | н | | I.E. | | | | | | | | 6 | Y | F | ç | | | | CR | | | | { | | | | | | | | | | | | | | 5 |
| | (C) | ears | s'a p | beak | -hel | ld va | lue. | .) | | 1 | | | | | | 0 | | | | | | ſ | 511 | - | | | 1 | | | | | | | | | | | | | | 5 |
| | | C Cars | | | | | | | | | | | | | | 6 | Y | Е | s | | | 0 | CR | LF | | | 1 | | | | | | | | | | | | | | 5 |
| | | C | | | | | | | | | | | | | | 6 | Y | Е | s | | | 0 | CR | LF | | | 1 | | | | | | | | | | | | | | 5 |
| | (CI | ears | pe | ak- | ind | vall | ey-h | ėld | alu | es.) | | | | | | | | | | | | | | | | | } | | | | | | | | | | | | | | |
| Cancellation of peak hold remote control | E | Р | м | CR | LF | | [| | | | | | | | | 3 | Y | Е | s | 1 | | 0 | CR | LF | | | 1 | | | | | | | | | | | | | | 5 |
| Response of remote-controlled | | Z | R | CR | LE | - | <u> </u> | <u> </u> | | | _ | \rightarrow | _ | + | _ | 3 | 0 | F | F | CE | 21 | F | | _ | + | | <u>{</u> | + | | | _ | + | + | | _ | + | - | _ | | + | 3 |
| digital zero | | - | [`` | | - | | | 1 | | | | | | | | Ŭ | (Res | pon | ise | òf a | sta | te i | n w | hio | h | digi | ital: | zer | o is | | | | edi | by r | em | ote | coi | ntro | I) | | |
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| Digital zero remote control | | Z | | | | N | | LF | | | | | | | | 6 | Υ | Е | s | | | 0 | CR | LF | | | | | | | | | | | | | | | | | 5 |
| | | tivat Z | | | | | | CR | LF | | | | | | | 7 | Y | Е | s | | | | CR | LF | | | | | | | | | | | | | | | | | 5 |
| | | acti | | | | | | 0 | CB | | | | | | | 8 | Y | _ | e | | | | CR | | | | 1 | | | | | | | | | | | | | | 5 |
| | | | | | | | | 0 00.) | | | | | | | | 0 | 1 | | 3 | | | ľ | - | LI | | | 1 | | | | | | | | | | | | | | 5 |
| Cancellation of digital zero remote | | z | Е м | | | | | 1 | | | | | | | | 3 | Y | F | 6 | | | | CR | | | | | | | | | | | | | | | | | | 5 |
| control | 1 | |] | | | | [| | | | | | | | | Ū | · | - | Ŭ | | | ſ | 511 | - | | | 1 | | | | | | | | | | | | | | Ū |
| Response of remote-controlled | R | E | s | CR | LF | 1 | } | { | | | _ | _ | _ | + | _ | 3 | 0 | F | F | C | RIL | FI | | _ | + | | 1 | + | | | - | + | _ | | _ | 1 | | _ | | ╋ | 3 |
| relay reset | | [|] | | - | } | [| | | | | | | | | - | (Res | pon | ise | of a | ista | | | | | rela | | | etis | de | acti | ivat | | | rem | ote | ç | ntro |) | | |
| | | | | | | 1 | | 1 | | | | | | | | | O (Res | | | | | te i | n w | hi | ¦ h: | rela | avr | ese |) etis | ac | tiva | ted | bv | | note | } • co | { ontr | ol) | | | 2 |
| | | | | | | 1 | | 1 | | | | | | | | | `L } | 0 | С | C | RL | F | | | | | Í. | 1 | | | | | | | | 1 | ł | | | | 3 |
| | | 1 | | 1 | | | | | | | | | | | | | (Re | spo | ns | e of | ras | tat | e II | 1 1 | ni/ | ch | rel | ay | res | eti | is r | ioti | ren | not | ec | ont } | ro ا { | ıed | | | |
| Relay reset remote control | | E | | | | | | LF | | | | | | | | 6 | Y | Е | s | | | • | CR | LI | = | | | ł | | | | | | | | | | | | | 5 |
| | R | | s | 1 | 0 | F | ξF. | CR | LF | | | | | | | 7 | Y | Е | s | | | | CR | LI | - | | | | | | | | | | | 1 | | | | | 5 |
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| Cancellation of relay reset remote control | | acti R | { | 1 | | 1 | 1 | | | | | | | | | 3 | Y | Е | s | | | | CR | LI | - | | | | | | | | | | | | | | | | 5 |

