Units for Measurement of Large DC and AC Currents

#### / Caution

- (1) Applying a voltage or current exceeding its maximum permissible value may cause the unit to be damaged.
- Always use the unit within the specified voltage range; otherwise, it may cause a fire, electric (2)
- hock or personal/equipment damage (3) For the purpose of functional improvement, the information written herein may be changed without prior notice
- (4) Information contained herein is considered accurate to the best of our knowledge. If you have
- any question or comment on the information, please contact us or our distributor Read this manual carefully and thoroughly before starting to operate the unit, and keep the manual available for future reference. (5)

#### 1 Before Using the Unit

Thank you for purchasing our quality designed and manufactured A6000 Series. Before unpacking the unit, check for damages during transportation. If you have noticed any damage, directly contact us or our distributor.

#### 1.1 Type Identification

Each model number of the A6000 series has its general specifications, and the following describes each note and the meaning. Before using the unit, check that the model number and specifications of the delivered unit match those of the product you ordered. For optional units, see the separate instruction Manuals.

A 6 Power supply unit 1 Alternating current (2 unit types) 2 Direct current Display unit 1 Multidisplay 2 Single display (2 unit types) Input unit : 1 DC voltage measurement DC current measurement (small electric current) (11 unit types) 2 3 DC current measurement (large electric current) AC voltage measurement AC current measurement (small electric current) AC current measurement (large electric current) Resistance measurement Temperature measurement Frequency measurement Load cell input B Process signal measurement Comparator out put unit : 0 None (2 unit types) Relay contact output Photocoupler output Option units : 0 None (8 unit types) External control 1 BCD output (TTL)+external control 2 3 BCD output (open collector)+external control Analog output (PWM)+external control 4 RS-232C 5 RS-485 RS-232C+analog output (PWM)

#### 1.2 Accessories

Accessory	Quantity	Remarks
6-p terminal cover	2 or 3 each	2 without a comparator output 3 with a comparator output
Mounting band	2 pieces	
Unit indication label	1 each	

RS-485+analog output (PWM)

#### Mounting Method 2

### 2.1 Panel Cut Size

Cut the panel to mount the A6000 series in accordance with the illustration below:



## 2.2 How to Mount the Unit on the Panel

Mount the A6000 series to the panel in accordance with the illustration below

#### (1) Remove the mounting band and insert the case from the front of the panel.

(2) Fix the case using the mounting band from the ear of the pane



- (1) The recommended panel thickness is 0.8 to 5mm
- Do not install the unit in locations where it is exposed to direct sunlight; where ambient emperature or humidity doesn't meet the requirements below; or where a drastic change in temperature may ause condensation. Ambient temperature: 0 to 50°C Ambient humidity: 35 to 85%
   Do not install the unit where it is exposed to dust, particles, chemicals harmful to electric components, corrosive gases, etc.
- (4) When this unit is installed inside other equipment, pay attention to the heat radiation and keep the heat inside the equipment 50°C or below.
- (5) Do not install the unit where it is exposed to excessive vibration or shock.
- (6) Install the unit horizontally; otherwise, ventilation will be adversely affected and may result in deterioration.

#### Terminals and Connections 3



#### 3.1 Power supply connections



## 3.2 Input Signal Connections



#### **Comparator Output Connections** 3.3





#### 3.4 Option connections

For connections of the options, see separate optional function instruction Manuals.

# 4 Parameter Settings

## 4.1 Multi Display Unit

#### Names and major functions



## Instruction Manual for MODEL A6xx3 or A6xx6

How to set a low layer value (Condition data/scaling data/comparator data)



#### Remarks:

The multi display unit can also follow the operation procedure of the single display unit operation system.
 Comparator judgment values can be set not only from Jog 2 and Jog 3 but also from the low layers of the comparator data.
 For operation procedures in the memory mode (maximum value/minimum value/(maximum value-minimum value)), see the operation procedure diagram of the single display unit.

#### 4.2 Single Display Unit

#### Names and major functions



Location	Name		Major function								
1	Judgment monitor	Displa	Displays judgment results when used with meter relay.								
2	Main monitor	Displays a measured value as well as menu names and values at the time of parameter setting.									
		RE	E Illuminates when the unit is set to the remote mode via communication function.								
		РH	PH Illuminates when peak hold, valley hold, or peak-valley hold is turned on.								
		DZ	Illun	ninates wh	en Digital 2	Zero is turn	ed on.				
		ΤZ	TZ Illuminates when Tracking Zero is turned on.								
3	Function monitor	ΜE	Illuminates when Digital Zero Backup is turned on.								
		P1		Pattern 1	Pattern 2	Pattern 3	Pattern 4	Pattern 5	Pattern 6	Pattern 7	Pattern 8
			P1	OFF	ON	OFF	ON	OFF	ON	OFF	
		P2 P3	Ρ2		OFF	ON			OFF	ON	ON
			Ρ3		UFF	OFF	OFF	ON	ON		
4	Enter	Switch	nes to	the param	eter setting	g mode.					
5	Mode	Chang norma	jes m I mea	odes at the surements	e time of pa s (when this	rameter se s button is	etting; swite oushed and	ches to the d held.)	memory m	ode at the	time of
6	Shift	Select (when	s digi this t	ts at the tir outton is pu	ne of parar ushed and	neter settir held.)	ig; DZ cont	trol at the ti	me of norn	nal measur	ements.
Ø	Increment	Chang (when	es val this bu	ues at the ti utton is push	me of param ned and held	eter setting l) ; special o	pattern sel	ection at the	time of nor	mal measure	ements



Use the Mode key to shift from the value change mode to the menu selection mode.

Mode

Enter or 

Use the Increment key to select the menu name of the parameter you want to change or return to measurement by pushing the Enter key

#### 4.3 Numeric and Character Indications



#### 4.4 Protection Levels

Each parameter of the A6000 has an individual protection level, and by setting the protection level of the condition data, you can set an access level. (For the protect level of each parameter, see the P.L. column of the tables in Section 4.5.)

The higher the protection level is, the less the number of settable parameters will be. If you set the protection level to the strictest LV3, you can change the protection level only, and all the other parameters may not be changed. (No comparator judgment value can be changed using the jog switches in this case.) \*The protection level set at the time of shipment is LV1. (Settings of display colors, scaling and judgment-related values only are available.)

#### 4.5 List of the Parameters

The parameters for the process signal measurement unit can be roughly divided into three types: condition data which deal with basic functions including sampling time; scaling data which control measurement including input range; and comparator data (for meter relay only) which deal with comparator output.

#### 4.5.1 Condition Data

Menu indication	Parameter name	Initial value	P.L	Setting range or alternatives	Major setting purpose and remarks			
AVG	Average times	50	0	1/2/4/8/10/20/50/100/200/ 400/800/1000/2000/5000	Selects Conversion rate (average times of internal sampling; sampling time: approx. 1 millisecond) *For the AC measurement unit, the max is 400 times on average (approx. 2.5 times/second).(Initial Value 400)			
MAV	Average times of movements	1	0	1/2/4/8/16/32	Selects the average times of movements.Filtering effects: Small<1(OFF)-2-4-8-16-32>Big			
S.WD	Step wide	1	0	1/2/5/10	Selects the range of display changes to maintain image display consistency. (If this parameter is set to 5, the lowest digit will display either 0 or 5 only).			
CLR	Display color	RED	1	RED/GREEN	Selects display colors.*Only when without meter relay.			
CLR.T	Display color type	Αυτο	1	AUTO/MANU	Selects automatic (red in the HI or LO mode or green in the GO mode) or manual setting for display color type. *Only when with meter relay.			
HI.CL	HI display color	RED	1	RED/GREEN	Selects red or green as display color at the time of HI judgment.*Only when CLR.T is MANU.			
GO.CL	GO display color	GREN	1	RED/GREEN	Selects red or green as display color at the time of GO judgment.*Only when CLR.T is MANU.			
LO.CL	LO display color	RED	1	RED/GREEN	Selects red or green as display color at the time of LO judgment.*Only when CLR.T is MANU.			
BLNK	Display blank level	OFF	0	OFF/LV1/LV2/LV3/ON	Selects the display brightness. -bright OFF-LV1-LV2-LV3-ON >turned off			
J.SW	Jog SW	ON	0	ON/OFF	Selects whether the jog SW is used or not.*With the multi display unit only.			
PVH	PH Selection	PH	0	PH/VH/PVH	Selects a type that operates when the PH function is turned on (peak hold/valley hold/peak-valley hold).			
DZ.BU	DZ backup	OFF	0	OFF/ON	Selects whether the digital zero value is backed up or not at the time when the unit is turned off.			
PS	P.SEL	1	0	1/2/4/8	Selects the number of patterns available for the pattern selection function.			
LINE	Linearize	OFF	0	OFF/2/4/8/16	Selects whether the linearize function is enabled/disabled and sets the number of correction points.			
TR.T	TZ time	000	0	000 to 999	Selects whether the tracking zero function is enabled/disabled and sets the correction time (setup value/conversion rate).			
TR.W	TZ correction range	01	0	01 to 99	Sets the correction range of the tracking zero function.*Only when TR.T is set to a value other than 000.			
P.ON	Power on delay time	0	0	0 to 9	Sets the time between the startup and actual start of measurements (setup value x 1 second).			
PRO	Protection level	LV.1	3	Lv.0/LV.1/LV.2/LV.3	Selects the protection level to prevent operation mistakes.High< LV3-LV2-LV1-LV0 >Low			
U-NO.	Unit number indication	OFF	0	OFF/ON	Selects whether the code of a unit mounted at the time of startup is displayed or not.			
S/H.T	Start/hold type	Α	0	A/B	Selects an operation type of start/hold (A: free run; B: one shot).*Only with the external control.			
S/H.D	S/H delay time	0	0	0 to 9999	Sets the delay time at the time of startup (setup value x 1 ms).*Only with the external control.			
PVH.T	PH type	Α	0	A/B	Selects an operation type of peak hold (A: real-time display; B: results display).*Only with the external control.			
DZ.C	DZ control	SW	0	SW/TERM	Selects a control method of Digital Zero (SW: front key; TERM: external control terminal).* Only with the external control.			
PS.C	P.SEL control	SW	0	SW/TERM	Selects a control method of Pattern Selection (SW: front key; TERM: external control terminal).*Only with the external control.			
BCD.L	BCD logic	N.LOG	0	N.LOG/P.LOG	Selects the BCD output logic (N: negative logic; P: positive logic).*Only when the BCD output is available.			
BAUD	Baud rate	9600	1	2400/4800/9600/19200/38400	Sets a baud rate for communication.*Only when the communication function is available.			
DATA	Data length	7	1	7/8	Selects the data length for communication.*Only when the communication function is available.			
P.BIT	Parity bit	E	1	E/O/N	Selects the parity bit for communication.*Only when the communication function is available.			
STP.B	Stop bit	2	1	1/2	Selects the stop bit for communication.*Only when the communication function is available.			
Т-	Delimiter	CR.LF	1	CR.LF/CR	Selects a delimiter for communication.*Only when the communication function is available.			
ADR	Equipment ID	01	1	01 to 99	Selects the equipment ID for the RS-485 function.*Only when the RS-485 function is available.			