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|--|--|---------|----------|----------|-----------|------|---------|-----------|-------|--------|-----------|--------|-------|--------------|-------|--------------|--------------|---|
| $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | Response of remote-controlled comparison output | | | - | Y | CR | LF | | | | | | | | | | 3 | O F F CR LF 3 (Response of a state in w hich all outputs are turned OFF by remote control) |
| $ \left \begin{array}{c c c c c c } & c c c c & c c c c & c c c c c & c c c c$ | • • • • • • | | | | | | | | | | | | | | | | | H I CR LF 2 |
| $ \left \begin{array}{c c c c c c c c c c c c c c c c c c c $ | | | | | | | | | | | | | | | | | | |
| $ \begin{array}{c c c c c c c c c c c c c c c c c c c $ | | | | | | | | | | 1 | | | | | | | | (Response of a state in which GO is turned ON by remote control) |
| $ \left \begin{array}{c c c c c c c c c } & \begin{array}{c c c c c c c c } & \begin{array}{c c c c c c c c c c c c c c c c c c c $ | | | | | | | | | | | | | | | | | | |
| $ \left \begin{array}{c c c c c c c c c c c c c c c c c c c $ | | | | | | | | | | | | | | | | | | * If multiple outputs are ON, response is made in the above order. |
| $ \begin{aligned} & $ | | | | | | | | | | 1 | | | | | | | | |
| Comparison output remote control n I | | | | | | | | | | | | | | | | | | N 0 ? CR LF 5 |
| $ \left \begin{array}{c c c c c c c c c c c c c c c c c c c $ | | | | | | | | | | | | | | | | | | (Response made if the relevant optional unit is not installed) |
| $\left \begin{array}{c c c c c c c c c c c c c c c c c c c $ | Comparison output remote control | R | 2 | L | Y | | н | 1 | CR | LF | | | | | | | 6 | Y E S CR LF 5 |
| | | | | | | | | | 0.0 | [| | | | | | | | Y E S CR LE 5 |
| $\left \left(\begin{array}{c} \left(\begin{array}{c} \left(\begin{array}{c} \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \right) \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \\ \left(1 \right) \right) \\ \left(1 \\ \left(1 \right$ | | | | | | | | ľ | UN | | | | | | | | | |
| R I L V J O F F ROLET 7 Y E S 0 0 F 0 0 F 0 0 0 F 0 0 0 F 0 | | | | | | | | 0 | CR | LF | | | | | | | 6 | Y E S CR LF 5 |
| $ \left \begin{array}{c c c c c c c c c c c c c c c c c c c $ | | | urn t | L { | Y I | _0.) | 0 | F | F | CR | LF | | | | | | 7 | Y E S CR LF 5 |
| Cancellation of comparison of use mode and produced with the number of averaging times and of the number of moving in the setter mode control is an interval of the number of moving interval interval of the number of moving interval interval of the number of moving interval inte | | (Т | urn | ıs C | ۶FF | all | con | par | ison | outp | uts. |) | | | | | | |
| Cancellation of comparison output rem do is control R C H CF L I CF CF <td></td> | | | | | | | | | | | | | | | | | | |
| autiparterm oble controll P S L CR F S CR F S L CR F S CR F S </td <td></td> | | | | | | | | | | | | | | | | | | |
| autiparterm oble controll P S L CR F S CR F S L CR F S CR F S </td <td>Cancellation of comparison</td> <td></td> <td></td> <td></td> <td>м</td> <td>CR</td> <td>LE</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td>3</td> <td>Y E S CR LF 5</td> | Cancellation of comparison | | | | м | CR | LE | | | | | | | | | | 3 | Y E S CR LF 5 |
| Response of remote-controlled pattern select P S L OR LP S LP | | `` | | Ĭ | | 0.1 | | | | | | | | | | | Ŭ | |
| Response of remote-controlled patient select P S L CR CR CR L CR CR CR L CR CR CR L CR CR< | | | | | | | | | | | | | | | | | | |
| patem select P S L 1 1 CR LF (Get Select explorements) CR L F L CR LF (L F L CR LF (Get Spate Finite explorements)) CR L F L CR LF (Get Spate Finite explorements) Patem selectremote control P S L 1 1 CR LF (Get Spate Finite explorements)) S CR LF L CR LF (Get Spate Finite explorements)) S CR LF L CR LF (Get Spate Finite explorements)) Cancellation of patem select P S M CR LF S M CR LF S M CR LF (Get Spate Finite explorements)) S CR LF (Get Spate Finite explorements)) Remote control response R S A CR LF S M CR LF S M CR LF (Get Spate Finite explorements)) S R (Get LF (Get Spate Finite explorements)) Remote control response R S A CR LF S M CR LF S M CR LF (Get Spate Finite explorements)) S R (Get LF (Get Spate Finite explorements)) Response control response R S A CR LF (Get Spate Finite explorements)) S R (Get Finite explorements)) S R (Get Finite explorements)) Collective cancellation of remote control (Get Spate Finite explorements)) S R (Get Finite explorements)) S R (Get Finite explorements)) S R (Get Finite explorements)) Satting of the number of available which the control (Get Spate Finite explorements)) S R (Get Finite explorements)) S R (Get Finite explorements)) S R (Get Finite explorements)) Satting of the number of moving averaging times to 'S (Get Finie explorements)) S (Get Finite exploreme | | | | | | | | | | | | | | | | | | |
| Pattern selectremole control P S L 1 OR LF Pattern selectremole control P S L 1 OR LF Cancellation of pattern select P S M CR F A CR F CR F CR CR F CR CR F CR CR F CR CR <td< td=""><td></td><td>P</td><td>1</td><td>s</td><td>L</td><td>CR</td><td>LF</td><td></td><td></td><td>Ì</td><td></td><td></td><td>1</td><td></td><td></td><td></td><td>3</td><td></td></td<> | | P | 1 | s | L | CR | LF | | | Ì | | | 1 | | | | 3 | |
| Pattern select remote control P S L 1 CR LF Pattern select remote control Concellation of pattern select P S M CR F CR LF Concellation of pattern select P S M CR F CR LF Remote control response R E A CR LF S CR LF LF Concellation of pattern select P S M CR F CR LF | pattern select | | | | | | | | | | | | | | | | | |
| Pattern select remote control P is SL is 1 cm iv Step is 0 v Step is a state in witch the pattern select is not remote controlled) Pattern select remote control P is SL is 1 cm v Vich is sen v; '; P is SL is 1 cm v Vich is sen v; '; P is SL is 1 cm v Vich is sen v; '; P is SL is 1 cm v Vich is sen v; '; P is SL is 1 cm v Vich is sen v; '; P is SL is 1 cm v Vich is sen v; '; P is SL is 1 cm v Vich is sen v; '; P is SL is 1 cm v Vich is sen v; '; P is SL is 1 cm v Vich is sen v; '; P is SL is 1 cm v Vich is sen v; '; P is SL is 1 cm v Vich is sen v; '; P is SL is 1 cm v Vich is sen v; '; P is SL is 1 cm v Vich is sen v; '; P is SL is 1 cm v Vich is sen v; '; P is SL is 1 cm v Vich is sen v; '; P is SL is 1 cm v Vich is sen vich is sen v; '; P is SL is 1 cm v Vich is sen vich v; '; P is SL is 1 cm v Vich is sen vich v; '; P is SL is 1 cm v Vich is sen vich v; '; P is SL is 1 cm v Vich is sen vich v; '; P is SL is 1 cm v Vich is sen vich v; '; P is SL is 1 cm v Vich is sen vich v; '; P is SL is 1 cm v Vich is sen vich v; '; P is SL is 1 cm v Vich is sen vich v; '; P is SL is 1 cm v Vich is sen vich v; '; P is SL is 1 cm v Vich is sen vich v; '; P is SL is 1 cm v Vich is sen vich v; '; P is SL is 1 cm v Vich is sen vich v; '; P is SL is 1 cm vich is sen vich v; '; P is SL is 1 cm vich is sen vich v; '; P is SL is 1 cm vich is sen vich v; '; P is SL is 1 cm vich is sen vich v; '; P is SL is 1 cm vich is sen vich v; '; P is SL is 1 cm vich is sen vich v; '; P is SL is 1 cm vich is sen vich v; '; P is SL is 1 cm vich is sen vich v; '; P is SL is 1 cm vich is sen vich v; '; | | | | | | | | | | | | | | | | | | (Response of a state in w hich the pattern used by remote control is "8") |
| Pattern selectrem ote control P S L 1 CR LF Gelse pattern in use to T7, P S L 1 CR LF S CR | | | | | | | | | | | | | | | | | | |
| $ \begin{array}{ c c c c c c c c c c c c c c c c c c c$ | | | | . [| | | | | | | | | | | | | _ | |
| Cancellation of pattern select P S M CR LF Remote control response R F A CR LF Remote control response R F A CR LF Remote control response R F A CR LF Collective cancellation of remote control lesponse R F A CR LF Collective cancellation of remote control lesponse A CR LF Image: CR L Image: CR Collective cancellation of remote control lesponse A V C CR LF Image: CR L Image: CR Collective cancellation of remote control lesponse A V C CR LF Image: CR | Pattern select remote control | | | | | | | | | - { | | | | | | | 5 | Y E S CR LF 5 |
| Cancellation of pattern select remote control P S M CR LF Image: Control of pattern select control of pat | | P | 18 | s } | L { | | 8 | CR | LF | | | | | | | | 5 | Y E S CR LF 5 |
| remote control Remote control response R E A CR F Remote control response R E A CR F Remote control response R E A CR F Remote control response R R R CR CR F R <td></td> <td>(S</td> <td>ets</td> <td>pa</td> <td>tter</td> <td>n in</td> <td>us</td> <td>e to</td> <td>"8.")</td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> <td></td> | | (S | ets | pa | tter | n in | us | e to | "8.") | | | | | | | | | |
| Remote control response R E A CR F CR F CR F Remote control response R E A CR F CR F CR F Remote control response R E A CR F CR F CR F Remote control response R F A CR F | | Р | 1 | s | м | CR | LF | | | | | | | | | | 3 | Y E S CR LF 5 |
| Collective cancellation of remote control L O C </td <td>remote control</td> <td></td> | remote control | | | | | | | | | | | | | | | | | |
| S T H CR LF | Remote control response | R | E | Ε | A | CR | LF | | | 1 | | + | 1 | \mathbf{H} | | | 3 | |
| Collective cancellation of remote controlled, L 0 C CR LF Image: Controlled of the con | | | | | | | | | | | | | | | | | | |
| Collective cancellation of remote control L O C </td <td></td> | | | | | | | | | | | | | | | | | | |
| Collective cancellation of remote control L O C CR LF Image: Control of the relay rest function is remote controled) Collective cancellation of remote control L O C CR LF Image: Control of the relay rest function is remote controled) Collective cancellation of remote control L O C CR LF Image: Control of the relay rest function is remote controled) Response of the number of averaging times A V G CR LF Image: Control of the relay rest function is remote controled) Setting of the number of averaging times A V G CR LF Image: Control of the relay rest function is remote controled) Response of the number of averaging times S 1 CR CR LF Image: Control of the number of averaging times is "1") Setting of the number of averaging times to "1.0" A V G CR LF Image: Control of the number of averaging times is "1") Setting of the number of moving averaging times to "1.0" A V G CR LF Image: Control of the number of averaging times is "1") Setting of the number of moving averaging times to "1.0" A | | | | | | | | | | | | | | | | | | |
| Collective cancellation of remote control L O C CR LF Section of remote control L O C CR LF Section of remote control L V C CR LF Section of remote control L V C CR LF Section of remote control L V C CR LF Section of remote control L V C CR LF Section of remote control L V C CR LF Section of remote control Response of a state in which the pattern select function is remote controlled) P Section of a state in which the pattern select function is remote controlled) Section of a state in which the number of averaging time s is remote controlled) Section of a state in which the number of averaging time s is remote controlled) Section of a state in which the number of averaging time s is remote controlled) Section of a state in which the number of averaging time s is remote controlled) Section of a state in which the number of averaging time s is remote controlled) Section of a state in which the number of averaging time s is remote controlled) Section of a state in which the number of averaging time s is remote controlled) Section of a state in which the number of averaging time s is remote controlled) Section of a state in which the number of averaging time s is remote controlled) | | | | | | | | | | | | | | | | | | |
| Collective cancellation of remote control L O C CR LF Image: Collective cancellation of remote controlled) Response of a state in which the creative reset function is remote controlled) Collective cancellation of remote control L O C CR LF Image: Collective cancellation of remote controlled) Collective cancellation of remote control L O C CR LF Image: Collective cancellation of remote controlled) Collective cancellation of remote control L O C CR LF Image: Collective cancellation of remote controlled) Setting of the number of averaging times A V G 1 CR LF Image: Collective cancellation which the number of averaging times is "1") Setting of the number of averaging times A V G 1 CR LF Image: Collective cancellation which the number of averaging times is "5000") S S Y E S CR LF Image: Collective cancellation which the number of averaging times is set SOO") S Y E S Y E S Y E S Y E S Y E | | | | | | | | | | | | | | | | | | |
| Collective cancellation of remote control L O C CR LF L P S L P S L CR LF Image: CR Image: C | | | | | | | | | | - { | | | | | | | | |
| Collective cancellation of remote control L O C CR LF L O C CR LF L FResponse of a state in which the pattern select function is remote controlled, response is made with data divided by delimiters. Image: Control of the number of averaging times is made with data divided by delimiters. Image: Control of the number of averaging times is made with data divided by delimiters. Image: Control of the number of averaging times is made with data divided by delimiters. Image: Control of the number of averaging times is made with data divided by delimiters. Setting of the number of averaging times A V G CR LF Image: Control of the number of averaging times is made with data divided by delimiters. Image: Control of the number of averaging times is made with data divided by delimiters. Image: Control of the number of averaging times is made with data divided by delimiters. Image: Control of the number of averaging times is made with data divided by delimiters. Setting of the number of averaging times to "1.") A V G I CR LF Image: Control of the number of averaging times is made with data divided by delimiters. Control of the number of averaging times is made with data divided by delimiters. Control of the number of averaging times is made with data divided by delimiters. Control of the number of averaging times is made with data divided by delimiters. Control of the number of averaging times is t | | | | | | | | | | | | | | | | | | R L Y CR LF 3 |
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| Collective cancellation of remote control L O C CR LF Image with data divided by delimiters. Response of the number of averaging times A V G CR LF A CR LF CR CR LF CR CR CR LF CR | | | | | | | | | | | | | | | | | | |
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| averaging times A V G 1 CR LF (Response of a state in which the number of averaging times is "1") Setting of the number of averaging times A V G 1 CR LF (Response of a state in which the number of averaging times is "5000") Setting of the number of averaging times A V G 1 CR LF (Response of a state in which the number of averaging times is "1") A V G 1 CR LF Set the number of averaging times to "1.") A V G Set the number of averaging times to "1.") A V G Set the number of averaging times to "1.") A V CR LF CR LF CR CR F CR LF CR F CR LF CR CR F CR CR CR CR CR< | Collective cancellation of remote contro | I L | . (| 0 | С | CR | LF | | | 1 | | | | | | | 3 | |
| averaging times A V G 1 CR LF (Response of a state in which the number of averaging times is "1") Setting of the number of averaging times A V G 1 CR LF (Response of a state in which the number of averaging times is "500") Setting of the number of averaging times of averaging times to "1") A V G 1 CR LF (Response of a state in which the number of averaging times is "1") Response of the number of averaging times of averaging times to "1") A V G I CR LF N V G I Set in which the number of averaging times is "1") Set in which the number of averaging times is "1") Set in which the number of averaging times is "1") Response of the number of moving averaging times Set in which the number of averaging times is set) Set in which the number of averaging times is set) Response of the number of moving averaging times M A V CR LF Set in which the number of moving averaging times is "1") Setting of the number of moving averaging times to "4".) M A V CR LF Set in which the number of moving averaging times is "1") Setting of the number of | Response of the number of | A | | vł | G | CR | LF | - | | | + | + | + | | - | - | 3 | 1 CR LF 1 |
| Setting of the number of averaging times is "5000") averaging times A V G 1 CR LF 5 Y E S CR LF Image: S S S CR LF Image: S | averaging times | | | | | | | | | | | | | | | | | (Response of a state in which the number of averaging times is "1") |
| Setting of the number of averaging times A V G 1 CR LF A V G 5 V E S CR LF A V G 5 0 0 0 CR LF A V G 5 0 0 0 CR LF A V G 5 0 0 0 CR LF Setting of the number of noving averaging times M A V CR LF B S CR LF Response of the number of moving averaging times M A V CR LF CR CR LF CR CR LF CR CR CR CR CR LF CR | | | | | | | | | | | | | | | | | | |
| averaging times (Sets the number of averaging times to "1.") 8 Y E S CR LF A V G 5 0 0 0 CR LF CR CR LF CR CR LF CR CR CR LF CR CR CR LF CR | | | | | | | | | | | | | | | | | | |
| A V G 5 0 0 0 CR LF Image: CR | | | | | | | | | | in a t | im es | to "1 | ٤, | | | | 5 | Y E S CR LF 5 |
| Response of the number of moving averaging times M A V CR LF Image: CR Image: CR LF Image: CR | | A | 1 | V | G | | 5 | 0 | 0 | 0 {0 | CRL | F | £ | | | | 8 | |
| Response of the number of moving averaging times is set) M A V CR LF Image: CR Image: | | (S | ets | the | e ni | ım b | er | ofav I | erag | ingt | im es | to "5 | 000 | .") | | | | |
| Response of the number of moving averaging times M A V CR LF IF | | | | | 1 | | | | | | | | | | | | | (Response made if an unsettable number of averaging times is set) |
| averaging times | Response of the number of maxim | | | 1 | V | CP | 1.5 | <u> </u> | | | | _ | 1 | | | \downarrow | | |
| Setting of the number of moving averaging timesMAV4CRLFIII< | | ™ | ' ' | ^[| × [| сĸ | LF | | | - | | | | | | | 3 | (Response of a state in which moving averaging is OFF) |
| Setting of the number of moving averaging times M A V 4 CR LF O N = 1 6 CR LF M A V 4 CR LF (Response of a state in which the number of moving averaging times is 16) Setting of the number of moving averaging times to "4".) M A V 1 1 6 CR LF M A V 1 1 6 CR LF Sets the number of moving averaging times to "16".) 6 Y E S CR LF M A V 0 CR LF 5 Y E S CR LF Sets the number of moving averaging times to "16".) K A V 0 CR LF 5 Y E S CR LF M A V 0 CR LF 5 Y E S CR LF Sets the number of moving averaging times to "16".) K K S CR LF M A V 0 CR LF Sets the number of moving averaging times to "16".) K K S CR LF M A V 0 CR LF Sets the number of moving averaging times is the moving averaging times in averaging time averaging times is s witched or moving averaging is deactivated im mediat | - | | | | 1 | | | | | | | 1 | | | | | | O N = 4 CR LF 4 |
| Setting of the number of moving averaging times M A V 4 CR LF Image: CR Image: CR <t< td=""><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td></td></t<> | | | | | | | | | | | | | | | | | | |
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| averaging times (Sets the number of moving averaging times to "4") 6 Y E S CR LF (Sets the number of moving averaging times to "16") 6 Y E S CR LF (Sets the number of moving averaging times to "16") 6 Y E S CR LF (Sets the number of moving averaging times to "16") 6 Y E S CR LF (Gets the number of moving averaging times to "16") 5 Y E S CR LF (Cancels (deactivates) the moving averaging times in averaging time averaging times is switched or moving averaging is deactivated im mediately after setting. averaging is deactivated im mediately after setting. I | Setting of the number of moving | M | 1 | A | v | | 4 | CR | LF | | | | | | | | 5 | Y E S CR LF 5 |
| (Sets the number of moving averaging times to "16".) M A V 0 CR LF 5 Y E S CR LF CR LF (Cancels (deactivates) the moving averaging function.) A CR LF CR | | (S | ets | the | εnί | ım b | er | of m | ving | | | ng tin | ies I | to "4" | .) | | | |
| M A V 0 (CR LF) 5 Y E S CR LF (Cancels (deactivates) the moving averaging function.) * The number of moving averaging times is switched or moving averaging is deactivated im mediately after setting. | | N (S | t / / | A the | V en i | ım h | 1 er | 6 of m | CR | LF | radi | na tim | | to "1 | s".) | | 6 | Y E S CR LF 5 |
| averaging is deactivated immediately after setting. | | N | 1 / | A | V | | 0 | CR | LF | | | 1 | 1 | | | | 5 | |
| | | (C | an | cels | s (d | ead | tiva | tes) | the | m ovi | ng a i | verag | ing : | funct | ion.) | | | |
| | | | | _} | _ { | | | | | | | | | | | | | averaging is deactivated in mediately aller setting. |