### 4.5.2 Scaling Data

Menu indication	Parameter name	Initial value	P.L.	Setting range or alternatives	Major setting purpose and remarks			
RANG	Input range	26	1	25/26	Selects an input range.*Note that input terminals vary depending on the actual input range.			
FSC	Full scale indication	9999	2	-9999 to +9999				
FIN	Full scale input	9999	2	-9999 to +9999	Sets the relationship between the input signal and its indication. * In the case of AC input, please use it by "+" setting by all means.			
OFS	Offset indication	0	2	-9999 to +9999	It is not displayed normally when I use it by "-" setting.			
OIN	Offset input	0	2	-9999 to +9999				
DLHI	Digital limiter HI	9999	0	-9999 to +9999	Sets the upper limit of the displayable range. (Any value equal to or exceeding the digital limiter HI setting will not be updated and kept at the setup value.			
DLLO	Digital limiter LO	-9999	0	-9999 to +9999	Sets the lower limit of the displayable range. (Any value equal to or below the digital limiter LO setting will not be updated and kept at the setup value.			
A.OUT	Analog output type	0-1	1	0-1/0-10/1-5/4-20	Selects an analog output range.*Only when the analog output is available.			
AOHI	Analog output HI	9999	1	-9999 to +9999				
AOLO	Analog output LO	0	1	-9999 to +9999	Sets the relationship between indications and analog outputs.*Only when the analog output is available.			
DP	Decimal point	None	2	Each digit can be set independently.	Sets the position of the decimal point.			

### 4.5.3 Comparator Data (for meter relay only)

Menu indication	Parameter name	Initial value	P.L.	Setting range or alternatives	Major setting purpose and remarks		
COMT	Comparator output type	O/U	1	O/U/ERR	Select either [above or below] or error comparator types.		
HI-S	Hl judgment value	1000	2	-9999 to +9999	Sets a HI judgment value.*Only when COM.T is O/U.		
LO-S	LO judgment value	500	2	-9999 to +9999	Sets a LO judgment value.*Only when COM.T is O/U.		
N.VAL	Nominal value	5000	2	-9999 to +9999	Sets a nominal value.*Only when COMT is ERR.		
ERR1	Error 1	5.00	2	0.00 to 99.99	Sets an error.*Only when COM T is ERR		
HI-H	HI hysteresis	0	1	0 to +999	Sets a HI hysteresis value *Only when COM.T is O/U.		
LO-H	LO hysteresis	0	1	0 to +999	Sets a LO hysteresis value *Only when COM.T is O/U.		
ER1.H	Error 1 hysteresis	1	1	0 to +999	Sets an error hysteresis *Only when COM.T is ERR.		
HI-L	HI logic	N.O	0	N.O/N.C	Sets a HI output logic (N.O.=normally open or N.C.=normally dosed)*Output when the power is OFF is always open (OFF).		
GO-L	GO logic	N.O	0	N.O/N.C	Sets a GO output logic (N.O.=normally open or N.C.=normally closed)*Output when the power is OFF is always open (OFF).		
LO-L	LO logic	N.O	0	N.O/N.C	Sets a LO output logic (N.O.=normally open or N.C.=normally closed)*Output when the power is OFF is always open (OFF).		

## 5 Setting Examples

#### 5.1 Scaling Data Setting Examples





%The hysteresis is effective either in the range lower than the HI judgment value or that higher than the LO judgment value.



\*Error is to be set as a percentage of the nominal value.

The hysteresis is to be set as xx digits of the indication value.
 The hysteresis is effective either in the range lower than the upper side error or that higher than the lower side error.

# 6 Specifications and Measurements

## 6.1 Input Specifications

Range	Measurement range	Indication	Error (23°C ±5°C; 35 to 85%)	Input impedance	Maximum permissible input			
25	±999.9mA	Offset: ±9999	+ (0, 10/ of sda + 0-light)	Approx. 0.1Ω	+34			
26	±2.000A	Full scale: ±9999	±(0.1% of fug + 2digit)	Approx. 0.01 Ω	- 38			
Sampling rate : Maximum approx. 1.000 times/second								
* The error is applied when the sampling rate is 20 times/second or less.								
		······································						
AC curre	ent measurements (Lar	ge electric current)						
Range	Measurement range	urement range Indication Error (23°C ±5°C; 35 to 85%)		Input impedance	Maximum permissible input			
25	999.9mA	Offset: ±9999	1 (0 70) - ( - ( - ) - 00 - ( - '))	Approx. 0.1 Ω	ЗA			
26	5A	Full scale: ±9999	± (0.7% of rag + 20algit)	(CT)	8A			
Compliantes - Mavimum annual 2.5 times/second								
Sampli	ng rate : N	laximum approx. 2.5 t	imes/second					
Sampli Measu	ng rate : M rement method ; T	laximum approx. 2.5 t rue rms value calcula	imes/second tion					
Sampli Measu Freque	ng rate : M rement method : T ency range : 4	faximum approx. 2.5 t rue rms value calcula 0Hz to 1kHz (25range	imes/second tion :) ,50Hz or 60Hz (26range)					
Sampli Measu Freque Respo	ng rate : M rement method : T ency range : 4 nse speed : A	1aximum approx. 2.5 t rue rms value calcula 0Hz to 1kHz (25range .pprox. 1 second (10%	imes/second tion e) ,50Hz or 60Hz (26range) 5 to 90%)					
Sampli Measu Freque Respon	ng rate : M rement method : T ency range : 4 nse speed : A	1aximum approx. 2.5 t rue rms value calcula 0Hz to 1kHz (25range pprox. 1 second (10%	imes/second tion e) ,50Hz or 60Hz (26range) 5 to 90%)					
Sampli Measu Freque Respo	ng rate : M rement method : T incy range : 4 nse speed : A	Maximum approx. 2.5 t irue rms value calcula 0Hz to 1kHz (25range .pprox. 1 second (10%	imes/second tion ) ,50Hz or 60Hz (26range) 6 to 90%)					
Sampli Measu Freque Respon	ng rate : M rement method : T incy range : 4 nse speed : A	1aximum approx. 2.5 t irue rms value calcula 0Hz to 1kHz (25range .pprox. 1 second (10%	imes/second tion ) ,50Hz or 60Hz (26range) 5 to 90%)					

## 6.2 General Specifications

Display	: Multi display Main display: Red/green 7-segment display (character height: approx. 20 mm) Sub display: Red 7-segment display (character height: approx. 6 mm) Single display Red/green 7-segment display (character height: approx 20 mm)
Display range	: -9999 to 9999
Operational temperature	: 0 to 50°C 35 to 85%RH
Storage temperature	: −10 to 70 °C; 60%RH or less
Power supply	: AC PS
	AC 100 to 240V±10% DC PS DC 12 to 48V±10%
Power consumption	: AC PS Maximum load: Approx. 8 VA at 100 VAC DC PS Maximum load: Approx. 7 W at 24 VDC
External dimension	: 48 mm (H) x 96 mm (W) x 97.5 mm (with no DX option unit mounted)
Weight	: Approx. 450g
Withstand voltage	: AC PS PS-input, output: 1,500 VAC, 1 minute (AC PS) Input-output: 500 VDC, 1 minute Output-output: 500 VDC, 1 minute Case-PS, input, output: 1,500 VAC, 1 minute DC PS PS-input, output: 500 VDC, 1 minute (DC PS) Input-output: 500 VDC, 1 minute Output-output: 500 VDC, 1 minute Case-PS, input, output: 1,500 VAC, 1 minute
Insulation resistance	: AC PS Among the above terminals: 500 VDC 100 MΩ or more DC PS
	Among the above terminals: 500 VDC 100 M $\Omega$ or more

The PS voltage must be applied or shut down at once (not gradually). Take at least a 10-second interval between a shutdown and startup.

# 6.3 Output for Comparison Specifications (for meter relay only)

A Caution

	Judg	ment result			
Inc		н			
Lower limit judgr	GO				
Lo	wer	limit judgment value 🗆 Ind	icated value		LO
Hysteresis Operating speed Relay contact outp	ut	: Can be set in the company compan	he range of 1 to 999 digits fo e sampling rate ●Photo coupler o	or each	judgment value
Contact quantity	:	Relay contact ×3	Output quantity	/ :	Photo coupler ×3
			A Output rating		30\/ DC 20mA

### 6.4 External Dimensions





# 7 Warranty and Service

#### 7.1 Warranty

The manufacturer warrants to the original retail customer its A6000 series universal digital panel meter to be free of defects in material and workmanship for use under normal care and will repair or replace any meter at no charge to the customer during the one (1) year warranty period of the meter.

#### 7.2 After Sales Service

Under strict quality control measures, this product was manufactured, tested, inspected and shipped. Should a defect in manufacture or workmanship be identified, please return the product to our distributor or directly to us. It would be highly appreciated if you could give a detailed account of the fault and enclose it with the product.



External Control Unit

#### 1 Before Using the Unit

This instruction manual is for the external control unit of the A6000 series. Read this manual along with the main unit's instruction manual before using the unit.



#### 2 Terminals and Connections

	Top         ①         ① HOLD           ②         ②         PH           ③         ③         DZ           ○         ④         ④           ③         DZ         ⑤           ○         ⑤         P.SEL0           ○         ⑤         P.SEL1           ○         ⑦         P.SEL2           ○         ⑧         NC           ③         ⑨         NC           Bottom         ●         ●								
Terminal	Function								
S/H	"Start/hold" control terminal. The "hold" state is turned on when this terminal is at the same potential as the COM terminal or short-circuited.								
PH	*Peak hold* control terminal. The peak hold function is turned on when this terminal is at the same potential as the COM terminal or short-circuited.								
DZ	*Digital zero* control terminal. The digital zero function is turned on when this terminal is at the same potential as the COM terminal or short-circuited. This setting is valid only when the external control terminal is selected as the control method for digital zero using condition data.								
R.RESET	*Relay reset control terminal. The relay reset function is turned on (only for the meter relay) when this terminal is at the same potential as the COM terminal or short-circuited.								
P.SEL0 P.SEL1 P.SEL2	Pattern selection' control terminals. Patterns can be selected by setting these terminals at the same potential as the COM terminal or short-circuiting them as shown in the table below. These settings are valid only when the external control terminal is selected as the control method for pattern selection using condition data.       Pattern 1     Pattern 2     Pattern 3     Pattern 4       P stell     Pattern 4     Pattern 5     Pattern 6     Pattern 7       P stell     Open     Short-circuited     Open     Short-circuited Short-circuited     Open       P stell     Open     Open     Open     Short-circuited Short-circuited     Short-circuited Short-circuited								
COM	External control's common terminals, which are at the same potential as the LO or AG terminal for the input circuit.								

# 3 Timing Charts



Start/hold type B



#### \*1 Specified sampling

The sampling speed is determined by the AVG parameter setting of condition data as shown in the table below

AVG setting	Sampling speed	Sampling cycle	AVG setting	Sampling speed	Sampling cycle
1	1041.65 times/sec	Approx. 960 µs	100	10.4165 times/sec	Approx. 96 ms
2	520.825 times/sec	Approx. 1.92 ms	200	5.20825 times/sec	Approx. 192 ms
4	260.4125 times/sec	Approx. 3.84 ms	400	2.604125 times/sec	Approx. 384 ms
8	130.20625 times/sec	Approx. 7.68 ms	800	1.3020625 times/sec	Approx. 768 ms
10	104.165 times/sec	Approx. 9.6 ms	1000	1.04165 times/sec	Approx. 960 ms
20	52.0825 times/sec	Approx. 19.2 ms	2000	0.520825 times/sec	Approx. 1.92 sec
50	20.833 times/sec	Approx. 48 ms	5000	0.20833 times/sec	Approx. 4.8 sec

XUsing a temperature measuring unit, the sampling speed is half of the value in the table above when the RTD is selected and quarter of it when the TC is selected.

%It is different, and a frequency measurement unit is indication update time with a range. Please refer to input specifications (Clause 6.1) of an instruction manual for frequency measurement.

- Please refer to input specifications (Clause 6.1) of an instruction manual for frequency measurement. \*3 External start signal The width of the external start signal must be from between 500 µs to a specified sampling cycle. A time
- delay can be set for the external start signal must be from between 500 µs to a specified sampling cycle. A tir delay can be set for the external start using the S/H delay time parameter of the condition data.
- \*4 Time delay for comparator output

Relay output: 10 ms max., photocoupler output: 200  $\mu s$  max.

#### 4 Specifications and External Dimensions

#### External control terminal

Internal circuit: Pulled up to approximately +5 V (through a 10  $k\Omega$  resistor).

Control signal's HI level: 4.2 to 5 V relative to the COM terminal

Control signal's LO level: 0 to 0.4 V relative to the COM terminal







#### 5 Warranty and Service

#### 5.1 Warranty

The manufacturer grants a warranty to the original retail customer stating that its A6000 series universal digital panel meter is free of defects in material and workmanship for use under normal care, and will repair or replace the meter at no charge to the customer during the one (1) year warranty period.

#### 5.2 After Sales Service

This product was manufactured, tested, inspected and shipped under strict quality control measures. Should a defect in manufacture or workmanship be identified, please return the product to our distributor or directly to us. It would be highly appreciated if you could give a detailed account of the problem and enclose it with the product.

# watanabe

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BCD Output and External Control Unit

#### 1 Before Using the Unit

This instruction manual is for the BCD output and external control unit of the A6000 series. Read this manual along with the main unit's instruction manual before using the unit.



#### 2 Terminals and Connections



Suitable connector (receptacle): KEL Corporation's 8822E-035-171-F

Terminal	Function								
10º1	Least significant bit output of least significant BCD digit. The output logic can be switched using condition data.								
10º2	Second least significant bit output of least significant BCD digit. The output logic can be switched using condition data.								
10º4	Second most significant bit output of least significant BCD digit. The output logic can be switched using condition data.								
10º8	Most significant bit output of least significant BCD digit. The output logic can be switched using condition data.								
	:								
10 <sup>3</sup> 1	Least significant bit output of most significant BCD digit. The output logic can be switched using condition data.								
10 <sup>3</sup> 2	Second least significant bit output of most significant BCD digit. The output logic can be switched using condition data.								
10 <sup>3</sup> 4	Second most significant bit output of most significant BCD digit. The output logic can be switched using condition data.								
10 <sup>3</sup> 8	Most significant bit output of most significant BCD digit. The output logic can be switched using condition data.								
POL	BCD polarity output. The output logic can be switched using condition data.								
OVER	BCD overflow output. The output logic can be switched using condition data.								
P.C	BCD print instruction output.								
ENABLE	*Enable BCD* control terminal. The BCD output is set to the high-impedance state or the transistor is turned off when this terminal is short-circuited or at the same potential as the D.COM terminal.								
D.COM	BCD output• fs common terminals								
S/H	"Start/hold" control terminal. The "hold" state is turned on when this terminal is at the same potential as the COM terminal or short-circuited.								
РН	"Peak hold" control terminal. The peak hold function is turned on when this terminal is at the same potential as the COM terminal or short-circuited.								
DZ	*Digital zero* control terminal. The digital zero function is turned on when this terminal is at the same potential as the COM terminal or short-circuited. This setting is valid only when the external control terminal is selected as the control method for digital zero using condition data.								
R.RESET	"Relay reset control terminal. The relay reset function is turned on (only for the meter relay) when this terminal is at the same potential as the COM terminal or short-circuited.								
P.SEL0 P.SEL1 P.SEL2	"Pattern selection" control terminals. Patterns can be selected by setting these terminals at the same potential as the COM terminal or short-circuiting them as shown in the table below. These settings are valid only when the external control terminal is selected as the control method for pattern selection using condition data.       PSELD     Pattern 1     Pattern 2     Pattern 3     Pattern 4     Pattern 5     Pattern 5       PSELD     Open     Stort-cauded     Open     Stort-cauded     Open     Stort- Open     Stort- Open     Stort- Open     Stort- Open								
COM	External control is common terminals, which are at the same potential as the LO or AG terminal for the input circuit.								



The samplin	The sampling speed is determined by the AVG parameter setting of condition data as shown in the table below:									
AVG setting	Sampling speed	Sampling cycle	AVG setting	Sampling speed	Sampling cycle					
1	1041.65 times/sec	Approx. 960 µs	100	10.4165 times/sec	Approx. 96 ms					
2	520.825 times/sec	Approx. 1.92 ms	200	5.20825 times/sec	Approx. 192 ms					
4	260.4125 times/sec	Approx. 3.84 ms	400	2.604125 times/sec	Approx. 384 ms					
8	130.20625 times/sec	Approx. 7.68 ms	800	1.3020625 times/sec	Approx. 768 ms					
10	104.165 times/sec	Approx. 9.6 ms	1000	1.04165 times/sec	Approx. 960 ms					
20	52.0825 times/sec	Approx. 19.2 ms	2000	0.520825 times/sec	Approx. 1.92 sec					
50	20.833 times/sec	Approx. 48 ms	5000	0.20833 times/sec	Approx. 4.8 sec					

 Wusing a temperature measuring unit, the sampling speed is half of the value in the table above when the RTD is selected and quarter of it when the TC is selected.
 XIt is different, and a frequency measurement unit is indication update time with a range.

XIt is different, and a frequency measurement unit is indication update time with a range. Please refer to input specifications (Clause 6.1) of an instruction manual for frequency measurement.

#### \*2 P.C output signal width

3 Timing Charts

The output signal width is determined by the specified sampling setting as shown in the table below:

AVG	P.C	AVG	P.C
setting	output width	setting	output width
1	Approx. 220 µs	100	
2	Approx. 0.25 ms	200	
4	Approx. 1.15 ms	400	
8	Approx. 2.3 ms	800	Approx. 30 ms
10	Approx. 2.9 ms	1000	
20	Approx. 5.8 ms	2000	
50	Approx. 14.4 ms	5000	
The output	width is always 30 m	ns for the frequ	lency measureme

\*3 External start signal

The width of the external start signal must be from between 500  $\mu$ s to a specified sampling cycle. A time delay can be set for the external start using the S/H delay time parameter of the condition data. ^4 Time delay for comparator output

Relay output: 10 ms max., photocoupler output: 200 µs max.

#### 4 Specifications and External Dimensions

#### BCD output

Output type :	open collector or TTL-compatible								
Polarity :	The applicable transistor (open collector) or polarity bit (TTL) turns on when								
	negative values are indicated.								
Overflow :	The applicable transistor (open collector) or bit (TTL) turns on when the overflow								
	state is indicated.								
Output logic :	Can be switched alternatively (the logic for the P.C bit cannot be changed).								
Output rating :	30 V DC and 10 mA (open collector), or fan-out 2 (TTL)								
The BCD ou data, which i for an output	n tput logic can be switched using the BCD logic parameter (BCD.L) of the condition s positive when BCD.L is set to P.LOG and negative when BCD.L is set to N.LOG type of Open collector. This logic is reversed if the output type is "TTL."								
External control terminal									

Internal circuit: Pulled up to approximately +5 V (through a 10  $k\Omega$  resistor).

Control signal's HI level: 4.2 to 5 V relative to the COM terminal

Control signal's LO level: 0 to 0.4 V relative to the COM terminal

## A Caution

# The BCD output circuit and the external control circuit are electrically isolated from each other (withstand voltage: 500 V DC for one minute). The external control circuit's COM terminals and the input circuit's LO or AG terminal are

- set at the same DC potential.