INSTRUCTION MANUAL MODEL A6xxx-x5/x6/x7/x8

| Function | 1 2 3 4 5 6 7 8 9 10 11 1 | 13 14 15 Char. Length 1 2 3 4 5 6 7 8 9 10 11 | 12 13 14 15 16 17 18 Char. Length |
|-----------------------------|---|---|---------------------------------------|
| Step wide response | S W D CR LF | 3 1 CR LF (Response of a state in which step wide is | |
| | | 1 0 CR LF | 2 |
| | | (Response of a state in which step wide is | "10") |
| Step wide setting | S W D 1 CR LF | 5 Y E S CR LF | 5 |
| | (Sets step wide to "1.") S W D 1 0 CR LF | 6 Y E S CR LF | 5 |
| | (Sets step wide to "10.") | * Step wide is switched immediately after s | |
| Display color response | | 3 R E D CR LF | 3 |
| | | (Response of a state in which the display c | ploris red) |
| | | G R E E N CR LF (Response of a state in which the displayc | blorisgreen) 5 |
| | | N O ? CR LF | 5 |
| | | (Response made if the comparison output | unitis not installed) |
| Display color setting | C L R R CR LF | 5 Y E S CR LF | 5 |
| | (Sets display color to red.)) C L R G CR LF | 5 Y E S CR LF | 5 |
| | (Sets display color to green.) | | 5 |
| | | NO ? CR LF (Response made if the comparison output | |
| Dianterration | | | |
| Display color type response | C L T CR LF | 5 A U T O CR LF (Response of a state in which the displayc | olor type is Auto) |
| | | M A N U A L CR LF | 6 |
| | | N O ? CR LF | 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 5 |
| | | (Response made if the comparison output | unit is not installed) |
| Display color type setting | C L T A CR LF | 5 Y E S CR LF | 5 |
| | (Sets the display color type to Auto.) | 5 Y E S CR LF | 5 |
| | C L R M CR LF (Sets the display color type to Manual.) | * The display color type is switched immedi | |
| | | NO CLF | |
| | | | |
| HI display color response | C H I CR LF | 3 R E D CR LF (Response of a state in which the HI displa | v color is red) 3 |
| | | GREENCRLF | 5 |
| | | (Response of a state in which the HIdispla AUTOCRLF | ycolorisgreen) 4 |
| | | (Response of a state in which the display c | olor type is Auto) |
| | | NO CLF | unitis not installed) 5 |
| | | | |
| HI display color setting | C H I R CR LF (Sets HI display color to red.) | 5 Y E S CR LF | 5 |
| | C H I G CR LF | 5 Y E S CR LF | 5 |
| | (Sets HI display color to green.) | + HÍdisplaý color is switched im mediately a A U T O CR LF | ftersetting. |
| | | (Response of a state in which the display c | |
| | | (Response made if the comparison output | unit is not installed) 5 |
| | | (Response of the state of independent judg | |
| GO display color response | | 3 R E D CR LF | 3 |
| | | (Response of a state in which the GO dis | play color is red) 5 |
| | | G R E E N CR LF (Response of a state in which the GO dis | |
| | | A U T O CR LF | 4 |
| | | (Response of a state in which the display NO?CRLF | 5 |
| | | (Response made if the comparison output | t unit is not installed) |
| GO display color setting | C G O R CR LF | 5 Y E S CR LF | 5 |
| | (Sets GO display color to red.) C G O G CR LF | 5 YES CRLF | 5 |
| | (Sets GO display color to green.) | * GO display color is switched immediate | ly after setting. |
| | | A U T O CR LF (Response of a state in which the display | color type is Auto) |
| | | NO ? CR LF | 5 |
| | | (Response made if the comparison output (Response of the state of independent ju | |
| | | | |
| LO display color response | C L O CR LF | 3 R E D CR LF (Response of a state in which the LO dis | 3 (av color is red) |
| | | GREENCRLF | 5 |
| | | (Response of a state in which the LO dis A U T O CR LF | |
| | | (Response of a state in which the display | color type is Auto) |
| | | NO? CR LF (Response made if the comparison output | t unit is not installed) |
| | | | |
| LO display color setting | C L O R CR LF (Sets LO display color to red.) | 5 Y E S CR LF | 5 |
| | C L O G CR LF | 5 Y E S CR LF | 5 |
| | (Sets LO display color to green.) | * LO display color is switched immediatel A U T O CR LF | 4 |
| | | (Response of a state in which the display N O ? CR LF | color type is Auto) |
| | | N O ? CR LF (Response made if the comparison outpu | t unit is not installed) |
| | | (Response of the state of independent ju | |
| | | | <u></u> |