### 5 Warranty and Service

#### 5.1 Warranty

The manufacturer grants a warranty to the original retail customer stating that its A6000 series universal digital panel meter is free of defects in material and workmanship for use under normal care, and will repair or replace the meter at no charge to the customer during the one (1) year warranty period.

#### 5.2 After Sales Service

This product was manufactured, tested, inspected and shipped under strict quality control measures. Should a defect in manufacture or workmanship be identified, please return the product to our distributor or directly to us. It would be highly appreciated if you could give a detailed account of the problem and enclose it with the product.



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Analog Output and External Control Unit

#### 1 Before Using the Unit

This instruction manual is for the analog output and external control unit of the A6000 series. Read this manual along with the main unit's instruction manual before using the unit.

#### 2 **Terminals and Connections**



#### 3 Timing Charts

Start/hold type A





#### \*1 Specified sampling

The sampling speed is determined by the AVG parameter setting of condition data as shown in the table below

AVG setting	Sampling speed	Sampling cycle	AVG setting	Sampling speed	Sampling cycle
1	1041.65 times/sec	Approx. 960 µs	100	10.4165 times/sec	Approx. 96 ms
2	520.825 times/sec	Approx. 1.92 ms	200	5.20825 times/sec	Approx. 192 ms
4	260.4125 times/sec	Approx. 3.84 ms	400	2.604125 times/sec	Approx. 384 ms
8	130.20625 times/sec	Approx. 7.68 ms	800	1.3020625 times/sec	Approx. 768 ms
10	104.165 times/sec	Approx. 9.6 ms	1000	1.04165 times/sec	Approx. 960 ms
20	52.0825 times/sec	Approx. 19.2 ms	2000	0.520825 times/sec	Approx. 1.92 sec
50	20.833 times/sec	Approx. 48 ms	5000	0.20833 times/sec	Approx. 4.8 sec
		14 AL 15		<b>K</b> ( <b>A</b> ) <b>A</b> ( <b>A</b> )	

%Using a temperature measuring unit, the sampling speed is half of the value in the table above when the RTD is selected and quarter of it when the TC is selected.

%It is different, and a frequency measurement unit is indication update time with a range. Please refer to input specifications (Clause 6.1) of an instruction manual for frequency measurement. \*3 External start signal

The width of the external start signal must be from between 500 µs to a specified sampling cycle. A time delay can be set for the external start using the S/H delay time parameter of the condition data

\*4 Time delay for alarm output

Relay output: 10 ms max., photocoupler output: 200 µs max.

#### 4 Specifications and External Dimensions

Analog output (PWM)

Output type	Load resistance	Accuracy	Response speed	Ripple
0 to 1V				
0 to 10V	$10k\Omega$ or more	1 (0 50( -4 50)	A	50mVp-p
1 to 5V		±(0.5% of FS)	Approx. 0.5 second	
4 to 20mA	$550\Omega$ or less			25mVp−p
Conversion system	: PWM conver	sion		
Resolution	: Equivalent to	14 bits		
Scaling	: Digital scalin	g		
External control ter	minal			
Internal circuit Control signal's HI level	: Pulled up t : 4.2 to 5V n	o approximately +5V ( elative to the COM terr	through a 10kΩ resistor). ninal ninal	
Control signal s LC	0 10 0.4 1	elative to the COW ten	ninai	
— 🔶 Cau	tion			

(1) Ana one minute) (2) COM terminals of external control circuits and LO terminals of input circuits have the same electric potential at direct current.





#### 5 Warranty and Service

#### 5.1 Warranty

The manufacturer grants a warranty to the original retail customer stating that its A6000 series universal digital panel meter is free of defects in material and workmanship for use under normal care, and will repair or replace the meter at no charge to the customer during the one (1) year warranty period.

#### 5.2 After Sales Service

This product was manufactured, tested, inspected and shipped under strict quality control measures. Should a defect in manufacture or workmanship be identified, please return the product to our distributor or directly to us. It would be highly appreciated if you could give a detailed account of the problem and enclose it with the product.

# watanabe

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~RS-232C/RS-485 and Analog Output Units~

# 1 Before Using the Unit

This Operation Manual corresponds to the communication function + analog output optional units of the A6000 Series Universal Digital Panel Meters. When using the instrument, please read through this manual in combination with the Operation Manual of the main unit.

# 2 Terminals and Connections



# 3 Examples of Connections and Use

# 3.1 Connecting the RS-232C Interface

A6000 series	D-sub 25-pin connector	A6000 series	D-sub 9-pip connector
nodular jack	of PC, etc.	modular jack	of PC, etc.
RXD 👞	► RXD (2)	RXD ┥	► RXD (2)
TXD 🚽	► TXD (3)	TXD ┥	► TXD (3)
SG 👞	► RTS (4)	SG 👞	► RTS (7)
	CTS (5)		CTS (8)
	SG (7)		SG (5)

# 3.2 Connecting the RS-485 Interface



\*If cascade wiring is carried out with a RS-485 connection, use a commercially available Y-type split connector or the like. \*To turn ON an RS-485 I/O unit's terminator (200 Q), short-circuit the two TERM terminals.

# 3.3 Control Codes Used in RS-485 Interface

Code	Hexadecimal	Name
STX	02H	Start of Text
ETX	03H	End of Text
EOT	04H	End of Transmission
ENQ	05H	Enquiry
ACK	06H	Acknowledge

# 3.4 Establishing RS-485 Communication

Function	1 2 3 4 5 6 7	Char. Length	1 2 3 4 5 6 7 8 9 10 Char. Length
Establishing	■NQ 0 1 OR LF	3	ACK 0 1 OR LF 3
communication	*Device ID is specified in		(Normal response)
Canceling communication	2 digits (00 is invalid).	1	* Response time: 40 ms maximum (No response is made if the device ID is different) (No response is made to cancellation of communication.) * Response time: 20 ms maximum

# 3.5 RS-485 Communication formats

As a means of error detection, a block check character (BCC) checksum is added to the RS-485 communication function of the A6000. See the following illustrations for details on the transmission and reception formats.

(RS-232C communication format is same as the command table which is mentioned in the next section.)



# 4 Communication Commands

Function	1	2	3	4	5	6 7	8	9	10	11 }	12	13	14 15	Char. I	_ength	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 Char.	r. Length
responses	10	3		CR											,	("+" indication without decimal point)	10
																- 5 0 0 0 H I CR LF 1	10
																("+" indication without decimal point)	11
																("+" indication with a decimal point)	l
																<pre>&lt; = 9 8 0 0 H I CR LF 1 ("+" side excess indication without decimal point)</pre>	10
																<   =   - { 9   8   0   .   0   H   I   CR   LF   1	11
																("-" side excess indication with a decimal point)	10
																(Peak hold indication without decimal point)	10
			[													5 0 0 0 A L 1 CR LF	11
																("+" indication without decimal point)	11
																("-" indication without decimal point)	
										1						("+" indication with a decimal point)	12
										1							
Measured value response	М	E	S	CR	LF									3	3	0 CR LF 1	12
hold, etc. or compression decision																	12
is notresponded.																("0.01" indication with a decimal point)	
			1													("-1" indication without decimal point)	12
																	12
			[													("-0.005" indication with a decimal point)	12
																(Excess indication with a decimal point)	12
																< = - 9 8 0 . 5 CR LF 1	12
										1						* All responses have a fixed length of 12 characters.	
	<u> </u> .		<u>}</u>	0.0						_{							4.5
* A measurement condition is not	J	G	M	CR											5	(Response of a state in which the judgment result is HI)	15
responded.																GO CR LF 1	15
																(Response of a state in which the judgment result is GO)	15
																(Response of a state in which the judgment result is LO)	10
																O F F CR LF 1	15
																	5
																(Response made if the relevant optional unit is not installed)	
																exception of an error.	
Unit num ber response	U	Ν	1	CR	LF									3	3	1 1 , 2 1 , N O , 4 6 CR LF 1	11
																(Response is made in the order of the display unit number, input	
																If the unit concerned is not installed, "NO" is returned.)	
Response of the maximum value	м			CP		_	-		4		+		_		_		10
minimum value, or maximum and			Â		-										,	(Response of maximum value)	10
minimum values																M I N - 1 0 0 . 0 CR LF 1 (Response of minimum value)	10
																M - M 6 0 0 . 0 CR LF 1	10
																(Response of maximum and minimum values)	
																with a delimiter.	_
Clear of the maximum value, minimum value, or maximum and		C C	L	ma	M xim u	A C m val	R LF							6	5	Y E S CR LF	5
minimum values	M	C	L	1	М	I C	RLF							6	;	Y E S CR LF	5
	(CI M	ears	the	m in	imui M	m val M∣Ci	ue.) RIIF							F	;	Y E S CRIE	5
	(C)	ears	the	ma	xim u	man	d m ir	im u	m va	lues	s.)				, 		
Key operation inhibition response	К	E	Y	CR	LF		_	$\left\{  \right\}$	_	+	-	+		3	3		3
	1	1			-											(Response of a state in which the key operation inhibition function is OFF)	
													1			C N CR LF I I I I I I I I I I I I I I I I I I	2
		_				_		[									_
Key operation inhibition setting		E eacti	Y Vaite	s th	O e kev	FFF	CR	{ LF	bition	∣ ղ fun	Ictio	n.)		7		Y E S CR LF	5
	ĸ	E	Y		0	N C	RLF	{		1				6	;	Y E S CR LF	5
	(Ac	tivat	es ti	he k	eyop	erati	on in l	nibiti }	on fu	Inctio	on.)						
Response of remote-controlled hold	s	Т	н	CR	LF			$\square$		1		-		3	3	S T A R T CR LF	5
																(Response of a state in which hold is deactivated by remote control)	4
																(Response of a state in which hold is activated by remote control)	
							1									Response of a state in which hold is not remote controlled)	3
		_															_
Hold remote control	D f	T eacti	H va te	s th	e hol	∪R∥Li d fun	⊢ ction	{						5	, ,	Y E S CR LF	5
	s	Т	н		н	CR	F			8				5	5	Y E S CR LF	5
	(Ac	tivat	es ti	ne h	oldfu	inctic	on.)										
Trigger input	Т	CR	LF											1		5 0 0 . 0 H I CR LF 1	11
																* The response format is the same as the DSP command.	ļ
	_																_
cancellation of hold remote control	<sup>E</sup>	S	м	CR	LF									3	,	TES CRIF	э

			,															
Function	1	2	3	4	5 }	6 {	7	8	9	10	11	12	13	14	15	Char. Length	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 Char. Len	ngth
Response of remote-controlled	P	V	} H	CR	LF	- {	}			1						3	PH-OFFCRLF 6	
peak hold			{		- 1	- }	{			1	- 1	- 1					Response of a state in which peak hold is deactivated by remote control)	
			1				{			1		- 1					V H - O F F CR LF 6	
		1	{				-			1							Response of a state in which valley hold is deactivated by remote control)	
						- {	1			-							PV-OFFCRLF 6	
			{				{			1		- 1					Response of a state in which peak & valley hold is deactivated by remote control)	
		1	}			- {	}			1	- 1						PH-ONCRLF 5	
			{				{			1	- 1						Response of a state in w hich peak hold is activated by remote control)	
			}			- {	}			- 8							V H - O N CR LF 5	
		1	{			- }	{			1	- 1	- 1					Response of a state in w hich valley hold is activated by remote control)	
						- {	}			1							PV-ONCRLF 5	
			{				{			1	- 1	- 1					Response of a state in which peak & valley hold is activated by remote control)	
			}			- {	}			-							L O C CRILF 3	
			{			- }	{			1	- 1	- 1					Response of a state in which peak hold is not remote controlled)	
		I	۱		_		{			1		- 1						
Peak hold selection setting	P	V	} H		Р	н₿	CR	F		1						6	YES CRLF 5	
	(Se	ets u	рре	akh	old.	) }	{			1		- 1						
	P	V	} H		V	нţ	CR   L	F		1						6	YES CRLF 5	
	(Se	ets u	p va	lley	۱old.	.) }	{			1	- 1	- 1						
	P	V	{н		P	νį	CR   L	F		-						6	YES CRIF 5	
	(Se	ets u	p pe	aka	ndv	alle	yhol	d.)		1	- 1	- 1						
			1				ş			8		- 1						
Peak hold remote control	P	V	} H		0	N {(	CR   L	F		1						6	YES CRLF 5	
	(Ad	ctivat	tes ti	ne p	eak l	nold	func	ction	.)	1	- 1	- 1						
	P	V	} H		0	Fξ	F C	R	F	1						7	YES CRLF 5	
	(D	eacti	ivate	s the	e pea	ak h	oldifu	unct	tion.	)	1							
			{		1		{			1		- 1						
Peak-held value response	P	I V	} D	CR	LF	- {	}			1	- 1					3	P H 5 0 0 . 0 CR LF 10	
		1	{			- 1	1				- 1						Response of peak-held value)	
			{			- {	{										V H   - 1 0 0 . 0 CR LF   10	
			1			- {	}			1	- 1						Response of valley-held value)	
			{				{			1	- 1	- 1					P V H 6 0 0 . 0 CR LF 10	
			}			- {	}			8							Response of peak- and valley-held values)	
		1	{			- }	{				- 1							
Clear of peak-held value	P	С	} L		P	н (	CRÌL	F		1						6	Y E S CR LF 5	
	(C)	lears	s'a p	eak	held	vaĺi	ue.)				- 1							
	P	С	{ L		V	н }о	CRÍL	F		1	- 1	- 1				6	Y E S CR LF 5	1
	(C)	lears	sav	alley	-heĺo	d val	ue.)			1								1
	Р	С	{L		Р	V i	CR { L	F		1						6	Y E S CR LF 5	
	(C)	lears	spea	ik-a	ndv	alle	γ-hél	d va	lues	s.)		- 1						
	, i	1	}' 1		1	1	1	Ξ.		1								
Cancellation of peak hold remote control	I E	Р	M	CR	LE		{			1	- 1	- 1				3	Y E S CR LE 5	
	-		£		- 1		{			1		- 1				Ū		
Response of remote-controlled		17	R	CR	LET	-{			+				-			3		-
digital zero	1	1	1	011	-					1						0	Response of a state in which digital zero is deactivated by remote control)	
algital zoro		1	}			- {	}			8	- 1							
		1	{			- }	1				- 1						Response of a state in which digital zero is activated at 1000 by remote control)	
			}			- {	}			1							- 1100000000000000000000000000000000000	
		1				- 1				1							Response of a state in which digital zero is activated at -1000 by remote control)	
		1	1				{			1	- 1	- 1					The value indicated when digital zero is activated is responded	
			{			- {	{				- 1							
			{				{			1	- 1						Response of a state in which digital zero is not remote controlled)	
			{			- {	{											
Digital zero remote control		7				N 3	~ D I I	-			- 1					6	V E S CRIE	
		tivat	{ `` {	inita	1 70 1					1						Ŭ		
		1 7	{ p	igna	01	E }	F		- 1		- 1					7	V E S CRIE	
		1 -	{ h	o di	ital	' }	1		1	1	- 1	- 1				'		
		1 7	ivate i D	s uit	11	2010 03				-						0		
				iaita			1000			!	- 1					0		
		livai	s u	igna	1 Zen	u ai	1000	0.)		1		- 1						
Concellation of digital zara remate		-	}	CD.		- {	}			1						2		
Cancellation of digital zero remote	15	14	1	CR			{			1	- 1	- 1				3		
control						- {	}			- 1								
-	_	-					_{	_	_	-!								
Response of remote-controlled	R	E	s	CR	LF		- {				- 1					3	O F F CR LF 3	
relayreset		1	}			- {					- 1						(Response of a state in w hich relay reset is deactivated by remote control)	
			{		- 1	- }					- 1	- 1					O N CR LF 2	
		1	}		- {	1											(Response of a state in w hich relay reset is activated by remote control)	
		1	1		- 1	- {	ţ.					- 1						
		1	{		- {	- }											(Response of a state in which relay reset is not remote controlled)	
		1	}		_ 1		1	1		1								
Relay reset remote control	R	E	{ S		0 }	N	CR	F								6	YES CRIF 5	
	(Ad	tivat	tes r	əlay	rese	t.) }	_ {	1		1		- 1						
	R	E	} s		0 {	Fξ	FC	R	F	1						7	YES CRIF 5	
	(D	eact	ivate	s re	ayre	eset	.)											
		1	1		- 1	- {	1				- 1							
Cancellation of relay reset	E	R	M	CR	LF }	- {										3	YES CRLF 5	
remote control		1	}		- 1	- {	1	1		1								
1	1	1	2	. 1	5	()						- 1			•			