| Function | 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 c | har. Length 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 Char. Length |
|-------------------------------------|--|---|
| Display blank response | B L K CR LF | 3 O F F CR LF 3 |
| | | (Response of a state in which blank setting is OFF) |
| | | (Response of a state in which blank setting is at LV1) |
| | | L V 2 CR LF 3 (Response of a state in which blank setting is at LV2) |
| | | (Response of a state in which blank setting is at LV2) L V 3 CR LF 3 |
| | | (Response of a state in which blank setting is at LV3) |
| | | O N CR LF 2 (Response of a state in which blank setting is ON) |
| | | (Response of a state in which blank setting is ON) |
| Display blank setting | B L K O F F CR LF | 7 YES CRLF 5 |
| | (Deactivates blank setting.) B L K L V 1 CR | 7 Y E S CR LF 5 |
| | (Sets blank setting to LV1.) | |
| | B L K L V 2 CR LF (Sets blank setting to LV2.) | 7 YES CRLF 5 |
| | B L K L V 3 CR LF | 7 YES CRLF 5 |
| | (Sets blank setting to LV3.) | 6 Y E S CR LF 5 |
| | (Activates blank setting.) | |
| | | |
| Jog switch response | J S W CR LF | 3 O N CR LF 2 (Response of a state in which jog switch setting is ON) |
| | | O F F CR\$ LF 3 (Response of a state in which jog switch setting is OFF) 3 |
| | | (Response of a state in which jog switch setting is OFF) N O ? CR LF 5 |
| | | (Response made if the relevant unit is not installed) |
| Jog switch setting | J S W O N CR LF | 6 Y E S CR LF 5 |
| | (Activates jog switch setting.) | |
| | J S W O F F CR: LF (Deactivates jog switch setting.) | 7 Y E S CR LF 5 |
| | | N O ? CR LF 5 |
| | | (Response made if the relevant unit is not installed) |
| Digital zero backup response | B D Z CR LF | 3 O N CR LF 2 |
| | | (Response of a state in which digital zero backup is ON) |
| | | O F F CR LF 3 (Response of a state in which digital zero backup is OFF) |
| | | |
| Digital zero backup control | B D Z O N CR LF (Activates digital zero backup:) | 6 Y E S CR LF 5 |
| | B D Z O F F CR LF | 7 Y E S CR LF 5 |
| | (Deactivates digital zero backup.) | |
| Digital zero data save command | S A V CR LF | 3 Y E S CR LF 5 |
| | | N O ? CR LF 5 |
| | | (Response made if the relevant unit is not installed) |
| Response of the number of patterns | P S N CRLF | 3 1 CR{LF |
| for pattern select | | (Response of a state in which the number of patterns for pattern select is "1") |
| | | 8 CR{LF 1 |
| | | (Response of a state in which the number of patterns for pattern select is "8") |
| Control over the number of patterns | P S N 1 CR LF | 5 Y E S CR LF 5 |
| for pattern select | (Sets the number of patterns for pattern select to "1.") P S N 8 CR LF 1 | 5 Y E S CR LF 5 |
| | (Sets the number of patterns for pattern select to "8.") | |
| Linearize function status response | | 3 O F F CR LF 3 |
| | | (Response of a state in which the linearize function is OFF) |
| | | 2 CR ³ LF 1 (Response of a state in which the linearize correction point is "2") |
| | | 1 6 CR LF 2 |
| | | (Response of a state in which the linearize correction point is "16") |
| Linearize function status setting | L I N O F F CR LF | 7 Y E S CR LF 5 |
| | (Deactivates the linearize function.) | |
| | L I N 2 CR LF (Sets linearize correction point to "2.") | 5 Y E S CR LF 5 |
| | L I N 1 6 CR LF | 6 Y E S CR LF 5 |
| | (Sets linearize correction point to "16.") | |
| Tracking zero response | T R K CR LF | 3 0 N T = 1 W = 1 CR LF 10 |
| | | (Response of a state in which the tracking zero time is "1" and tracking zero width is "1") O N T = 9 9 9 W = 9 9 CR LF 12 |
| | | (Response of a state in which the tracking zero time is "99" and |
| | | tracking zero width is "99") O F CR LF 3 |
| | | (Response of a state in which the tracking zero function is OFF) |
| Tracking zero setting | | 7 YES CRLF 5 |
| | (Sets tracking zero time to "1.") | |
| | T R K T = 9 9 7 CR LF (Sets tracking zero time to "99.") | 8 Y E S CR LF 5 |
| | T R K W = 1 CR LF | 7 YES CRLF 5 |
| | (Sets tracking zero width to 1 digit.) | |
| | T R K W = 9 9 CR LF (Sets tracking zero width to 99 digits.) | 8 Y E S CR LF 5 |
| | T R K T = 0 CR LF | 7 Y E S CR LF 5 |
| | (Deactivates the tracking zero function.) * In order to validate a tracking zero setup, please perform a n | number of times setup of an average continuously after carrying out a tracking zero setup. |
| L | | |

| Function | 1 2 3 4 5 6 7 8 9 10 11 12 13 | 3 14 15 Char. Length 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 Char. Length |
|---------------------------------|---|--|
| Power-on delay time response | P O N CR LF | 3 0 CR LF 1 |
| | | (Response of a state in which the power-on delay function is OFF) |
| | | 1 CR LF 1 1 (Response of a state in which the power-on delay time is 1 second) 1 |
| | | 9 CR LF |
| | | (Response of a state in which the power-on delay time is 9 seconds) |
| D | | |
| Power-on delay time setting | PON 1 CRLF (Sets power-on delay time to 1 second.) | 5 Y E S CR LF 5 |
| | PON 9 CRLF | 5 YES CRLF 5 |
| | (Sets power-on delay time to 9 seconds.) | |
| | PON 0 CR LF | 5 Y E S CR LF 5 |
| | (Deactivates the power-on delay function.) | |
| Protect level response | P R O CR LF | 3 L V 0 CR LF 3 |
| | | (Response of a state in which the protect level is at LV0) |
| | | L V 1 CR LF 3 |
| | | (Response of a state in which the protect level is at LV1) |
| | | L V 2 CR LF 3 (Response of a state in which the protect level is at LV2) |
| | | L V 3 CR LF |
| | | (Response of a state in which the protect level is at LV3) |
| Desite et la calla a tita a | | 7 YES CRIF |
| Protect level setting | P R O L V 0 CR LF (Sets protect level to LV0.) | 7 Y E S CR LF 5 |
| | | 7 Y E S CR LF 5 |
| | (Sets protect level to LV1.) | |
| | PROLV2CRLF | 7 YES CRLF 5 |
| | (Sets protect level to LV2.) P R O L V 3 CR LF | 7 Y E S CR LF 5 |
| | (Sets protect level to LV3.) | |
| | | |
| Unit number indication response | U N O CR LF | 3 0 N CR LF 2 |
| | | (Response of a state in which the unit number indication is ON) O F F CR LF 3 |
| | | (Response of a state in which the unit number indication is OFF) |
| | | |
| Unit number indication setting | U N O O N CR LF | 6 Y E S CR LF 5 |
| | (Activates unit number indication.) | 7 YES CRLF 5 |
| | UNOF CREAT (Deactivates unit number indication.) | |
| | | |
| Start hold type response | S T T CR LF | 3 A CR LF 1 |
| | | (Response of a state in which the start hold type is A) B CR LF |
| | | B CR LF 1 (Response of a state in which the start hold type is B) |
| | | |
| Start hold type setting | S T T A CR LF | 5 Y E S CR LF 5 |
| | (Sets start hold type to A) | 5 YES CRLF |
| | S T T T B CR LF (Sets start hold type to B.) | 5 Y E S CR LF 5 |
| | | |
| Peak hold type response | P V T CR LF | 3 A CR LF 1 |
| | | (Response of a state in which the peak hold type is A) B CR LF 1 |
| | | (Response of a state in which the peak hold type is B) |
| | | |
| - | | |
| Peak hold type setting | P V T A CR LF | 5 Y E S CR LF 5 |
| Peak hold type setting | P V § T A §CR {LF (Sets peak hold type to A.) P V § T P V § T B {CR {LF} (Sets peak hold type to B.) Image: Set | |