Response of remote-controlled       R       L       Y       CR       LF       3       O       F       F       CR       LF       Image: CR       Imag	e control) 2 on trol) 2 control) 2 control 2
comparison output       (Response of a state in which all outputs are turned OFF by remo         H       I CR LF       I         (Response of a state in which HI is turned ON by remote       (Response of a state in which HI is turned ON by remote         (Response of a state in which CO is turned ON by remote       Image: CR LF I Image: CR LF	e control) 2 on trol) 2 con trol) 2
Image: Constant of a state in which His turned ON by remote         G   O   CR   LF	control) 2 control) 2
G   O   CR   LF	control) 2 2
(Response of a state in which GO is turned ON by remote         L       O       CR       L       I </td <td>control) 2</td>	control) 2
L       O       CR       I	2
* If multiple outputs are ON, response is made in the abov L O C CR LF	ontrol) I
L O C CR LF	order.
	3
(Response made if the relevant optional unit is not installe	3d)
	3) U
Comparison output remote control R L Y H I CR LF 6 Y E S CR LF CR LF	5
	5
(Turns ON GO.)	
	5
	5
(Turns OFF all comparison outputs.)	
	5
(Response made if the output concerned is not produced)	·/
Cancellation of comparison R C M CR LF 3 Y E S CR LF	5
	5
(Response made if the relevant optional unit is not installe	1) (t
Response of ender-controlled P S L CK LT S S I CK LT S S I CK LT S S S S S S S S S S S S S S S S S S	s "1")
	1
(Response of a state in which the pattern used by remote control	s "8")
L O C CKLF	trolled)
Pattern select remote control P S L 1 CR LF 5 Y E S CR LF	5
	5
(Sets pattern in use to '8.')	
Cancellation of pattern select P S M CK LF 3 Y E S CK LF 6 6 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7 7	5
Remote control response         R         E         A         CR         LF         3         N         O         ?         CR         LF         1 <th1< th=""> <th1< t<="" td=""><td>5</td></th1<></th1<>	5
	3
(Response of a state in which the hold function is remote	ontrolled)
	3
	itrolled)
(Response of a state in which the peak hold function is remote co	3
(Response of a state in w hich the peak hold function is remote co         D       Z       R       CR       I	ontrolled)
(Response of a state in w hich the peak hold function is remote co         D       Z       R       CR       LF	ontrolled) 3
(Response of a state in w hich the peak hold function is remote co         D       Z       R       CR       LF       1	ontrolled) 3 ontrolled) 3 ontrolled) 3
(Response of a state in which the peak hold function is remote of D         D       Z       R       CR       LF       1	ontrolled) sontrolled) sontrolled) rolled) 3
$ \left\{ \begin{array}{c c} (Response of a state in which the peak hold function is remote comparison of a state in which the digital zero function is remote comparison of a state in which the digital zero function is remote comparison of a state in which the digital zero function is remote comparison of a state in which the relay reset function is remote comparison of a state in which the comparison output function is remote c$	antrolled) antrolled) antrolled) antrolled) antrolled) antrolled) antrolled) antrolled) antrolled) antrolled) antrolled)
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(Response of a state in which the peak hold function is remote co         D       Z       R       CR       LF	antrolled) antrolled) antrolled) antrolled) antrolled) antrolled) be is
Collective cancellation of remote control       L       O       C       CR       LF       I	ntrolled) ntrolled) ntrolled) ntrolled) ntrolled) se is 5
Collective cancellation of remote control       L       O       C       CR       LF       L       CR       LF       L       CR       LF       L       LF       L       L       LF       L       L       LF       L       L       L       CR       LF       L       LF       L       L       L       CR       LF       L       L       L       LF       L       L       L       L       L       CR       LF       L       L       L       L       L       L       L       L       L       L       L	ntrolled) nolled) ase is 1 5 1 1 3 3 3 3 5 1
Collective cancellation of remote control       L       O       C       CR       LF       L       LF       L <td>3 nhrolled) 1 3 nrolled) 1 3 nrolled) 1 3 ntrolled) 5 5 1 s is "1") 1</td>	3 nhrolled) 1 3 nrolled) 1 3 nrolled) 1 3 ntrolled) 5 5 1 s is "1") 1
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Collective cancellation of remote control       L       O       C       CR       LF       Image: Control of the number of averaging times         Response of a state in which the read reset of the number of averaging times       A       V       G       CR       LF       Image: Control of the number of averaging times to "1.")         Setting of the number of averaging times       A       V       G       1       CR       LF       Image: Control of the number of averaging times to "1.")         Setting of the number of averaging times       A       V       G       1       CR       LF       Image: Control of the number of averaging times to "1.")         Setting of the number of averaging times       A       V       G       1       CR       LF       Image: CR       S       CR       LF       Image: CR       Imag	3       ontrolled)       3       ontrolled)       3       ntrolled)       3       ntrolled)       5       esis       5       9       5
Collective cancellation of remote control       L       O       C       CR       LF       Image: Control of the number of a state in which the pack hold function is remote control is remote control         Collective cancellation of remote control       L       O       C       CR       LF       Image: Control of the number of a state in which the relay reset function is remote control is remote control of the number of averaging times         A       V       G       CR       LF       Image: Control of the number of averaging times to "1.")       Setting of the number of averaging times to "1.")       A       V       G       1       CR       LF       Image: Control of the number of averaging times to "1.")         A       V       G       1       CR       LF       Image: Control of the number of averaging times to "1.")       Setting of the number of averaging times to "1.")       Setting of the number of averaging times to "1.")       Setting of the number of averaging times to "1.")       Setting of the number of averaging times to "1.")       Setting of the number of averaging times to "1.")       Setting of the number of averaging times to "1.")       Setting of the number of averaging times to "1.")       Setting of the number of averaging times to "1.")       Setting of the number of averaging times to "1.")       Setting of the number of averaging times to "1.")       Setting of the number of averaging times to "1.")       Setting of the number of averaging times to "5000.")       Seting of the number of averag	3       ontrolled)       3       ontrolled)       3       ntrolled)       3       ntrolled)       5       es is       5       000")       5       ing.       5
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Collective cancellation of remote control       L       O       C       C       L       F       C </td <td>3 ontrolled) i 3 irrolled) i 3 irrolled) se is 5 5 6 5 5 5 5 5 5 5 5 5 5 5 5 5</td>	3 ontrolled) i 3 irrolled) i 3 irrolled) se is 5 5 6 5 5 5 5 5 5 5 5 5 5 5 5 5
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Collective cancellation of remote control       L       O       C       CR       LF       LF       LF       L       C       CR       LF       LF       L       CR       CR       LF       LF       L       CR       CR       LF       LF       L       CR       CR       LF       LF </td <td>3       ontrolled)       3       ontrolled)       3       ntrolled)       3       ntrolled)       5       5       5       5       5       5       5       5       5       5       5       5       6       5       6       7</td>	3       ontrolled)       3       ontrolled)       3       ntrolled)       3       ntrolled)       5       5       5       5       5       5       5       5       5       5       5       5       6       5       6       7
Collective cancellation of remote control       L       O       C       CR       LF       Image: Cr	3       ontrolled)       3       ontrolled)       3       ntrolled)       3       ntrolled)       5       5       1       4       000')       5       5       5       9       5       5       6       6       6       6       6       7       4       6       5       3       4       6       5       3       4       5       5       5       5       5       5       6       5       6       5       5       6       5       6       5       5       5       5       6       5       5       6       6       6       6       6       6       6       6       6       6       6       6 </td
Collective cancellation of remote control       L       O       C       CR       LF       L       K	3       ontrolled)       3       ontrolled)       3       ntrolled)       3       ntrolled)       3       ntrolled)       5       1       6e is       5       1       4       5       5       1       5       5       5       5       1       4       5       5       5       1       6       5       1       5       5       1       5 </td
Collective cancellation of remote control       L       O       C </td <td>3       ontrolled)       3       ontrolled)       3       ntrolled)       3       ntrolled)       3       ntrolled)       5       es is       5       1       5       5       5       5       1       5<!--</td--></td>	3       ontrolled)       3       ontrolled)       3       ntrolled)       3       ntrolled)       3       ntrolled)       5       es is       5       1       5       5       5       5       1       5 </td
Collective cancellation of remote control       L       O       C       CR       LF       L       Y       CR       CR       LF       L       SR       CR       LF       L       SR       CR       LF       L       SR       SR       SR       SR       SR       SR       SR       SR       SR       CR       LF       L       SR       <	3       ontrolled)       3       ontrolled)       3       ntrolled)       3       ntrolled)       3       ntrolled)       5       9       1       5       9       1       5       1       5       1       5       1       5       5       1       5       5       1       5       5       1       5
Collective cancellation of remote control       L       O       C </td <td>a     3       ontrolled)     3       ontrolled)     3       introlled)     3       introlled)     5       es is 1     1       es is 4)     5       ing.     5       ing.     5       ing.     5       ing.     5       ing.     5       j     5       ing.     5       j     5       j     5       j     5       j     5       j     5       j     5       j     5       j     5       j     5       j     5</td>	a     3       ontrolled)     3       ontrolled)     3       introlled)     3       introlled)     5       es is 1     1       es is 4)     5       ing.     5       ing.     5       ing.     5       ing.     5       ing.     5       j     5       ing.     5       j     5       j     5       j     5       j     5       j     5       j     5       j     5       j     5       j     5       j     5
Collective cancellation of remote control       L       O       C       CR       LF       Image: Critical interview of a state in which the relay resolution to its remote of R is [S] CR is [F]       Image: Critical interview of R is [S] CR is [S	3       ontrolled)       3       ontrolled)       3       ntrolled)       se is       5       es is "1")       4       000")       5       ing.       5 </td

## INSTRUCTION MANUAL MODEL A6xxx-x5/x6/x7/x8

Function	1 2 3 4 5 6 7 8 9 10 11 12 13 1	14 15 Char. Length 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 Char. Length
Step wide response	S W D CR LF	3 1 CR LF 1 1
		(Response of a state in which step wide is "10")
Step wide setting	S W D 1 CR LF	5 YES CRIF 5
		6 Y E S CR LF 5
	(Sets step wide to "10.")	* Step wide is switched immediately after setting.
Dianlawaalaa aaaaaa		
Displaycolor response	U L R UR LF	(Response of a state in which the display color is red)
		G R E E N CR LF 5
		(Response of a state in which the display color is green)
		(Response made if the comparison output unit is not installed)
Displaycolorsetting	C L R R CR LF	5 Y E S CR LF 5
	(Sets display color to red.)	
	(Sets display color to green.)	
		N O ? CR LF 5
		(Response made if the comparison output unit is not installed)
Display color type response		
		(Response of a state in which the display color type is Auto)
		M A N U A L CR LF 6
		(Response made if the comparison output unit is not installed)
Display color type setting	C L T A CR LF	5 Y E S CR LF 5
		5 Y E S CR LF 5
	(Sets the display color type to Manual.)	* The display color type is switched immediately after setting.
		N O ? CR LF 5
HI display color response	C H I CR LF	3 R E D CR LF 3
		(Response of a state in which the HI display color is red)
		(Response of a state in which the HI display color is green)
		A U T O CR LF 4
		(Response of a state in which the display color type is Auto)
		NO ? CR LF 5
HI display color setting	C H I R CR LF	5 Y E S CR LF 5
	(Sets HI display color to red.)	
	(Sets HI display color to green)	5 Y E S CR LF 5
		(Response of a state in which the display color type is Auto)
		(Response made if the comparison output unit is not installed)
		(Response of the state of independent judgment specifications)
GO display color response	C G O CRILF	3 R E D CR LF 3 (Response of a state in which the GO display color is red)
		G R E E N CR LF 5
		(Response of a state in which the GO display color is green)
		(Response of a state in which the display color type is Auto)
		N O ? CR LF
		(Response made if the comparison output unit is not installed)
CO display solar actting	C.C.O. B.OD.LE	
GO display color setting	(Sets GO display color to red.)	
	C G O G CR LF	5 YES CRLF 5
	(Sets GO display color to green.)	* GO display color is switched immediately after setting.
		A U I U CR LF 4 (Response of a state in which the display color type is Auto)
		N O ? CR LF 5
		(Response made if the comparison output unit is not installed)
		(Response of the state of independent judgment specifications)
LO display color response	C L O CR LF	3 R E D CR LF 3
		(Response of a state in which the LO display color is red)
		G R E E N CR LF 5 (Response of a state in which the LO display color is green)
	: : : : : : : : : : : : : :	
	: : : : : : : : : : : : : :	(Response of a state in which the display color type is Auto)
		N U ? CR LF 5 (Response made if the comparison output unit is not installed)
LO display color setting	C L O R CR LF	5 Y E S CR LF 5
	(Sets LO display color to red.)	
	(Sets LO display color to green.)	* LO display color is switched immediately after setting.
		A U T O CR LF 4
	1 : : : : : : : : : : : : : :	(Response of a state in which the display color type is Auto)
		(Response made if the comparison output unit is not installed)
		(Response of the state of independent judgment specifications)
1		