| Function | 1 2 3 4 5 6 7 8 9 10 11 12 13 | 14 15 Char. Length | | |
|----------------------|---|--------------------|---|----------------|
| Baud rate response | B A U CR LF | 3 | 2 4 0 0 CR LF | 4 |
| | | | (Response of a state in which the baud rate is 2400 bps) | |
| | | | (Response of a state in which the baud rate is 4800 bps) | 4 |
| | | | 9 6 0 0 CR LF | 4 |
| | | | (Response of a state in which the baud rate is 9600 bps) | |
| | | | 1 9 2 0 0 CR LF | 5 |
| | | | (Response of a state in which the baud rate is 19200 bps) | |
| | | | 3 8 4 0 0 CR LF | 5 |
| | | | (Response of a state in which the baud rate is 38400 bps) | |
| | B A U 2 4 0 0 CR LF | 8 | Y E S CR LF | 5 |
| | (Sets the baud rate to 2400 bps.) | Ŭ | | , i i |
| | B A U 4 8 0 0 CR LF | 8 | Y E S CR LF | 5 |
| | (Sets the baud rate to 4800 bps.) | | | |
| | B A U 9 6 0 0 CR LF | 8 | Y E S CR LF | 5 |
| | (Sets the baud rate to 9600 bps.) B A U 1 9 2 0 0 CR LF | 9 | Y E S CR LF | 5 |
| | (Sets the baud rate to 19200 bps.) | 9 | | |
| | B A U 3 8 4 0 0 CR LF | 9 | Y E S CR LF | 5 |
| | (Sets the baud rate to 38400 bps.) | | * The baud rate is switched upon next power-up. | |
| | | | | |
| Data length response | D A T CR LF | 3 | 7 CR LF | 1 |
| | | | (Response of a state in which the data length is 7 bits) 8 CR LF | 1 |
| | | | (Response of a state in which the data length is 8 bits) | |
| | | | | |
| | DAT 7 CR LF | 5 | Y E S CR LF | 5 |
| | (Sets data length to 7 bits.) | | | |
| | DAT 8 CR LF | 5 | Y E S CR LF | 5 |
| | (Sets data length to 8 bits.) | | * The data length is switched upon next power-up. | |
| Parity bit response | P B T CR LF | 3 | E V E N CR LF | 4 |
| ranty bit lesponse | | 5 | (Response of a state in which a parity bit is even parity) | 4 |
| | | | O D D CR LF | 3 |
| | | | (Response of a state in which a parity bit is odd parity) | |
| | | | N O CR LF | 2 |
| | | | (Response of a state in which a parity bit is none) | |
| | P B T E CR LF | 5 | Y E S CR LF | 5 |
| | (Sets a parity bit to even parity.) | 5 | | |
| | P B T O CR LF | 5 | Y E S CR LF | 5 |
| | (Sets a parity bit to odd parity.) | | | |
| | P B T N CR LF | 5 | Y E S CR LF | 5 |
| | (Sets a parity bit to none.) | | * A parity bit is switched upon next power-up. | |
| Otan hit manana a | S B T CR LF | | 1 CR LF | |
| Stop bit response | | 3 | (Response of a state in which a stop bit is 1 bit) | 1 |
| | | | 2 CR LF | 1 |
| | | | (Response of a state in which a stop bit is 2 bits) | |
| | | | | |
| | S B T 1 CR LF | 5 | Y E S CR LF | 5 |
| | (Sets a stop bit to 1 bit.) | 5 | | 5 |
| | S B T 2 CR LF (Sets a stop bit to 2 bits.) | 5 | Y E S CR LF * A stop bit is switched upon next power-up. | 5 |
| | | | | |
| Delimiter response | D L M CR LF | 3 | C R + L F CR LF | 5 |
| | | | (Response of a state in which a delimiter is CR + LF) | |
| | | | C R CR LF | 2 |
| | | | (Response of a state in which a delimiter is CR) | |
| | D L M C L CR LF | 6 | Y E S CR LF | 5 |
| | (Sets a delimiter to CR + LF.) | 0 | | |
| | D L M C CR LF | 5 | Y E S CR LF | 5 |
| | (Sets a delimiter to CR.) | | * A delimiter is switched upon next power-up. | |
| | | | | |
| Device ID response | A D R CR LF | 3 | 1 CR LF | 1 |
| | | | (Response of a state in which the device ID is "01") | 2 |
| | | | 9 9 CR LF | 2 ² |
| | | | | |
| Device ID setting | A D R 1 CR LF | 5 | Y E S CR LF | 5 |
| 5 | (Sets device ID to "01".) | | | |
| | A D R 9 9 CR LF | 6 | Y E S CR LF | 5 |
| | (Sets device ID to "99".) | | * Device ID is switched upon next power-up. | |
| | | | | 1 1 |

| Function | 1 | 2 3 4 | 5 6 7 8 | 9 10 11 | 12 13 1 | 1 15 Char. Leng | th 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 Char. | . Length |
|-----------------------------------|---|----------|---------|---------|---------|-----------------|---|----------|
| Condition data parameter response | A | | | | | 3 | A V G 1 CR LF | 5 |
| | | | | | | | (Response of a state in which the number of averaging times is "1") M A V O F F CR LF | 7 |
| | | | | | | | (Response of a state in which the moving averaging function is OFF) | _ |
| | | | | | | | S W D 1 CR LF 4 (Response of a state in which step wide is "1") | 5 |
| | | | | | | | C L R R E D CR LF | 7 |
| | | | | | | | (Response of a state in which the display color is red) 1 C L T M A N U A L CR LF 1 | 10 |
| | | | | | | | (Response of a state in which the display color type is Manual) | 10 |
| | | | | | | | | 7 |
| | | | | | | | (Response of a state in which the HH display color is red) C H I R E D CR LF I <td< td=""><td>7</td></td<> | 7 |
| | | | | | | | (Response of a state in which the HI display color is red) | _ |
| | | | | | | | C G O R E D CR LF | 7 |
| | | | | | | | | 7 |
| | | | | | | | (Response of a state in which the LO display color is red) C L R E D CR L I | 7 |
| | | | | | | | (Response of a state in which the LL display color is red) | |
| | | | | | | | B L K O F F CR LF | 7 |
| | | | | | | | | 6 |
| | | | | | | | (Response of a state in which the jog switch is ON) | |
| | | | | | | | P V H P H - O F F CR LF 1 (Response of a state in which peak hold select is OFF at PH) 1 | 10 |
| | | | | | | | B D Z O N CR LF | 6 |
| | | | | | | | (Response of a state in which digital zero backup is ON) P S N 1 CR LF | 5 |
| | | | | | | | (Response of a state in which pattern select is "1") | |
| | | | | | | | L I N O F F CR LF Image: CR Image: CR <t< td=""><td>7</td></t<> | 7 |
| | | | | | | | | 7 |
| | | | | | | | (Response of a state in which tracking zero is OFF) | 5 |
| | | | | | | | PONOOCRLF (Response of a state in which the delay time is "0") | 5 |
| | | | | | | | | 7 |
| | | | | | | | (Response of a state in which the protect level is at LV0) U N O F F CR LF F <td< td=""><td>7</td></td<> | 7 |
| | | | | | | | (Response of a state in which unit number indication is OFF) | _ |
| | | | | | | | S T T A CR LF Image: CR Image | 5 |
| | | | | | | | S T D | 9 |
| | | | | | | | P V T A CR LF Image: CR Image | 5 |
| | | | | | | | B A U 9 6 0 0 CR LF | 8 |
| | | | | | | | (Response of a state in which the baud rate is 9600 bps) D A T 7 CR LF | 5 |
| | | | | | | | (Response of a state in which the data length is 7 bits) | 5 |
| | | | | | | | | 8 |
| | | | | | | | (Response of a state in which a parity bit is even parity) S B T 2 CR LF 4 | 5 |
| | | | | | | | (Response of a state in which a stop bit is 2 bits) | |
| | | | | | | | D L M C R + L F CR LF (Response of a state in which a delimiter is CR + LF) | 9 |
| | | | | | | | | 5 |
| | | | | | | | (Response of a state in which the device ID is 01) | |
| Scaling data parameter response | A | L 2 CR L | F | | | 3 | | 3 |
| | | | | | | | (The pattern used previously is responded.) | 7 |
| | | | | | | | (Response of a state in which the measurement range is 2 A) | |
| | | | | | | | (Response of a state in which the input type is open collector) | 8 |
| | | | | | | | F S C 9 9 9 9 9 CR LF 1 (Response of a state in w hich the full-scale indicated value is "9999") 1 | 10 |
| | | | | | | | F I N 9 9 9 CR LF 1 | 10 |
| | | | | | | | (Response of a state in which the full-scale input value is "9999") O F S I O CR LF | 10 |
| | | | | | | | (Response of a state in which the offset indicated value is "0") | 10 |
| | | | | | | | (Response of a state in which the offset input value is "0") | |
| | | | | | | | | 7 |
| | | | | | | | P P R 1 CR LF | 5 |
| | | | | | | | (Response of a state in which the frequency division value is "1") D L H I 9 9 9 9 0 CR LF | 10 |
| | | | | | | | (Response of a state in which the digital limiter HI value is "9999") | |
| | | | | | | | D L L O - 9 9 9 CR LF 1 (Response of a state in which the digital limiter LO value is "-9999") | 10 |
| | | | | | | | A O U T 0 - 1 CR LF | 8 |
| | | | | | | | | 9 |
| | | | | | | | (Response of a state in which the analog output HI indicated value is "9999") | 6 |
| | | | | | | | (Response of a state in which the analog output LO indicated value is "0") | |
| | | | | | | | UNITIC CRLF (Response of a state in which the temperature indication unit is °C) | 6 |
| | | | | | | | | 7 |
| | | | | | | | (Response of a state in which there is no decimal point) | |
| | | | | · · · · | 4 i :- | · · | | |

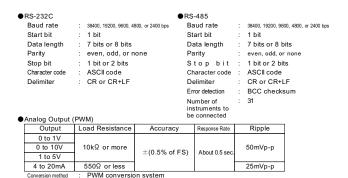
| Function | | 2 | | | 5 | 6 7 8 | 9 | 10 | 11 } 12 | 2 13 | 14 | 15 | Char. Length | |
|--|---|---|---|----|----|-------|------------|-----|---------|------|-----|----|--------------|--|
| Comparator data parameter response *Case of the comparison output type is high-and low-limit setting | A | L | 3 | CR | LF | | | | | | | | 3 | P - 1 CR LF 3 (The pattern used previously is responded.) C O M T O / U CR LF 8 |
| | | | | | | | | | | | | | | (Response of a state in which the comparison output type is of high-and low-limit setting) H - S 1 0 0 0 0 CR LF 10 10 |
| | | | | | | | | | | | | | | (Response of a state in which the HI judgment value is "1000") L O - S - S - S - S - S - S |
| | | | | | | | | | | | | | | (Response of a state in which the LO judgment value is "500") 1 H I - H 0 CR LF 10 10 |
| | | | | | | | | | | | | | | (Response of a state in which the HI hysteresis is "0") 1 L O - H 1 0 CR L 0 10 |
| | | | | | | | | | | | | | | (Response of a state in which the LO hysteresis is "0") H I - L N O CR LF |
| | | | | | | | | | | | | | | (Response of a state in which HI logic is normally open) Image: Comparison of a state in which GO logic is normally open) 7 (Response of a state in which GO logic is normally open) 7 |
| | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | (Response of a state in which LO logic is normally open) |
| *Case of the comparison output type is the tolerance judgment | A | L | 3 | CR | LF | | \uparrow | | - | 1 | | | 3 | P - 1 CR LF 3 (The pattern used previously is responded.) 3 3 3 3 |
| | | | | | | | | | | | | | | C O M T E R R CRLF 8 (Response of a state in which the comparison output type is of |
| | | | | | | | | | | | | | | $ \begin{array}{c c} Response \\ Ins \\ V \\ A \\ L \\ Ins \\ I$ |
| | | | | | | | | | | | | | | Response of a state in which the nominal value is "5000") 1 E R 1 5 0 0 CR LF 11 |
| | | | | | | | | | | | | | | (Response of a state in which tolerance 1 is "5.00") 1 E R 1 1 0 CR{LF 10 |
| | | | | | | | | | | | | | | $\begin{array}{c c c c c c c c c c c c c c c c c c c $ |
| | | | | | | | | | | | | | | (Response of a state in which HI logic is normally open) G O ! - L N O CR LF |
| | | | | | | | | | | | | | | (Response of a state in which GO logic is normally open) |
| | | | | | | | | | | | | | | Response of a state in which LO logic is normally open) N O ? CR LF |
| Calibration data response | | | 4 | CR | LF | | - | | _ | _ | | | 3 | (Response made if the relevant input unit is not installed) P - 1 (CR LF |
| | | - | | | | | | | | | | | - | The pattern used previously is responded.) S N S R 5 CR LF 6 |
| | | | | | | | | | | | | | | (Response of a state in which the sensor power is 5 V) 1 Z R I N 0 . 0 0 CR LF 10 |
| | | | | | | | | | | | | | | CResponse of a state in which the zero input value is "0.000") Z E R O 0 CR LF 6 |
| | | | | | | | | | | | | | | (Response of a state in which the zero indicated value is "0") S P I I N 2 0 0 CR LF 10 |
| | | | | | | | | | | | | | | (Response of a state in which the span input value is "2.000") \$\$ P A N \$\$ 9 9 9 9 CR LF\$\$ \$\$ 9 |
| | | | | | | | | | | | | | | (Response of a state in which the span indicated value is "9999") N O ? CR LF 5 |
| | | | | | | | | | | | | | | (Response made if the relevant input unit is not installed) |
| Linearize data response | A | L | 5 | CR | LF | | | | | | | | 3 | 0 1 6 (Response of a state in which the linearize data N-01 input value is "0") 0 1 1 0 = 0 ICR LF 3 6 6 |
| | | | | | | | | | | | | | | 0 1 0 = 0 0R LF 6 (Response of a state in which the linearize data N-01 output value is "0") 0 2 1 = 1 0 0 CR LF 8 |
| | | | | | | | | | | | | | | (Response of a state in which the linearize data N-02 input value is "100") 0 2 0 = 1 1 1 0 CR LF 8 |
| | | | | | | | | | | | | | | (Response of a state in which the linearize data N-02 output value is "110") |
| | | | | | | | | | | | | | | 0 2 1 = 5 0 0 CR LF 8 |
| | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | 1 6 I I 9 0 0 0 CR LF 9 (Response of a state in which the linearize data N-16 9 |
| | | | | | | | | | | | | | | input value is "9000") |
| | | | | | | | | | | | | | | output value is "9200") |
| | | | | | | | | | | | | | | (Response of a state in which the linearize function is OFF) |
| Common response | ┢ | - | ┝ | 1 | | | | | | + | | | | Y E S CR LF 5 |
| | | | | | | | | | | | | | | (Normal response) N 0 7 CR LF 5 |
| | | | | | | | | | | | | | | (Response to an undefined command, etc.) |
| | | | | | | | | | | | | | | E R R O R A CR LF I F F F F F F F F F F F F F F F F F |
| | | | | | | | | | | | | | | (Response made if there is a communication parameter error) * There are ERROR B to ERROR F as an equivalent response command. * If there is a response of the ERROR X command, perform the |
| | | | | | | | | | | | | | | same steps again. If this does not solve the problem, turn the meter supply OFF and then ON again. |
| Response made if internal memory data is abnormal | | | | | | | | | | | | | | D A T A L O S T C O N D CR LF 14 (Response made if condition data is abnormal) |
| * Generally, a response is made only once. | | | | | | | | | | | | | | D A T A L O S T C O M CR LF 13 |
| | | | | | | | | | | | | | | (Response made if comparator data is abnormal) |
| | | | | | | | | | | | | | | (Response made if scaling data is abnormal) |
| | | | | | | | | | | | | | | * Set scaling data again. |
| | - | - | • | 2 | | | - | · · | 0 | | , 1 | | | |