Function	1 2 3 4 4 5 6 6 7 8 9 10 11 12 13 14 15 Char. Length 1 2 3 4 4 5 6 7 8 9 10 11 12 13 14 15 Char. Length 1 2 3 4 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 Ch	ıar. Length
Display blank response		3
	(Response of a state in which blank setting is OFF)	•
		3
	(Response of a state in which biank setting is at LV1)	3
	(Response of a state in which blank setting is at 1/2)	5
		3
	(Response of a state in which blank setting is at LV3)	
		2
	(Response of a state in which blank setting is ON)	
Display blank setting		5
		5
	(Sets black setting to LV1)	5
		5
	(Sets blank setting to LV2.)	
	BLK LV3CRLF 7 YES CRLF	5
	(Sets blank setting to LV3.)	
		5
	(Activates blank setting.)	
log switch response		2
	(Response of a state in which ion switch setting is ON)	2
		3
	(Response of a state in which jog switch setting is OFF)	
	NO ? CRLF	5
	Response made if the relevant unit is not installed)         Image: CResponse made if the relevant unit is not installed)	
		_
Jog switch setting		5
		5
		5
	NO ? CRIE	5
	(Response made if the relevant unit is not installed)	-
Digital zero backup response	B D Z CR LF 3 O N CR LF	2
	(Response of a state in which digital zero backup is ON)	
		3
	(Response of a state in which digital zero backup is OFF)	
Digital zero backup control		5
		5
		5
	(Deactivates digital zero backup.)	
Digital zero data save command	S A V CR LF	5
		E
	(Response made if the relevant unit is not installed)	5
Response of the number of patterns	PSNCRLF 3 1 CRLF	1
for pattern select	(Response of a state in which the number of patterns for pattern select is	s "1")
	8 CR LF 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	1
	(Response of a state in which the number of patterns for pattern seleci is	s "8")
Control over the number of patterns		5
for pattern select	(Sets the number of natterns for nattern select to 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	5
		5
	(Sets the number of patterns for pattern select to "8.")	Ũ
Linearize function status response		3
	(Response of a state in which the linearize function is OFF)	
		1
	(Response of a state in which the linearize correction point is "2")	n
	I (Response of a state in which the linearize correction point is "16")	2
Linearize function status setting		5
-	Cheactivates the linearize function.)	
		5
	(Sets inearze correction point to "2."	_
		5
Tracking zero response		10
	(Response of a state in which the tracking zero time is "1" and tracking zero width i	is "1")
		12
	(Response of a state in which the tracking zero time is "99" and	
	tracking zero width is "99")	~
		3
	(Response of a state in which the tracking zero function is OFF)	
Tracking zero setting		5
Listing Lord County	(Sets tracking zero time to "1.")	0
		5
	(Sets tracking zero time to "99.")	
		5
	(Sets tracking zero width to 1 digit.)	_
	$  Y   = \{ S \mid S   S   S   S   S   S   S   S   S  $	5
		5
		J
	* In order to validate a tracking zero setup, please perform a number of times setup of an average continuously after carrying out a tracking zero s	etup.

Function	1	2	3	4	5	6	} 7	8	9	10	1	1 12	13	14	15	5 Char.	ength	1 }	2	3	4		5	6	7	8	9	10	1	11	12	13	14	1	5 { 1	16	17 {	18	Char	Length
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	(Se	ets p	ow	er-c	n d	eĺay	tim	e to !	9'se	ecor	۱ḋs.	)									1						}										- 1			
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	(De	eact	ivato	es t	he p	oowe	er-o	nde	lạy	func	tion	)									1						1													
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Unit number indication response	+	N	$\frac{1}{10}$	C	2 1 1	-	+	+	+	-	+	+	+	+	+		2	-	N	CR	$\frac{1}{1}$	F	+	-		-	+	+	+	+	$\dashv$		⊢	+	+	+	$\dashv$	_		$\frac{1}{2}$
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		1	1															1				1	1				1			1	Ĩ		1	1						
Peak hold type setting	P	V	} T		A	CF	₹{LI									5	;	Y	Е	s			C	R	LF								1							5
	P	v is p	eak { T	: 10		npet CP	υ Α. { ] Ι Ι	/									;	γĺ	Е	s			6	R	LF								1			1				5
	(Se	ets p	eal	ho	ld t	/pet	οB	)											-			Í						1					1							
		1	1	1		1	ş	1										- {			1		8			1		1					1	1	1	- {	1			

Function	1	2	} 3	4	5	6	7	8 {	9	10	11	12	13	14	15	Char. Leng	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 Char. Ler
Baud rate response	В	А	ļυ	CR	LF	1						Í	1	1	1	3	2 4 0 0 CR LF 4
			}	1								{					(Response of a state in which the baud rate is 2400 bps)
			{	}								}					4 8 0 0 CR LF 4
			}	{								{					(Response of a state in which the baud rate is 4800 bps)
			1									1					(Response of a state in which the baud rate is 9600 bps)
			1	}				1				Į.					1 9 2 0 0 CR LF 5
			1									1		1			(Response of a state in which the baud rate is 19200 bps)
			1									1					3 8 4 0 0 CR LF 5
			}	{				- 1				{		1			(Response of a state in which the baud rate is 38400 bps)
	B	Δ	١u		2	4	0	0	CR	1F		1		1		8	Y E S CRIE
	(Se	ets th	he b	auc	rate	e to 2	2400	bps	s.)			}				Ű	
	В	А	Įυ	}	4	8	0	0	ĊR	LF		ļ				8	Y E S CR LF 5
	(Se	ets th	he b	auc	rate	e to 4	1800	bps	s.)			{					
	B		{ U ho h	}	9 Lirate	1 b		{ U }   b n i	CR	LF		1				8	Y E S CR LF 5
	В	A	ξυ	}	1	9	2	0	0	CR	LF	}				9	Y E S CR LF 5
	(Se	ets th	he b	auc	rate	e to 1	920	0 b	ps.)			{					
	В	Α	Įυ	1	3	8	4	0	0	CR	LF	1				9	Y E S CR LF 5
	(Se	ets th	he b	auc	rate	e to 3	3840	0 bj	ps.)			1					* The baud rate is switched upon next power-up.
Data length response		Δ	<u>}</u> т	CR	IF	-						}	-	-	-	3	
Duta longar looponoo	1		1									{					(Response of a state in which the data length is 7 bits)
			{	}								}					8 CR LF 1
			}					1				1					(Response of a state in which the data length is 8 bits)
			- L		7							{				5	
	(Se	) A ets.d	{ ' lata	len	t h t	0 7 h	oits )					1				5	
	D	A	{ Τ	}	8	CR	LF					Į		1		5	Y E S CR LF 5
	(Se	ets d	lata	len	gth t	8 t	oits.)					1					* The data length is switched upon next power-up.
<b>D</b>		<u> </u>	<u>{</u>		<u> </u>	<u> </u>						Į	<u> </u>	<u> </u>	Ļ		
Parity bit response	I۲.	в	}	CR								1				3	E V E N CR LF 4
			1	}				1				Į.					
			1									1		1			(Response of a state in which a parity bit is odd parity)
			1	{								Į.					N O CR LF 2
			}	{				- 1				{		1			(Response of a state in which a parity bit is none)
		в	÷Τ		F	CR	LE					1				5	Y E S CRIE
	l(Se	ets a	} ipa	¦ ritv t	it to	eve	n pa	ritv.)				}		1			
	P	В	ĮΤ.	Ì	0	CR	LF	Í				ļ				5	Y E S CR LF 5
	(Se	ts a	pa	rity t	it to	odd	pari	ity.)				1				_	
	P	B	{ T	) 	N	CR	LF					1				5	Y E S CR LF 5
	(Se	ls a	i pai }	 	1		e.)					1					A parity bit is switched upon next power-up.
Stop bit response	s	В	ÌΤ	CR	LF	İ						İ	1	1	1	3	1 CR LF 1
			1									{					(Response of a state in which a stop bit is 1 bit)
			{									1					2 CR LF 1
			}					1				1					(Response of a state in which a stop bit is 2 bits)
	s	в	Íт		1	CR	LF					1				5	Y F S CR LF 5
	(Se	, – ets a	sto	, p bi	t to	1 bit.	)					}				-	
	s	В	ĮΤ.	{	2	CR	LF					1				5	Y E S CR LF 5
	(Se	ts a	s to	p bi	t to 2	2 bits	5.)					1					* A stop bit is switched upon next power-up.
Delimiter response		-	M	CR	LF	-	$\left  \right $	-			-	ţ	+	-	-	3	
	1	-	{									1					(Response of a state in which a delimiter is CR + LF)
			{	}								1					C R CR LF 2
			1	1								1					(Response of a state in which a delimiter is CR)
			۱. М		~	١.	CD					1				6	
	(Se	i∟ etsa	i del	limi	erto		+ LF	E.)				}					
	D	L	М	1	С	CR	LF	1				1				5	Y E S CR LF 5
	(Se	ts a	de	lįmi	erto	CR	.)					{					* A delimiter is switched upon next power-up.
	<b>_</b>		<u>{</u>		1	<u> </u>						Į	-	-	<u> </u>		
Device ID response			K	UR	LF							Į		1		3	(Response of a state in which the device ID is "01")
				1								1	1	1			9 9 CR LF 2
			1			1		1				1	1				(Response of a state in which the device ID is "99")
	Ι.	_										1				_	
Device ID setting	A	D	} R	1	1	CR	LF					1		1		5	Y E S CR LF 5
				.e iL }	9	9	CR	LF				1				6	Y E S CR LF 5
	(Se	ets d	levio	; ce ID	to	99".	)					1		1		Ĭ	* Device ID is switched upon next power-up.
	Γ		1	1		1						{	1	1			

Function	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	Char. Length	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 Char. Lengt
Condition data parameter response	A	L	1	CR	LF									_		3	A V G 1 CR LF 5
																	(Response of a state in which the number of averaging times is "1")
																	(Response of a state in which the moving averaging function is OFF)
																	S W D 1 CR LF 5
										1							(Response of a state in which step wide is "1")
										1							CLREDCRLF 7
																	(Response of a state in which the display color is red)
						- {				1							C L I M A N U A L OK LF   10
			{							1							
										8							(Response of a state in which the HH display color is red)
			{							8							CHIREDCRLF 7
																	(Response of a state in which the HI display color is red)
			{							1							
																	(Response of a state in which the LO display color is red)
										1							
						- {				1							(Response of a state in which the LL display color is red)
																	BLKOFFCRLF 7
																	(Response of a state in which display blank is OFF)
																	(Response of a state in which the ion switch is ON)
						- {				1							
										1							(Response of a state in which peak hold select is OFF at PH)
																	B D Z O N CR LF 6
										8							(Response of a state in which digital zero backup is ON)
			{							1							P S N 1 CR LF 5
			{							1							
																	(Response of a state in which linearize is OFF)
																	TRK OFFCRLF 7
										1							(Response of a state in which tracking zero is OFF)
																	PON 0 CRILF 5
										1							
										1							(Response of a state in which the protect level is at LV0)
																	UNOOFFCRLF 7
			{							1							(Response of a state in which unit number indication is OFF)
																	S I I A CR LF 5
										8							P V T A CR LF 5
			{							1							(Response of a state in which the peak hold type is A)
						- {				1							B A U 9 6 0 0 CR LF 8
																	(Response of a state in which the baud rate is 9600 bps)
										8							D A I / OR LF 5
																	(Response of a state in which a parity bit is even parity)
										1							S B T 2 CR LF 5
																	(Response of a state in which a stop bit is 2 bits)
																	D L M C R + L F CR LF 9
										8							A D R 1 CR LF 5
																	(Response of a state in which the device ID is 01)
			}			1				1							
Scaling data parameter response	A	L	2	CR	LF											3	P - 1 CR LF 3
																	R A N G 2 A CR LF 7
			}														(Response of a state in which the measurement range is 2 A)
			{														ISELO.CCRLF 8
			{														
			{														(Response of a state in w hich the full-scale indicated value is "9999")
			{														F I N 9 9 9 9 CR LF 10
			}														OFES 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
			{														(Response of a state in which the offset indicated value is "0")
			}														O [ I ] N   0 CR LF   10
			Į														Response of a state in which the offset input value is "0")
			{														(Response of a state in which the pre-scale value is "1.00")
			}			- {											P P R 1 CR LF 5
			{														(Response of a state in which the frequency division value is "1")
			{														(Response of a state in which the digital limiter HI value is "9999")
	1		1														D L L O  - 9 9 9 0 CR LF               10
	1		1	1													(Response of a state in which the digital limiter LO value is "-9999")
			1														(Response of a state in which the analog output type is 0 to 1 V)
			{														A O H I 9 9 9 9 CR LF 9
	1		1														(Response of a state in which the analog output HI indicated value is "9999")
	1		}														(Response of a state in which the analog output LO indicated value is "0")
	1		}														
			1														(Response of a state in which the temperature indication unit is °C)
	1		1														U E E F E U F F CR LF
	1																

Function	1	2	{ 3	} 4	5	6	1	3 } 9	10	11	12	13 }	14	15	Char. Length	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 Char. Length
*Case of the comparison output type is	A	L .	3	CR	LF										3	(The pattern used previously is responded)
high-and low-limit setting				1												
				1												(Response of a state in which the comparison output type is of
																high-and low-limit setting)
				ļ												H I - S 1 0 0 0 CR LF 10
				1												(Response of a state in which the HI judgment value is "1000")
				}												(Response of a state in which the LO judgment value is "500")
				1												(Response of a state in which the HI hysteresis is "0")
				1												L O - H 0 CR LF 10
				}												(Response of a state in which the LO hysteresis is "0")
				1												H I - L N O CR LF 7
				ļ												(Response of a state in which HI logic is normally open)
				1												(Response of a state in which CO logic is normally open)
				1												
																(Response of a state in which LO logic is normally open)
				1												N O ? CR LF 5
			L	<u> </u>				_	_							(Response made if the relevant input unit is not installed)
*Case of the comparison output type is	A	L	3	CR	LF										3	P - 1 CR LF 3
the tolerance judgment				1												(The pattern used previously is responded.)
				1												(Response of a state in which the comparison output type is of
				1												the tolerance judgment)
				}												N V A L 5 0 0 0 CR LF 10
																(Response of a state in which the nominal value is "5000")
				1												E R R 1 5 . 0 0 CR LF 11
																(Response of a state in which tolerance 1 is "5.00")
				[												
				}												
																(Response of a state in which HI logic is normally open)
				į												
				1												(Response of a state in which GO logic is normally open)
				1												L O - L N O CR LF 7
				]												(Response of a state in which LO logic is normally open)
				į												N O ? CR LF 5
Calibration data response	Δ	-	4	CR	LE		-	+	+				+	-	3	
	1	-													Ŭ	(The pattern used previously is responded.)
																SNSR 5CRLF 6
				Į												(Response of a state in which the sensor power is 5 V)
				1												Z R I N 0 . 0 0 0 CR LF 10
				1												(Response of a state in which the zero input value is "0.000")
				]												Z E R O O CR LF 6
				1												
				1												(Response of a state in which the span input value is "2.000")
				į												S P A N 9 9 9 9 CR LF 9
				}												(Response of a state in which the span indicated value is "9999")
																N O ? CR LF 5
				1												(Response made if the relevant input unit is not installed)
l inearize data response	A		5	CR	I.F.		_	+	_					_	3	
	· ·	-	-	1											-	(Response of a state in which the linearize data N-01 input value is "0")
				1												0 1 0 = 0 CR LF 6
				]												(Response of a state in which the linearize data N-01 output value is "0")
				1												(Response of a state in which the linearize data N-02 input value is "100")
				}												0 2 0 = 1 1 0 CR LF
				1												(Response of a state in which the linearize data N-02
				]												
				1												
				}												
				1												1 6     = 9 0 0 0 CB LF 9
	1	1		1												(Response of a state in which the linearize data N-16
	1															input value is "9000")
	1	1		1												(Response of a state in which the linearize data N-16
				}												output value is "9200")
				1												N O ? CR LF 5
																(Response of a state in which the linearize function is OFF)
				1												
Common response		1	1	1		i	-	1	1				Ť			YES CRLF 5
	1	1		}												(Normal response)
				]												N O ? CR LF 5
	1															(Response to an undefined command, etc.)
				1												
	1	1		}				1								(Response to data out of the setting range or data not meeting the setting conditions)
	1			1												(Response made if there is a communication parameter error)
	1															* There are ERROR B to ERROR F as an equivalent response command.
	1							1								* If there is a response of the ERROR X command, perform the
	1															same steps again. If this does not solve the problem, turn the meter
Response made if internal memory	1			1												
data is abnormal	1	1														(Response made if condition data is abnormal)
* Generally, a response is made	1			1												* Set condition data again.
only once.	1		1	]												DATALOST COMCRLF 13
	1			1												(Response made if comparator data is abnormal)
	1															Set comparator data again.
	1			1												(Response made if scaling data is abnormal)
	1															* Set scaling data again
	1															

## INSTRUCTION MANUAL MODEL A6xxx-x5/x6/x7/x8

Function	1 2 3 4 5 6 7 8 9 10 11 12 13 14 15	Char. Length	h 1 2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 Cr	har. Length
Scaling data setting	M E I CR LF	3	P - 1 CR LF	3
			(The patient used previously is responded.)	
		1		з
	(Sets data-setting pattern to "2")	1		5
	M CR LF	2	RANG 2 A CRLF	7
	1 V OR LF	2	R A N G 1 V CR LF	7
	(Sets the measurement range to 1 V.)			
	M CR LF	1	F S C 9 9 9 9 CR LF	8
	8 0 0 0 CR LF	4	F S C 8 0 0 0 CR LF	8
	(Sets the full-scale indicated value to "8000.")			_
	M CR LF	1	OFS 0 CR LF	5
		~		0
	2 U UR LF	2		ю
		1	Y E S ODIE	5
	* Setting necessary data and then sending the E			5
	command causes data acquired up to that point to be		NO 2 OBLE	5
	return to measurement operation.		(Response made if a value out of the setting range is input)	Ũ
Comparator data setting	C O M CR LF	3	P - 1 CR LF	3
*Case of the compans on output type	* The main unit's indication becomes "COM" at the		(The pattern used previously is responded.)	
is high-and low-limit setting.	instant the COM command has been received.			
Sets data-setting pattern to "2" and HI	2 CR LF	1	P - 2 CR LF	3
logic to "8000",set LO logic to "-5000",	(Sets data-setting pattern to "2.")			
and sets HI &LO logic to normally	M CR LF	1	C O M T O / U CR LF	8
closed.				
	M CR LF	1	H I - S 1 0 0 0 CR LF	9
				0
		4	H I - S 8 0 0 0 CR LF	9
		1		8
				0
	- 5 0 0 0 CRUE	5		10
	(Sets LO logic to "-5000.")	Ŭ		10
	MICRIF	1	HI-HOCRLE	6
				-
	M CR LF	1	LO-HOCRLF	6
	M CR LF	1	HI-LNOCRLF	7
	N C CR LF	2	H I - L N C CR LF	7
	(Sets HI logic to normally closed.)			
	M CR LF	1	GO-LNOCRLF	7
				_
	M CR LF	1		1
		2		7
	(Sets LO logic to permally closed )	2		'
		1	Y E S ODIE	5
	* A return to measurement operation using the F			U
	command (If the N command is sent, a return to		E R R O R 0 CR IF	7
	side judgment value is made.)		(Response made if a value not meeting the setting conditions is input)	
			NO ? CRLF	5
			(Response of a state in which the relevant input unit is not installed)	
*Case of the compason output type	C O M CR LF	3	P - 1 CR LF	3
is sets the nominal value to "8000",	* The main unit's indication becomes "COM" at the		(The pattern used previously is responded.)	
sets the tolerance 1 to "20.00".	M CR LF	1	C O M T O / U CR LF	8
	E R R CR LF	6	C O M T E R R CR LF	8
	(Sets the comparator output type to tolerance judgment.)			40
	M CR LF	1	N V A L 5 0 0 0 CR LF	10
				10
	8 0 0 0 CR LF	4		10
		1		11
	2 0 0 0 CR LF	5		11
	(Sets tolerance 1 to "20.00.")			
	MCRLF	1		10
	ECRLF	1	Y E S OR LF	5
	* A return to measurement operation using the E			
	command (If the N command is sent, a return to			7
	side judgment value is made.)		(Response made if a value not meeting the setting conditions is input)	_
				5
			(Response of a state in which the relevant input unit is not installed)	

\* The same setting methods as those above are also used for setting of other data (such as linearize data).

# 5 Specifications and Dimensions



about 14 bits or equivalent

Resolution

## 6 Warranty and After-sales Services

### 6.1 Warranty

The warranty period of this product is one year from the date of delivery. If a problem occurs during this warranty period and its cause is determined to be attributable to us, and will repair the product without charge.

### 6.2 After-sales Services

This product has been manufactured, tested, and inspected under strict quality control before shipment from the factory. If the product breaks down, contact your sales representative or our local office (or send it). In this case, write down the problem in detail and report it to your service representative (or enclose it with the product).