INSTRUCTION MANUAL MODEL A6xxx-x5/x6/x7/x8

| Function Scaling data setting | 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 Char. Length 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 Char. Length 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 Char. Length 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 Char. Length 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 M E T CR LF 3 P - 1 CR LF 14 15 16 | 17 18 Char. Length |
|---|---|--------------------|
| | * Indication becomes "MET" at the instant the MET (The pattern used previously is responded.) | |
| | command has been received. | |
| | 2 CR LF | 3 |
| | M CR LF 2 R A N G 2 A CR LF | 7 |
| | | |
| | | 7 |
| | (Sets the measurement range to 1 V.) 1 F S C 9 9 9 CR LF | 8 |
| | | U U U |
| | 8 0 0 0 CR LF 4 F S C 8 0 0 0 CR LF | 8 |
| | (Sets the full-scale indicated value to "8000.") 1 0 F S 0 CR LF Image: CR Image: CR <td>5</td> | 5 |
| | | 5 |
| | 2 0 0R LF 2 0 F S 2 0 0R LF | 6 |
| | (Sets the offset indicated value to "20.") | |
| | E CR LF | 5 |
| | command causes data acquired up to that point to be NO ? CR LF | 5 |
| | return to measurement operation. (Response made if a value out of the setting range is input) | |
| Comparator data setting | COMCRIF | 3 |
| *Case of the companson output type | * The main unit's indication becomes "COM" at the (1) (The pattern used previously is responded.) | |
| is high-and low-limit setting. | instant the COM command has been received. | |
| Sets data-setting pattern to "2" and HI logic to "8000",set LO logic to "-5000", | | 3 |
| and sets HI &LO logic to normally | Sets data-setting pattern to "2.") 1 C O M U CR LF I | 8 |
| closed. | | |
| | M CR LF 1 H I - S 1 0 0 0 CR LF | 9 |
| | 8 0 0 0 CR LF | 9 |
| | (Sets HI logic to "8000.") | |
| | M CR LF 1 L O - S 5 0 0 CR LF | 8 |
| | - 5 0 0 0 0 0 CR LF 5 L O - S - 5 0 0 0 0 CR LF | |
| | - 5 0 | 10 |
| | | 6 |
| | | |
| | M CR LF 1 L O - H 0 CR LF | 6 |
| | M CR LF | 7 |
| | | |
| | N C CR LF LF LF LF (Sets HI logic to normally closed.) 2 H I - L N C CR LF | 7 |
| | M CR LF 1 G O - L N O CR LF | 7 |
| | | |
| | M CR LF 1 L O - L N O CR LF | 7 |
| | | 7 |
| | (Sets LO logic to normally closed.) | |
| | | 5 |
| | A return to measurement operation using the E E R R O R 0 CR LF | 7 |
| | command (If the N command is sent, a return to side judgment value is made.) | |
| | N 0 ? 08 LF | 5 |
| | (Response of a state in which the relevant input unit is not installed) | |
| *Case of the compason output type is sets the nominal value to "8000", | C O M CR LF 3 P - 1 CR LF 3 P - 1 CR LF 5 COM" at the CT A state of the pattern used previously is responded.) | 3 |
| sets the tolerance 1 to "20.00". | | 8 |
| | | |
| | E R R CR LF 6 C O M T E R R CR LF (Sets the comparator output type to tolerance judgment.) | 8 |
| | M CR LF 1 N V A L 5 0 0 0 CR LF | 10 |
| | | |
| | 8 0 0 0 CR LF 4 N V A L 8 0 0 0 CR LF | 10 |
| | (Sets the nominal value to "8000.") 1 E R 1 5 . 0 0 CR LF | 11 |
| | | |
| | 2 0 0 0 CR LF 5 E R R 1 2 0 . 0 0 CR LF | 11 |
| | Sets tolerance 1 to "20.00.") 1 E R 1 H 0 0 CR LF 0 CR | 10 |
| | | |
| | | 5 |
| | * Areturn to measurement operation using the E | |
| | command (If the N command is sent, a return to side judgment value is made.) | 7 |
| | side judgment value is made.) (Response made if a value not meeting the setting conditions is input NO OR | 5 |
| | (Response of a state in which the relevant input unit is not installed) | |
| * The serves estimation methods as these a | above are also used for setting of other data (such as linearize data) | |

* The same setting methods as those above are also used for setting of other data (such as linearize data).

5 Specifications and Dimensions



about 14 bits or equivalent

Resolution

6 Warranty and After-sales Services

6.1 Warranty

The warranty period of this product is one year from the date of delivery. If a problem occurs during this warranty period and its cause is determined to be attributable to us, and will repair the product without charge.

6.2 After-sales Services

This product has been manufactured, tested, and inspected under strict quality control before shipment from the factory. If the product breaks down, contact your sales representative or our local office (or send it). In this case, write down the problem in detail and report it to your service representative (or enclose it with the product).

